L-force catalogue

Automation systems
Drive solutions

Controls
Inverter
Motors
Gearboxes
Engineering Tools

Motors: MCS synchronous servo motors, MCA asynchronous servo motors

Gearboxes: g700-P planetary gearbox

Lenze
As easy as that.

Contents of the L-force catalogue

■ **Selected portfolio**

▨ **Additional portfolio**

Lenze makes many things easy for you.

With our motivated and committed approach, we work together with you to create the best possible solution and set your ideas in motion - whether you are looking to optimise an existing machine or develop a new one. We always strive to make things easy and seek perfection therein. This is anchored in our thinking, in our services and in every detail of our products. It's as easy as that!

1

Developing ideas

Are you looking to build the best machine possible and already have some initial ideas? Then get these down on paper together with us, starting with small innovative details and stretching all the way to completely new machines. Working together, we will develop an intelligent and sustainable concept that is perfectly aligned with your specific requirements.

2

Drafting concepts

We see welcome challenges in your machine tasks, supporting you with our comprehensive expertise and providing valuable impetus for your innovations. We take a holistic view of the individual motion and control functions here and draw up consistent, end-to-end drive and automation solutions for you - keeping everything as easy as possible and as extensive as necessary.

3

Implementing solutions

Our easy formula for satisfied customers is to establish an active partnership with fast decision making processes and an individually tailored offer. We have been using this principle to meet the ever more specialised customer requirements in the field of machine engineering for many years.

4

Manufacturing machines

Functional diversity in perfect harmony: as one of the few full-range providers in the market, we can provide you with precisely those products that you actually need for any machine task – no more and no less. Our L-force product portfolio, a consistent platform for implementing drive and automation tasks, is invaluable in this regard.

5

Ensuring productivity

Productivity, reliability and new performance peaks on a daily basis – these are our key success factors for your machine. After delivery, we offer you cleverly devised service concepts to ensure continued safe operation. The primary focus here is on technical support, based on the excellent application expertise of our highly-skilled and knowledgeable after-sales team.

A matter of principle:
the right products for every application.
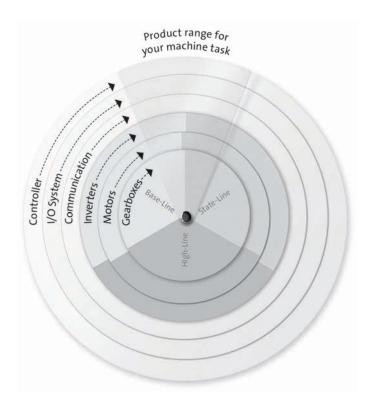
Lenze's extensive L-force product portfolio follows a very simple principle. The functions of our finely scaled products are assigned to the three lines Base-Line, State-Line or High-Line.

But what does this mean for you? It allows you to quickly recognise which products represent the best solution for your own specific requirements.
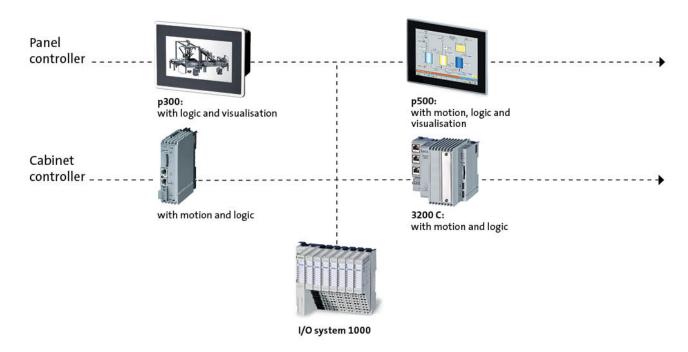
Powerful products with a major impact:
• Easy handling
• High quality and durability
• Reliable technologies in tune with the latest developments
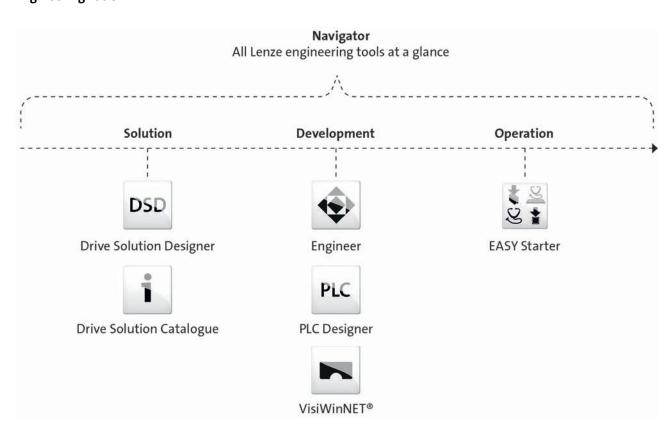
Lenze products undergo the most stringent testing in our own laboratory. This allows us to ensure that you will receive consistently high quality and a long service life. In addition to this, five logistics centres ensure that the Lenze products you select are available for quick delivery anywhere across the globe. It's as easy as that!

Product range for your machine task

Controller
I/O System
Communication
Inverters
Motors
Gearboxes
Base-Line
State-Line
High-Line

L-force product portfolio

Controls

Panel
controller

p300:
with logic and visualisation

p500:
with motion, logic and
visualisation

Cabinet
controller

with motion and logic

3200 C:
with motion and logic

I/O system 1000

Engineering Tools

Navigator
All Lenze engineering tools at a glance

Solution

Development

Operation

DSD

Drive Solution Designer

Engineer

EASY Starter

Drive Solution Catalogue

PLC

PLC Designer

VisiWinNET®

L-force product portfolio

Inverter

High-Line

Servo-Inverter i700

Servo Drives ECS

Inverter Drives 8400
TopLine

Servo Drives 9400 HighLine

Inverter Drives 8400
HighLine

State-Line

Inverter Drives 8400
StateLine

decentralised
Inverter Drives 8400 protec

decentralised
Inverter Drives 8400 motec

decentralised
Inverter Drives SMV
IP65

Inverter Drives SMV IP31

Inverter Drives smd

Inverter Drives 8400
BaseLine

Base-Line

L-force product portfolio

Motors

High-Line

MQA asynchronous servo motors

SDSGS synchronous servo motors

MDXKS synchronous servo motors

Synchronous servo motors MCS

Asynchronous servo motors MCA

Asynchronous servo motors SDSGA

State-Line

MF three-phase AC motors

MH three-phase AC motors

MD three-phase AC motors

Basic MD/MH three-phase AC motors

Base-Line

L-force product portfolio

Gearboxes

Planetary gearboxes g700-P

Planetary gearboxes MPR/MPG

Shaft-mounted
helical gearboxes g500-S

Helical-bevel gearboxes

Helical gearboxes g500-H

Bevel gearboxes g500-B

Helical-bevel gearboxes

Worm gearboxes

g700-P planetary geared motors

3 ... 707 Nm (synchronous servo motors)

g700-P planetary geared motors

Contents

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g700-P planetary geared motors

General information

List of abbreviations

c		Load capacity
i		Ratio
J	[kgcm²]	Moment of inertia
m	[kg]	Mass
M_2	[Nm]	Output torque
$M_{2, max}$	[Nm]	Max. output torque
$n_{2, eto}$	[r/min]	Transition speed
$n_{2, th}$	[r/min]	Thermal limit speed

CCC	China Compulsory Certificate
CE	Communauté Européenne
CSA	Canadian Standards Association
cURus	Combined certification marks of UL for the USA and Canada
DIN	Deutsches Institut für Normung e.V.
EMC	Electromagnetic compatibility
EN	European standard
GOST	Certificate for Russian Federation
IEC	International Electrotechnical Commission
IM	International Mounting Code
IP	International Protection Code
NEMA	National Electrical Manufacturers Association
UL	Underwriters Laboratory Listed Product
UR	Underwriters Laboratory Recognized Product
VDE	Verband deutscher Elektrotechniker (Association of German Electrical Engineers)

g700-P planetary geared motors

General information

Product information

In combination with synchronous servo motors, our planetary gearbox form a compact and powerful drive unit. Numerous options at the input end provide for the drive to be easily and precisely adapted to your application.

The planetary gearbox g700 is the ideal solution for demanding and dynamic tasks. With its high reliability, long service life and outstanding scalability, it provides everything you need to manage demanding machine tasks.

Versions

- High input speed possible Max. input speed 18000 rpm
- Wide variety of ratios i= 3...512 in 24 ratios
- High rated torque bandwidth 20 ... 800 Nm in five sizes
- Lifetime lubrication
- Suitable for any mounting position, hence only one variant
- With MCS synchronous servo motors, rated torque: 0.5 Nm ... 72 Nm

The product name

Gearbox type	Product range		Type	Rated torque [Nm]	Product
Planetary gearbox	g700	-	P	20	g700-P20
				44	g700-P44
				130	g700-P130
				260	g700-P260
				800	g700-P800

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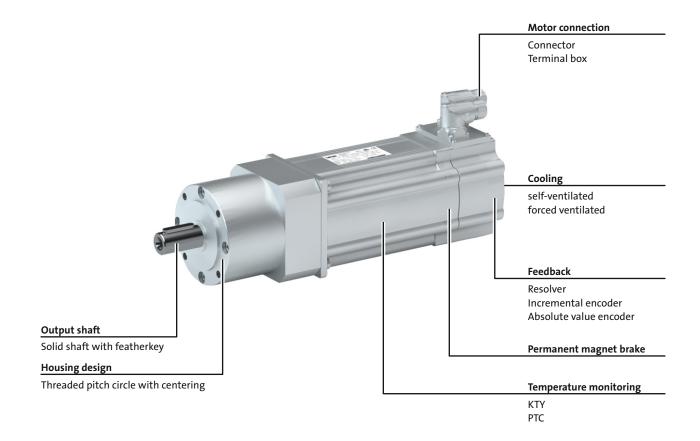
g700-P planetary geared motors

General information

Equipment

Overview

The equipment includes all the options available as standard and all
the built-on accessories of the product.

Motor connection
Connector
Terminal box

Cooling
self-ventilated
forced ventilated

Feedback
Resolver
Incremental encoder
Absolute value encoder

Permanent magnet brake

Temperature monitoring
KTY
PTC

Output shaft
Solid shaft with featherkey

Housing design
Threaded pitch circle with centering

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g700-P planetary geared motors

General information

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The gearbox kit

Geared motor

Product	g700-P20	g700-P44	g700-P130	g700-P260	g700-P800
Motor type					
	Synchronous servo motor				
Servo motor					
0.6 - 1.5 Nm	MCS06				
2.3 - 4.5 Nm		MCS09			
5.5 - 17 Nm			MCS12		
9.2 - 42 Nm				MCS14	
27 - 72 Nm				MCS19	
Technical data					
Output torque	See selection table				
Output speed	See selection table				
Ratio	See selection table				
Load capacity	See selection table				
Moment of inertia	See selection table				
Mounting position					
Standard	Any				
Colour					
	Primed Paint in various corrosion-protection designs in accordance with RAL colours				
Surface and corrosion protection					
	Without OKS(uncoated) OKS-G (primed) OKS-S (small) OKS-M (medium) OKS-L (large)				

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g700-P planetary geared motors

General information

The gearbox kit

Motor details

Product					
	MCS				
	06C41 06C60 06F41 06F60 06I41 06I60	09L41 09D41 09L51 09D60 09F38 09F60 09H41 09H60	12H14 12L17 12D17 12L20 12H15 12D20 12D35 12H34 12L39 12D41 12H35 12L41	14D14 14L14 14H12 14P11 14P14 14D15 14H15 14L15 14H28 14P26 14L30 14D30 14H32 14P32 14D36 14L32	19F12 19P12 19J12 19P14 19J14 19F14 19J29 19P29 19F29 19J30 19F30 19P30
Connection type					
	Plug connectors	Plug connectors Terminal box			
Permanent magnet holding brake					
Rated torque [Nm]	2.2	8.0	12	22	37
Brake voltage [V]	DC 24				
Feedback					
	With absolute value encoder With incremental encoder With resolver				
Cooling					
	Self-ventilated	Self-ventilated Forced-ventilated			
Temperature monitoring					
	KTY83-110 thermal detector	PTC thermistor KTY83-110 thermal detector			
Approval					
	cURus GOST_R UkrSepro				
Enclosure					
	IP54 IP65				

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► Further information and installation feasibilities can be found in the Motors chapter.

g700-P planetary geared motors

General information

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The gearbox kit

Motor details

Connection type

Plug connectors	Terminal box

Cooling: self-ventilated

With resolver	With permanent magnet brake	With feedback With feedback and permanent magnet brake

Cooling: forced ventilated

With resolver	With permanent magnet brake	With feedback With feedback and permanent magnet brake

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The gearbox kit

Gearbox details

Product	g700-P20	g700-P44	g700-P130	g700-P260	g700-P800
Driven shaft					
Solid shaft with featherkey [mm]	10x23	14x30	20x36	25x50	40x80
Design	Standard				
Gasket	NBR				
Bearing	Standard				
Housing					
Housing version	Without foot with centering				
Output flange					
flange diameter [mm]	40	60	80	115	160
Lubricant					
Type	Klüberplex BEM34-132				
Breather element	Without				
Backlash					
Backlash	Standard				

► Further information and installation feasibilities can be found in
the Gearboxes chapter.

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The gearbox kit

Gearbox details

Solid shaft
With centering |

Dimensioning

General information about the data provided in this catalogue

The powers, torques and speeds specified in this catalogue are rounded values and are valid under the following conditions:
- Operating time/day = 8 h (100% OT)
- Duty class I for up to 10 switching operations/h
- Mounting positions and designs in this catalogue
- Standard lubricant
- T_{amb} = 30 °C for gearboxes,
  T_{amb} = 40 °C for motors (in accordance with EN 60034)
- Site altitude < = 1000 m amsl
- The selection tables provide the permissible mechanical powers and torques. For notes on the thermal power limit, see chapter drive dimensioning.
- The rated power specified for motors and geared motors applies to operating mode S1 (in accordance with EN 60034).

Under different operating conditions, the values obtained may vary from those listed here.

In the case of extreme operating conditions, please consult your Lenze sales office.

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g700-P planetary geared motors

General information

Dimensioning

Load capacity and application factor

Load capacity c of gearboxes
Rated value for the load capacity of Lenze geared motors.
- c is the ratio of the permissible rated torque of the gearbox to the rated torque supplied by the drive component (e.g. the built-in Lenze motor).
- The value of c must always be greater than the value of the application factor k calculated for the application.

Required: c ≥ k

Application factor k (according to DIN 3990)
Takes into account the influence of temporally variable loads which are actually present during the anticipated operating time of gearboxes and geared motors.
k is determined by:
- the type of load
- the load intensity
- temporal influences

Duty class	Load type
I	Smooth operation, small or light jolts
II	Uneven operation, average jolts
III	Uneven operation, severe jolts and/or alternating load

Application factor k

► S_h = switchings/h

g700-P planetary geared motors

General information

Dimensioning

Weights

The values given in the tables consider the following gearbox/motor combination:
- Gearbox with solid shaft including lubricant amount
- Motor with feedback

For versions deviating from this, additional weights have to be considered.

The respective values can be found for:
- Geared motors with feedback
  > Chapter: Geared motors/Technical data
- Motor options: Brake
  > Chapter: Motors/Accessories

Moments of inertia

The given moments of inertia of the gearbox refer to the drive shaft. The influence of the ratio (i^2) has been considered in the data.

When the total moment of inertia of the geared motor is calculated, the values of the geared motors and the brake have to be added.

The respective values can be found for:
- Geared motors with feedback
  > Chapter: Geared motors/Technical data/Selection tables
- Motor options: Brake
  > Chapter: Motors/Accessories

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Selection tables, notes

Notes on the selection tables

The selection tables show the available combinations of gearbox
type, number of stages, ratio and motor. They are used only to provide
basic orientation.
The following legend indicates the structure of the selection tables.

Number of the gear stage of the gearbox

2-stage gearboxes

| Inverter operation | | | | | | i | Product | | Cooling | |
$M_{2, max}$ [Nm]	$n_{2, th}$ [r/min]	M_2 [Nm]	$n_{2, eto}$ [r/min]	c	J [kgcm²]		g700	MCS		
6.7	506	5	506	1.3	0.200	8.000	-P20	06C41	Selbst	27
9.4	579	4	579	2.1	0.200	7.000	-P20	06C41	Selbst	27
15	810	3	810	4.8	0.200	5.000	-P20	06C41	Selbst	27
17	405	6	405	2.6	0.300	10.000	-P44	06C41	Selbst	29

For operating mode S1
Torque M_2 and
thermal output speed $n_{2, th}$

Product Gearbox

Product Motor

Ratio i

Type of motor cooling

Moment of inertia of geared motor

Page number for dimensions

For operating mode S2, S3 und S6
Max. permissible acceleration torque of geared
motor $M_{2, max}$ and
output speed $n_{2, eto}$

Load capacity of the gearbox
c is the ratio between the permissible rated torque of the
gearbox and the rated torque of the three-phase AC
motor (converted to the driven shaft).
c must be always higher than the service factor k
determined for the application k.

$$c = \frac{M_{2, zul}}{M_{1,N} \cdot i \cdot \eta_{Getr}} > k$$

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g700-P planetary geared motors

Technical data

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Selection tables

1-stage gearboxes

| Inverter operation | | | | | | i | Product | | Cooling | |
$M_{2,\,max}$ [Nm]	$n_{2,\,th}$ [r/min]	M_2 [Nm]	$n_{2,\,eto}$ [r/min]	c	J [kgcm²]		g700	MCS		
5.0	450	5	450	1.1	0.200	10.000	-P20	06C60	natural	46
6.0	563	4	563	1.6	0.200	8.000	-P20	06C60	natural	46
6.0	506	5	506	1.3	0.200	8.000	-P20	06C41	natural	46
7.0	1500	1	1500	2.3	0.200	3.000	-P20	06C60	natural	46
7.0	1350	2	1350	2.2	0.200	3.000	-P20	06C41	natural	46
9.0	643	3	643	2.5	0.200	7.000	-P20	06C60	natural	46
9.0	579	4	579	2.1	0.200	7.000	-P20	06C41	natural	46
10	900	2	900	5.7	0.200	5.000	-P20	06C60	natural	46
10	810	3	810	4.8	0.200	5.000	-P20	06C41	natural	46
14	1125	3	1125	5.8	0.300	4.000	-P44	06F60	natural	48
14	643	3	643	5.1	0.200	7.000	-P44	06C60	natural	48
14	579	4	579	4.8	0.200	7.000	-P44	06C41	natural	48
15	1500	3	1500	5.6	0.400	3.000	-P44	06I60	natural	48
15	1013	4	1013	4.9	0.300	4.000	-P44	06F41	natural	48
15	450	5	450	3.1	0.300	10.000	-P44	06C60	natural	48
15	450	9	450	1.7	0.300	10.000	-P44	06F60	natural	48
15	450	12	450	1.3	0.400	10.000	-P44	06I60	natural	48
15	405	6	405	2.6	0.300	10.000	-P44	06C41	natural	48
15	405	12	405	1.3	0.300	10.000	-P44	06F41	natural	48
15	405	14	405	1.0	0.400	10.000	-P44	06I41	natural	48
16	1350	4	1350	5.1	0.400	3.000	-P44	06I41	natural	48
16	563	3	563	4.6	0.200	8.000	-P44	06C60	natural	48
17	506	4	506	3.9	0.200	8.000	-P44	06C41	natural	48
18	563	7	563	2.6	0.300	8.000	-P44	06F60	natural	48
18	563	9	563	1.9	0.400	8.000	-P44	06I60	natural	48
18	563	14	563	1.3	1.100	8.000	-P44	09D60	natural	48
18	506	9	506	1.9	0.300	8.000	-P44	06F41	natural	48
18	506	12	506	1.6	0.400	8.000	-P44	06I41	natural	48
18	506	18	506	1.0	1.100	8.000	-P44	09D41	natural	48
19	900	4	900	4.8	0.300	5.000	-P44	06F60	natural	48
19	810	5	810	4.1	0.300	5.000	-P44	06F41	natural	48
21	1125	4	1125	4.3	0.400	4.000	-P44	06I60	natural	48
22	1013	5	1013	4.0	0.400	4.000	-P44	06I41	natural	48
23	900	4	900	5.9	1.900	3.000	-P130	09D60	natural	51
24	900	6	900	5.2	1.900	3.000	-P130	09D41	natural	51
25	1500	5	1500	3.7	1.200	3.000	-P44	09D60	natural	48
25	643	6	643	2.8	0.300	7.000	-P44	06F60	natural	48
25	643	8	643	2.1	0.400	7.000	-P44	06I60	natural	48
25	643	12	643	1.4	1.100	7.000	-P44	09D60	natural	48
25	643	16	643	1.1	1.500	7.000	-P44	09F60	natural	48

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g700-P planetary geared motors

Technical data

Selection tables

1-stage gearboxes

Inverter operation						i	Product		Cooling	↗
M$_{2, max}$ [Nm]	n$_{2, th}$ [r/min]	M$_2$ [Nm]	n$_{2, eto}$ [r/min]	c	J [kgcm²]		g700	MCS		
25	579	8	579	2.4	0.300	7.000	-P44	06F41	natural	48
25	579	10	579	1.9	0.400	7.000	-P44	06I41	natural	48
25	579	15	579	1.3	1.100	7.000	-P44	09D41	natural	48
26	1350	6	1350	3.3	1.200	3.000	-P44	09D41	natural	48
28	1500	7	1500	2.8	1.600	3.000	-P44	09F60	natural	48
28	1250	9	1250	2.5	1.600	3.000	-P44	09F38	natural	48
28	900	5	900	3.6	0.400	5.000	-P44	06I60	natural	48
28	810	7	810	3.3	0.400	5.000	-P44	06I41	natural	48
28	500	6	500	5.9	0.600	8.000	-P130	06F60	natural	51
30	500	8	500	5.0	0.600	8.000	-P130	06F41	natural	51
31	625	8	625	5.6	1.600	4.000	-P130	09D41	natural	51
35	1125	7	1125	2.9	1.200	4.000	-P44	09D60	natural	48
36	1013	9	1013	2.6	1.200	4.000	-P44	09D41	natural	48
38	1125	9	1125	2.2	1.600	4.000	-P44	09F60	natural	48
38	938	12	938	2.0	1.600	4.000	-P44	09F38	natural	48
38	305	8	305	4.4	1.000	10.000	-P130	06F60	natural	51
38	305	11	305	3.3	1.000	10.000	-P130	06F41	natural	51
38	305	11	305	3.3	1.000	10.000	-P130	06I60	natural	51
38	305	14	305	2.6	1.000	10.000	-P130	06I41	natural	51
38	305	17	305	2.2	1.800	10.000	-P130	09D60	natural	51
38	305	22	305	1.7	1.800	10.000	-P130	09D41	natural	51
38	305	23	305	1.6	2.200	10.000	-P130	09F60	natural	51
38	305	29	305	1.3	2.600	10.000	-P130	09H60	natural	51
38	305	30	305	1.3	2.200	10.000	-P130	09F38	natural	51
38	305	35	305	1.1	3.500	10.000	-P130	09L51	natural	51
38	305	36	305	1.0	2.600	10.000	-P130	09H41	natural	51
39	900	6	900	4.4	2.300	3.000	-P130	09F60	natural	51
39	600	7	600	5.3	1.600	5.000	-P130	09D60	natural	51
40	900	8	900	4.0	2.300	3.000	-P130	09F38	natural	51
40	900	8	900	2.4	1.200	5.000	-P44	09D60	natural	48
40	900	12	900	1.8	1.600	5.000	-P44	09F60	natural	48
40	810	11	810	2.1	1.200	5.000	-P44	09D41	natural	48
40	750	15	750	1.6	1.600	5.000	-P44	09F38	natural	48
40	600	10	600	4.7	1.600	5.000	-P130	09D41	natural	51
43	550	17	550	5.6	6.600	3.000	-P260	12D17	forced	68
43	500	8	500	4.4	0.700	8.000	-P130	06I60	natural	51
44	500	11	500	4.0	0.700	8.000	-P130	06I41	natural	51
50	900	12	900	2.8	4.800	3.000	-P130	12D41	natural	51
50	650	15	650	2.8	4.800	3.000	-P130	12D20	natural	51
50	550	20	550	2.3	4.800	3.000	-P130	12D17	forced	66

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g700-P planetary geared motors

Technical data

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Selection tables

1-stage gearboxes

Inverter operation						i	Product		Cooling	⌀
$M_{2, max}$ [Nm]	$n_{2, th}$ [r/min]	M_2 [Nm]	$n_{2, eto}$ [r/min]	c	J [kgcm²]		g700	MCS		
50	500	13	500	2.9	1.500	8.000	-P130	09D60	natural	51
50	500	17	500	2.6	1.500	8.000	-P130	09D41	natural	51
50	500	18	500	2.2	1.900	8.000	-P130	09F60	natural	51
50	500	23	500	1.8	2.300	8.000	-P130	09H60	natural	51
50	500	28	500	1.6	3.200	8.000	-P130	09L51	natural	51
50	500	29	500	1.6	2.300	8.000	-P130	09H41	natural	51
50	500	33	500	1.4	4.400	8.000	-P130	12D41	natural	51
50	500	35	500	1.3	3.200	8.000	-P130	09L41	natural	51
50	469	24	469	2.0	1.900	8.000	-P130	09F38	natural	51
50	441	46	441	1.1	4.400	8.000	-P130	12D35	forced	66
50	244	42	244	1.2	4.400	8.000	-P130	12D20	natural	51
51	900	17	900	2.1	4.800	3.000	-P130	12D35	forced	66
51	625	8	625	4.7	2.000	4.000	-P130	09F60	natural	51
52	625	11	625	4.3	2.000	4.000	-P130	09F38	natural	51
54	900	8	900	3.5	2.700	3.000	-P130	09H60	natural	51
55	900	10	900	3.2	2.700	3.000	-P130	09H41	natural	51
57	571	11	571	4.7	1.500	7.000	-P130	09D60	natural	51
58	413	23	413	5.7	5.800	4.000	-P260	12D17	forced	68
59	571	14	571	4.0	1.500	7.000	-P130	09D41	natural	51
62	571	15	571	3.5	1.900	7.000	-P130	09F60	natural	51
62	571	19	571	2.8	2.300	7.000	-P130	09H60	natural	51
62	571	24	571	2.5	3.200	7.000	-P130	09L51	natural	51
62	571	25	571	2.4	2.300	7.000	-P130	09H41	natural	51
62	571	29	571	2.1	4.400	7.000	-P130	12D41	natural	51
62	571	30	571	2.0	3.200	7.000	-P130	09L41	natural	51
62	536	20	536	3.0	1.900	7.000	-P130	09F38	natural	51
62	504	40	504	1.5	4.400	7.000	-P130	12D35	forced	66
62	504	50	504	1.2	7.700	7.000	-P130	12H35	natural	51
62	429	54	429	1.1	7.700	7.000	-P130	12H30	natural	51
62	279	37	279	1.7	4.400	7.000	-P130	12D20	natural	51
62	236	47	236	1.3	4.400	7.000	-P130	12D17	forced	66
66	625	16	625	3.0	4.500	4.000	-P130	12D41	natural	51
66	600	11	600	4.0	1.900	5.000	-P130	09F60	natural	51
66	488	20	488	3.0	4.500	4.000	-P130	12D20	natural	51
67	625	23	625	2.2	4.500	4.000	-P130	12D35	forced	66
67	600	14	600	3.6	1.900	5.000	-P130	09F38	natural	51
67	413	26	413	2.5	4.500	4.000	-P130	12D17	forced	66
71	625	11	625	3.8	2.400	4.000	-P130	09H60	natural	51
72	625	14	625	3.4	2.400	4.000	-P130	09H41	natural	51
72	330	28	330	5.7	5.500	5.000	-P260	12D17	forced	68

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g700-P planetary geared motors

Technical data

Selection tables

1-stage gearboxes

Inverter operation						i	Product		Cooling	⌀
$M_{2, max}$ [Nm]	$n_{2, th}$ [r/min]	M_2 [Nm]	$n_{2, eto}$ [r/min]	c	J [kgcm²]		g700	MCS		
73	867	19	867	5.1	11.000	3.000	-P260	14D36	natural	56
73	867	19	867	5.1	9.900	3.000	-P260	12H35	natural	56
73	867	20	867	4.9	9.900	3.000	-P260	12H30	natural	56
76	500	24	500	4.3	11.000	3.000	-P260	14D15	natural	56
77	500	27	500	3.9	9.900	3.000	-P260	12H15	natural	56
78	867	28	867	3.7	11.000	3.000	-P260	14D30	forced	68
78	867	28	867	3.7	9.900	3.000	-P260	12H34	forced	68
78	350	15	350	5.4	3.700	10.000	-P260	09D60	natural	56
79	450	33	450	3.3	11.000	3.000	-P260	14D14	forced	68
79	450	33	450	3.3	9.900	3.000	-P260	12H14	forced	68
83	350	20	350	4.3	3.700	10.000	-P260	09D41	natural	56
84	900	22	900	1.7	8.100	3.000	-P130	12H35	natural	51
84	900	23	900	1.7	8.100	3.000	-P130	12H30	natural	51
84	500	29	500	1.7	8.100	3.000	-P130	12H15	natural	51
85	900	10	900	3.1	3.600	3.000	-P130	09L51	natural	51
85	900	13	900	2.7	3.600	3.000	-P130	09L41	natural	51
85	600	20	600	2.5	4.500	5.000	-P130	12D41	natural	51
85	600	29	600	1.9	4.500	5.000	-P130	12D35	forced	66
85	390	26	390	2.5	4.500	5.000	-P130	12D20	natural	51
85	330	33	330	2.1	4.500	5.000	-P130	12D17	forced	66
91	600	14	600	3.2	2.400	5.000	-P130	09H60	natural	51
93	600	18	600	2.9	2.400	5.000	-P130	09H41	natural	51
95	350	21	350	4.1	4.100	10.000	-P260	09F60	natural	56
95	350	27	350	3.3	4.500	10.000	-P260	09H60	natural	56
95	350	28	350	3.2	4.100	10.000	-P260	09F38	natural	56
95	350	34	350	2.7	5.400	10.000	-P260	09L51	natural	56
95	350	36	350	2.6	4.500	10.000	-P260	09H41	natural	56
95	350	41	350	2.3	6.600	10.000	-P260	12D41	natural	56
95	350	43	350	2.2	5.400	10.000	-P260	09L41	natural	56
95	350	58	350	1.6	6.600	10.000	-P260	12D35	forced	68
95	350	72	350	1.3	11.000	10.000	-P260	14D36	natural	56
95	350	72	350	1.3	9.900	10.000	-P260	12H35	natural	56
95	300	77	300	1.2	9.900	10.000	-P260	12H30	natural	56
95	195	53	195	1.8	6.600	10.000	-P260	12D20	natural	56
95	165	67	165	1.4	6.600	10.000	-P260	12D17	forced	68
95	150	88	150	1.1	11.000	10.000	-P260	14D15	natural	56
96	625	25	625	5.3	9.800	4.000	-P260	14D36	natural	56
96	625	25	625	5.3	9.100	4.000	-P260	12H35	natural	56
98	625	27	625	4.9	9.100	4.000	-P260	12H30	natural	56
101	438	21	438	5.0	2.800	8.000	-P260	09F38	natural	56

g700-P planetary geared motors

Technical data

Selection tables

1-stage gearboxes

Inverter operation						i	Product		Cooling	
$M_{2, max}$ [Nm]	$n_{2, th}$ [r/min]	M_2 [Nm]	$n_{2, eto}$ [r/min]	c	J [kgcm²]		g700	MCS		
101	375	32	375	4.3	9.800	4.000	-P260	14D15	natural	56
102	375	35	375	4.0	9.100	4.000	-P260	12H15	natural	56
103	625	37	625	3.8	9.800	4.000	-P260	14D30	forced	68
103	625	37	625	3.8	9.100	4.000	-P260	12H34	forced	68
105	338	44	338	3.3	9.800	4.000	-P260	14D14	forced	68
105	338	44	338	3.3	9.100	4.000	-P260	12H14	forced	68
108	500	26	500	4.6	5.400	7.000	-P260	12D41	natural	56
110	600	17	600	2.8	3.300	5.000	-P130	09L51	natural	51
110	600	21	600	2.4	3.300	5.000	-P130	09L41	natural	51
110	600	36	600	1.5	7.800	5.000	-P130	12H35	natural	51
110	600	38	600	1.5	7.800	5.000	-P130	12H30	natural	51
110	300	48	300	1.5	7.800	5.000	-P130	12H15	natural	51
111	625	29	625	1.8	7.800	4.000	-P130	12H35	natural	51
111	625	31	625	1.8	7.800	4.000	-P130	12H30	natural	51
111	375	38	375	1.8	7.800	4.000	-P130	12H15	natural	51
112	500	38	500	3.3	5.400	7.000	-P260	12D35	forced	68
113	279	34	279	3.6	5.400	7.000	-P260	12D20	natural	56
115	867	30	867	3.4	13.000	3.000	-P260	12L41	natural	56
115	867	39	867	2.8	17.000	3.000	-P260	14H32	natural	56
115	867	39	867	2.7	13.000	3.000	-P260	12L39	forced	68
115	867	49	867	2.3	26.000	3.000	-P260	14L32	natural	56
115	867	60	867	1.9	70.000	3.000	-P260	19F30	natural	56
115	650	37	650	2.9	13.000	3.000	-P260	12L20	natural	56
115	625	13	625	3.3	3.300	4.000	-P130	09L51	natural	51
115	625	17	625	2.9	3.300	4.000	-P130	09L41	natural	51
115	550	48	550	2.3	13.000	3.000	-P260	12L17	forced	68
115	500	45	500	2.4	17.000	3.000	-P260	14H15	natural	56
115	500	66	500	1.7	26.000	3.000	-P260	14L15	natural	56
115	475	78	475	1.4	70.000	3.000	-P260	19F14	natural	56
115	236	45	236	2.8	5.400	7.000	-P260	12D17	forced	68
116	500	22	500	5.2	3.300	7.000	-P260	09H41	natural	56
120	500	31	500	5.3	9.600	5.000	-P260	14D36	natural	56
120	500	31	500	5.3	8.800	5.000	-P260	12H35	natural	56
120	438	20	438	5.2	3.200	8.000	-P260	09H60	natural	56
120	438	25	438	4.3	4.100	8.000	-P260	09L51	natural	56
120	438	27	438	4.1	3.200	8.000	-P260	09H41	natural	56
120	438	31	438	3.6	5.300	8.000	-P260	12D41	natural	56
120	438	32	438	3.4	4.100	8.000	-P260	09L41	natural	56
120	438	45	438	2.6	5.300	8.000	-P260	12D35	forced	68
120	438	57	438	2.1	9.400	8.000	-P260	14D36	natural	56

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g700-P planetary geared motors

Technical data

Selection tables

1-stage gearboxes

Inverter operation						i	Product		Cooling	
M$_{2, max}$ [Nm]	n$_{2, th}$ [r/min]	M$_2$ [Nm]	n$_{2, eto}$ [r/min]	c	J [kgcm²]		g700	MCS		
120	438	57	438	2.1	8.600	8.000	-P260	12H35	natural	56
120	438	84	438	1.4	12.000	8.000	-P260	12L41	natural	56
120	438	108	438	1.1	12.000	8.000	-P260	12L39	forced	68
120	422	81	422	1.5	8.600	8.000	-P260	12H34	forced	68
120	403	108	403	1.1	15.000	8.000	-P260	14H32	natural	56
120	375	61	375	1.9	8.600	8.000	-P260	12H30	natural	56
120	375	81	375	1.5	9.400	8.000	-P260	14D30	forced	68
120	244	41	244	2.8	5.300	8.000	-P260	12D20	natural	56
120	244	104	244	1.1	12.000	8.000	-P260	12L20	natural	56
120	206	53	206	2.2	5.300	8.000	-P260	12D17	forced	68
120	188	71	188	1.7	9.400	8.000	-P260	14D15	natural	56
120	188	77	188	1.6	8.600	8.000	-P260	12H15	natural	56
120	169	92	169	1.3	9.400	8.000	-P260	14D14	forced	68
120	169	92	169	1.3	8.600	8.000	-P260	12H14	forced	68
122	500	34	500	5.0	8.800	5.000	-P260	12H30	natural	56
126	300	40	300	4.3	9.600	5.000	-P260	14D15	natural	56
128	300	44	300	4.0	8.800	5.000	-P260	12H15	natural	56
129	500	47	500	3.8	9.600	5.000	-P260	14D30	forced	68
129	500	47	500	3.8	8.800	5.000	-P260	12H34	forced	68
132	270	54	270	3.3	9.600	5.000	-P260	14D14	forced	68
132	270	54	270	3.3	8.800	5.000	-P260	12H14	forced	68
135	500	21	500	5.5	4.200	7.000	-P260	09L51	natural	56
135	500	27	500	4.4	4.200	7.000	-P260	09L41	natural	56
135	500	49	500	2.6	9.500	7.000	-P260	14D36	natural	56
135	500	49	500	2.6	8.700	7.000	-P260	12H35	natural	56
135	500	74	500	1.8	12.000	7.000	-P260	12L41	natural	56
135	500	94	500	1.4	12.000	7.000	-P260	12L39	forced	68
135	482	71	482	1.9	8.700	7.000	-P260	12H34	forced	68
135	461	94	461	1.4	16.000	7.000	-P260	14H32	natural	56
135	461	116	461	1.2	25.000	7.000	-P260	14L32	natural	56
135	429	53	429	2.5	8.700	7.000	-P260	12H30	natural	56
135	429	71	429	1.9	9.500	7.000	-P260	14D30	forced	68
135	279	91	279	1.5	12.000	7.000	-P260	12L20	natural	56
135	236	114	236	1.2	12.000	7.000	-P260	12L17	forced	68
135	214	61	214	2.2	9.500	7.000	-P260	14D15	natural	56
135	214	67	214	2.0	8.700	7.000	-P260	12H15	natural	56
135	214	108	214	1.2	16.000	7.000	-P260	14H15	natural	56
135	193	81	193	1.7	9.500	7.000	-P260	14D14	forced	68
135	193	81	193	1.7	8.700	7.000	-P260	12H14	forced	68
136	300	33	300	5.8	23.000	3.000	-P800	12L20	natural	62

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g700-P planetary geared motors

Technical data

Selection tables

1-stage gearboxes

Inverter operation						i	Product		Cooling	⌀
$M_{2, max}$ [Nm]	$n_{2, th}$ [r/min]	M_2 [Nm]	$n_{2, eto}$ [r/min]	c	J [kgcm²]		g700	MCS		
136	300	40	300	5.4	26.000	3.000	-P800	14H15	natural	62
137	300	27	300	5.6	23.000	3.000	-P800	12L41	natural	62
140	300	36	300	4.7	26.000	3.000	-P800	14H32	natural	62
143	300	43	300	4.9	23.000	3.000	-P800	12L17	forced	70
145	300	62	300	3.9	26.000	3.000	-P800	14H12	forced	70
146	300	36	300	4.5	23.000	3.000	-P800	12L39	forced	70
149	300	56	300	3.4	26.000	3.000	-P800	14H28	forced	70
155	625	39	625	3.6	12.000	4.000	-P260	12L41	natural	56
155	625	52	625	2.8	16.000	4.000	-P260	14H32	natural	56
155	625	52	625	2.8	12.000	4.000	-P260	12L39	forced	68
155	625	65	625	2.3	25.000	4.000	-P260	14L32	natural	56
155	625	81	625	1.9	69.000	4.000	-P260	19F30	natural	56
155	488	50	488	2.9	12.000	4.000	-P260	12L20	natural	56
155	413	64	413	2.3	12.000	4.000	-P260	12L17	forced	68
155	375	60	375	2.5	16.000	4.000	-P260	14H15	natural	56
155	375	88	375	1.7	25.000	4.000	-P260	14L15	natural	56
155	356	104	356	1.5	69.000	4.000	-P260	19F14	natural	56
179	250	67	250	5.6	22.000	4.000	-P800	14H28	forced	70
185	250	79	250	4.9	22.000	4.000	-P800	14H12	forced	70
187	188	65	188	5.8	12.000	8.000	-P800	12H15	natural	62
190	194	69	194	5.5	12.000	8.000	-P800	12H34	forced	70
190	194	69	194	5.5	13.000	8.000	-P800	14D30	forced	70
195	500	49	500	3.6	12.000	5.000	-P260	12L41	natural	56
195	500	65	500	2.8	16.000	5.000	-P260	14H32	natural	56
195	500	65	500	2.8	12.000	5.000	-P260	12L39	forced	68
195	500	81	500	2.3	25.000	5.000	-P260	14L32	natural	56
195	500	101	500	1.9	69.000	5.000	-P260	19F30	natural	56
195	390	62	390	3.0	12.000	5.000	-P260	12L20	natural	56
195	330	80	330	2.3	12.000	5.000	-P260	12L17	forced	68
195	300	75	300	2.5	16.000	5.000	-P260	14H15	natural	56
195	300	110	300	1.7	25.000	5.000	-P260	14L15	natural	56
195	285	130	285	1.5	69.000	5.000	-P260	19F14	natural	56
196	169	81	169	4.8	12.000	8.000	-P800	12H14	forced	70
196	169	81	169	4.8	13.000	8.000	-P800	14D14	forced	70
205	300	46	300	3.9	36.000	3.000	-P800	14L32	natural	62
206	300	61	300	3.7	36.000	3.000	-P800	14L15	natural	62
214	300	85	300	2.9	36.000	3.000	-P800	14L14	forced	70
216	300	71	300	2.7	36.000	3.000	-P800	14L30	forced	70
223	230	65	230	5.7	20.000	5.000	-P800	14H15	natural	62
232	230	70	230	5.4	17.000	5.000	-P800	12L17	forced	70

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g700-P planetary geared motors

Technical data

Selection tables

1-stage gearboxes

Inverter operation						i	Product		Cooling	↔
$M_{2, max}$ [Nm]	$n_{2, th}$ [r/min]	M_2 [Nm]	$n_{2, eto}$ [r/min]	c	J [kgcm²]		g700	MCS		
235	300	57	300	3.2	77.000	3.000	-P800	19F30	natural	62
235	300	74	300	3.2	77.000	3.000	-P800	19F14	natural	62
236	230	88	230	4.5	20.000	5.000	-P800	14H28	forced	70
242	230	104	230	3.9	20.000	5.000	-P800	14H12	forced	70
243	300	107	300	2.4	77.000	3.000	-P800	19F12	forced	70
246	300	93	300	2.1	77.000	3.000	-P800	19F29	forced	70
259	250	77	250	5.0	31.000	4.000	-P800	14L15	natural	62
265	250	88	250	4.5	31.000	4.000	-P800	14L30	forced	70
274	250	109	250	3.8	31.000	4.000	-P800	14L14	forced	70
283	250	69	250	5.5	73.000	4.000	-P800	19F30	natural	62
288	300	58	300	3.2	47.000	3.000	-P800	14P32	natural	62
290	300	83	300	3.0	47.000	3.000	-P800	14P14	natural	62
299	300	119	300	2.3	47.000	3.000	-P800	14P11	forced	70
299	250	94	250	4.3	73.000	4.000	-P800	19F14	natural	62
300	300	94	300	2.2	47.000	3.000	-P800	14P26	forced	70
309	250	117	250	3.5	73.000	4.000	-P800	19F29	forced	70
316	250	140	250	3.0	73.000	4.000	-P800	19F12	forced	70
318	230	71	230	5.3	29.000	5.000	-P800	14L32	natural	62
339	230	101	230	4.0	29.000	5.000	-P800	14L15	natural	62
345	250	69	250	5.5	42.000	4.000	-P800	14P32	natural	62
345	230	114	230	3.6	29.000	5.000	-P800	14L30	forced	70
354	230	140	230	3.0	29.000	5.000	-P800	14L14	forced	70
366	300	82	300	2.4	117.000	3.000	-P800	19J30	natural	62
369	300	114	300	2.2	117.000	3.000	-P800	19J14	natural	62
371	194	73	194	5.3	15.000	8.000	-P800	12L41	natural	62
372	300	145	300	1.4	117.000	3.000	-P800	19J29	forced	70
372	300	180	300	1.5	117.000	3.000	-P800	19J12	forced	70
372	230	91	230	4.4	71.000	5.000	-P800	19F30	natural	62
373	250	106	250	3.8	42.000	4.000	-P800	14P14	natural	62
378	250	119	250	3.5	42.000	4.000	-P800	14P26	forced	70
385	194	98	194	4.1	19.000	8.000	-P800	14H32	natural	62
389	230	122	230	3.4	71.000	5.000	-P800	19F14	natural	62
389	194	94	194	4.3	15.000	8.000	-P800	12L20	natural	62
391	250	156	250	2.7	42.000	4.000	-P800	14P11	forced	70
394	194	98	194	4.1	15.000	8.000	-P800	12L39	forced	70
394	188	115	188	3.6	19.000	8.000	-P800	14H15	natural	62
399	230	151	230	2.8	71.000	5.000	-P800	19F29	forced	70
400	300	92	300	2.1	172.000	3.000	-P800	19P30	natural	62
400	300	147	300	1.7	172.000	3.000	-P800	19P14	natural	62
400	300	153	300	1.3	172.000	3.000	-P800	19P29	forced	70

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g700-P planetary geared motors

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1-stage gearboxes

| Inverter operation | | | | | | i | Product | | Cooling | ⌀ |
$M_{2, max}$ [Nm]	$n_{2, th}$ [r/min]	M_2 [Nm]	$n_{2, eto}$ [r/min]	c	J [kgcm²]		g700	MCS		
400	300	207	300	1.3	172.000	3.000	-P800	19P12	forced	70
406	230	179	230	2.4	71.000	5.000	-P800	19F12	forced	70
406	194	152	194	2.8	19.000	8.000	-P800	14H28	forced	70
408	194	123	194	3.4	15.000	8.000	-P800	12L17	forced	70
413	150	177	150	2.5	19.000	8.000	-P800	14H12	forced	70
450	250	102	250	4.0	113.000	4.000	-P800	19J30	natural	62
450	250	115	250	3.6	168.000	4.000	-P800	19P30	natural	62
450	250	148	250	2.9	113.000	4.000	-P800	19J14	natural	62
450	250	192	250	2.3	113.000	4.000	-P800	19J29	forced	70
450	250	194	250	2.3	168.000	4.000	-P800	19P14	natural	62
450	250	202	250	2.2	168.000	4.000	-P800	19P29	forced	70
450	250	240	250	1.8	113.000	4.000	-P800	19J12	forced	70
450	250	276	250	1.6	168.000	4.000	-P800	19P12	forced	70
450	230	91	230	4.4	41.000	5.000	-P800	14P32	natural	62
450	230	132	230	3.2	111.000	5.000	-P800	19J30	natural	62
450	230	138	230	3.1	41.000	5.000	-P800	14P14	natural	62
450	230	148	230	2.9	166.000	5.000	-P800	19P30	natural	62
450	230	153	230	2.8	41.000	5.000	-P800	14P26	forced	70
450	230	190	230	2.3	111.000	5.000	-P800	19J14	natural	62
450	230	242	230	1.8	111.000	5.000	-P800	19J29	forced	70
450	230	245	230	1.8	166.000	5.000	-P800	19P14	natural	62
450	230	254	230	1.7	166.000	5.000	-P800	19P29	forced	70
450	230	300	230	1.5	111.000	5.000	-P800	19J12	forced	70
450	230	346	230	1.3	166.000	5.000	-P800	19P12	forced	70
450	210	200	210	2.2	41.000	5.000	-P800	14P11	forced	70
450	194	125	194	3.4	28.000	8.000	-P800	14L32	natural	62
450	194	156	194	2.8	70.000	8.000	-P800	19F30	natural	62
450	194	156	194	2.8	39.000	8.000	-P800	14P32	natural	62
450	194	194	194	2.3	28.000	8.000	-P800	14L30	forced	70
450	194	223	194	2.0	110.000	8.000	-P800	19J30	natural	62
450	194	246	194	1.8	165.000	8.000	-P800	19P30	natural	62
450	194	250	194	1.8	70.000	8.000	-P800	19F29	forced	70
450	194	253	194	1.8	39.000	8.000	-P800	14P26	forced	70
450	194	388	194	1.1	110.000	8.000	-P800	19J29	forced	70
450	194	407	194	1.1	165.000	8.000	-P800	19P29	forced	70
450	188	173	188	2.5	28.000	8.000	-P800	14L15	natural	62
450	178	206	178	2.1	70.000	8.000	-P800	19F14	natural	62
450	178	307	178	1.4	110.000	8.000	-P800	19J14	natural	62
450	169	230	169	1.9	39.000	8.000	-P800	14P14	natural	62
450	169	234	169	1.9	28.000	8.000	-P800	14L14	forced	70

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g700-P planetary geared motors

Technical data

Selection tables

1-stage gearboxes

Inverter operation						i	Product		Cooling	
$M_{2, max}$ [Nm]	$n_{2, th}$ [r/min]	M_2 [Nm]	$n_{2, eto}$ [r/min]	c	J [kgcm²]		g700	MCS		
450	169	392	169	1.1	165.000	8.000	-P800	19P14	natural	62
450	150	292	150	1.5	70.000	8.000	-P800	19F12	forced	70
450	131	323	131	1.4	39.000	8.000	-P800	14P11	forced	70

g700-P planetary geared motors

Technical data

Selection tables

2-stage gearboxes

Inverter operation						i	Product		Cooling	
$M_{2, max}$ [Nm]	$n_{2, th}$ [r/min]	M_2 [Nm]	$n_{2, eto}$ [r/min]	c	J [kgcm²]		g700	MCS		
14	450	4	450	5.9	0.200	9.000	-P44	06C41	natural	49
17	500	4	500	2.3	0.200	9.000	-P20	06C60	natural	47
17	450	5	450	2.2	0.200	9.000	-P20	06C41	natural	47
18	300	7	300	2.5	0.200	15.000	-P20	06C60	natural	47
18	270	8	270	2.1	0.200	15.000	-P20	06C41	natural	47
18	180	12	180	1.6	0.200	25.000	-P20	06C60	natural	47
18	162	14	162	1.3	0.200	25.000	-P20	06C41	natural	47
20	375	5	375	2.6	0.200	12.000	-P20	06C60	natural	47
20	338	7	338	2.4	0.200	12.000	-P20	06C41	natural	47
20	281	7	281	2.6	0.200	16.000	-P20	06C60	natural	47
20	253	9	253	2.2	0.200	16.000	-P20	06C41	natural	47
20	225	9	225	2.1	0.200	20.000	-P20	06C60	natural	47
20	203	11	203	1.8	0.200	20.000	-P20	06C41	natural	47
20	141	15	141	1.4	0.200	32.000	-P20	06C60	natural	47
20	127	18	127	1.1	0.200	32.000	-P20	06C41	natural	47
21	375	4	375	5.0	0.300	12.000	-P44	06C60	natural	49
22	338	5	338	4.8	0.300	12.000	-P44	06C41	natural	49
28	300	6	300	4.5	0.200	15.000	-P44	06C60	natural	49
28	270	7	270	4.2	0.200	15.000	-P44	06C41	natural	49
30	281	6	281	4.1	0.200	16.000	-P44	06C60	natural	49
31	253	8	253	3.9	0.200	16.000	-P44	06C41	natural	49
33	500	7	500	3.4	0.300	9.000	-P44	06F60	natural	49
35	450	9	450	2.9	0.300	9.000	-P44	06F41	natural	49
38	313	10	313	5.2	0.900	12.000	-P130	06F41	natural	53
40	225	8	225	3.6	0.200	20.000	-P44	06C60	natural	49
40	203	10	203	3.4	0.200	20.000	-P44	06C41	natural	49
40	180	11	180	3.0	0.200	25.000	-P44	06C60	natural	49
40	180	21	180	1.7	0.300	25.000	-P44	06F60	natural	49
40	180	28	180	1.3	0.400	25.000	-P44	06I60	natural	49
40	162	13	162	2.8	0.200	25.000	-P44	06C41	natural	49
40	162	28	162	1.4	0.300	25.000	-P44	06F41	natural	49
40	162	35	162	1.1	0.400	25.000	-P44	06I41	natural	49
40	113	19	113	2.1	0.200	40.000	-P44	06C60	natural	49
40	113	34	113	1.2	0.300	40.000	-P44	06F60	natural	49
40	101	23	101	1.8	0.200	40.000	-P44	06C41	natural	49
44	500	10	500	2.6	0.400	9.000	-P44	06I60	natural	49
44	500	15	500	1.7	1.200	9.000	-P44	09D60	natural	49
44	500	20	500	1.3	1.600	9.000	-P44	09F60	natural	49
44	450	12	450	2.4	0.400	9.000	-P44	06I41	natural	49
44	450	19	450	1.5	1.200	9.000	-P44	09D41	natural	49

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g700-P planetary geared motors

Technical data

Selection tables

2-stage gearboxes

Inverter operation						i	Product		Cooling	
$M_{2, max}$ [Nm]	$n_{2, th}$ [r/min]	M_2 [Nm]	$n_{2, eto}$ [r/min]	c	J [kgcm²]		g700	MCS		
44	417	26	417	1.2	1.600	9.000	-P44	09F38	natural	49
44	375	10	375	2.8	0.300	12.000	-P44	06F60	natural	49
44	375	13	375	2.1	0.400	12.000	-P44	06I60	natural	49
44	375	20	375	1.4	1.200	12.000	-P44	09D60	natural	49
44	375	27	375	1.0	1.600	12.000	-P44	09F60	natural	49
44	338	13	338	2.4	0.300	12.000	-P44	06F41	natural	49
44	338	17	338	1.9	0.400	12.000	-P44	06I41	natural	49
44	338	26	338	1.2	1.200	12.000	-P44	09D41	natural	49
44	300	12	300	2.5	0.300	15.000	-P44	06F60	natural	49
44	300	17	300	1.9	0.400	15.000	-P44	06I60	natural	49
44	300	25	300	1.2	1.100	15.000	-P44	09D60	natural	49
44	281	13	281	2.3	0.300	16.000	-P44	06F60	natural	49
44	281	18	281	1.7	0.400	16.000	-P44	06I60	natural	49
44	281	27	281	1.1	1.200	16.000	-P44	09D60	natural	49
44	270	17	270	2.1	0.300	15.000	-P44	06F41	natural	49
44	270	21	270	1.7	0.400	15.000	-P44	06I41	natural	49
44	270	32	270	1.1	1.100	15.000	-P44	09D41	natural	49
44	253	18	253	2.0	0.300	16.000	-P44	06F41	natural	49
44	253	23	253	1.6	0.400	16.000	-P44	06I41	natural	49
44	253	35	253	1.0	1.200	16.000	-P44	09D41	natural	49
44	225	17	225	2.0	0.300	20.000	-P44	06F60	natural	49
44	225	23	225	1.5	0.400	20.000	-P44	06I60	natural	49
44	203	23	203	1.7	0.300	20.000	-P44	06F41	natural	49
44	203	28	203	1.4	0.400	20.000	-P44	06I41	natural	49
44	141	14	141	2.6	0.200	32.000	-P44	06C60	natural	49
44	141	27	141	1.5	0.300	32.000	-P44	06F60	natural	49
44	141	36	141	1.1	0.400	32.000	-P44	06I60	natural	49
44	127	17	127	2.4	0.200	32.000	-P44	06C41	natural	49
44	127	36	127	1.2	0.300	32.000	-P44	06F41	natural	49
47	267	10	267	5.2	0.900	15.000	-P130	06F60	natural	53
50	63	28	63	1.8	0.700	64.000	-P130	06C60	natural	53
50	63	34	63	1.5	0.700	64.000	-P130	06C41	natural	53
51	267	14	267	4.4	0.900	15.000	-P130	06F41	natural	53
51	250	10	250	5.0	0.700	16.000	-P130	06F60	natural	53
52	125	11	125	5.8	0.500	32.000	-P130	06C60	natural	53
53	125	13	125	5.5	0.500	32.000	-P130	06C41	natural	53
55	250	15	250	4.3	0.700	16.000	-P130	06F41	natural	53
57	313	11	313	4.5	1.000	12.000	-P130	06I60	natural	53
59	313	14	313	4.1	1.000	12.000	-P130	06I41	natural	53
64	444	12	444	4.8	1.500	9.000	-P130	09D60	natural	53

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g700-P planetary geared motors

Technical data

Selection tables

2-stage gearboxes

Inverter operation						i	Product		Cooling	
$M_{2, max}$ [Nm]	$n_{2, th}$ [r/min]	M_2 [Nm]	$n_{2, eto}$ [r/min]	c	J [kgcm²]		g700	MCS		
67	444	16	444	4.3	1.500	9.000	-P130	09D41	natural	53
68	200	14	200	4.4	0.700	20.000	-P130	06F60	natural	53
70	100	15	100	5.0	0.500	40.000	-P130	06C60	natural	53
72	200	20	200	3.7	0.700	20.000	-P130	06F41	natural	53
72	100	18	100	4.7	0.500	40.000	-P130	06C41	natural	53
75	267	15	267	3.9	1.000	15.000	-P130	06I60	natural	53
77	267	19	267	3.5	1.000	15.000	-P130	06I41	natural	53
81	250	16	250	3.8	0.800	16.000	-P130	06I60	natural	53
83	250	20	250	3.5	0.800	16.000	-P130	06I41	natural	53
90	160	18	160	3.7	0.700	25.000	-P130	06F60	natural	53
93	294	19	294	5.5	2.800	9.000	-P260	09F38	natural	58
94	160	26	160	3.2	0.700	25.000	-P130	06F41	natural	53
99	313	19	313	3.0	1.800	12.000	-P130	09D60	natural	53
102	313	25	313	2.7	1.800	12.000	-P130	09D41	natural	53
106	200	20	200	3.3	0.700	20.000	-P130	06I60	natural	53
108	200	26	200	3.0	0.700	20.000	-P130	06I41	natural	53
110	267	24	267	2.6	1.800	15.000	-P130	09D60	natural	53
110	267	32	267	2.3	1.800	15.000	-P130	09D41	natural	53
110	267	34	267	1.9	2.200	15.000	-P130	09F60	natural	53
110	267	42	267	1.6	2.600	15.000	-P130	09H60	natural	53
110	267	51	267	1.4	3.500	15.000	-P130	09L51	natural	53
110	267	54	267	1.4	2.600	15.000	-P130	09H41	natural	53
110	267	61	267	1.2	4.700	15.000	-P130	12D41	natural	53
110	267	63	267	1.2	3.500	15.000	-P130	09L41	natural	53
110	250	44	250	1.8	2.200	15.000	-P130	09F38	natural	53
110	160	27	160	2.8	0.700	25.000	-P130	06I60	natural	53
110	160	34	160	2.5	0.700	25.000	-P130	06I41	natural	53
110	160	42	160	1.9	1.500	25.000	-P130	09D60	natural	53
110	160	54	160	1.7	1.500	25.000	-P130	09D41	natural	53
110	160	56	160	1.4	1.900	25.000	-P130	09F60	natural	53
110	160	71	160	1.1	2.300	25.000	-P130	09H60	natural	53
110	160	89	160	1.0	2.300	25.000	-P130	09H41	natural	53
110	150	73	150	1.3	1.900	25.000	-P130	09F38	natural	53
110	130	78	130	1.2	4.700	15.000	-P130	12D20	natural	53
110	110	99	110	1.0	4.700	15.000	-P130	12D17	forced	67
110	100	32	100	2.8	0.600	40.000	-P130	06F60	natural	53
110	100	44	100	2.4	0.600	40.000	-P130	06F41	natural	53
110	100	45	100	2.1	0.700	40.000	-P130	06I60	natural	53
110	100	56	100	1.9	0.700	40.000	-P130	06I41	natural	53
110	100	68	100	1.4	1.500	40.000	-P130	09D60	natural	53

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g700-P planetary geared motors

Technical data

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Selection tables

2-stage gearboxes

Inverter operation						i	Product		Cooling	
$M_{2, max}$ [Nm]	$n_{2, th}$ [r/min]	M_2 [Nm]	$n_{2, eto}$ [r/min]	c	J [kgcm²]		g700	MCS		
110	100	86	100	1.2	1.500	40.000	-P130	09D41	natural	53
110	100	90	100	1.0	1.900	40.000	-P130	09F60	natural	53
112	444	18	444	3.6	1.900	9.000	-P130	09F60	natural	53
115	417	24	417	3.3	1.900	9.000	-P130	09F38	natural	53
120	313	27	313	2.3	2.200	12.000	-P130	09F60	natural	53
120	313	34	313	1.8	2.600	12.000	-P130	09H60	natural	53
120	313	35	313	2.1	2.200	12.000	-P130	09F38	natural	53
120	313	41	313	1.6	3.500	12.000	-P130	09L51	natural	53
120	313	43	313	1.6	2.600	12.000	-P130	09H41	natural	53
120	313	49	313	1.4	4.700	12.000	-P130	12D41	natural	53
120	313	51	313	1.4	3.500	12.000	-P130	09L41	natural	53
120	294	68	294	1.1	4.700	12.000	-P130	12D35	forced	67
120	250	26	250	2.5	1.600	16.000	-P130	09D60	natural	53
120	250	34	250	2.3	1.600	16.000	-P130	09D41	natural	53
120	250	36	250	1.9	2.000	16.000	-P130	09F60	natural	53
120	250	45	250	1.5	2.400	16.000	-P130	09H60	natural	53
120	250	54	250	1.3	3.300	16.000	-P130	09L51	natural	53
120	250	57	250	1.4	2.400	16.000	-P130	09H41	natural	53
120	250	65	250	1.2	4.500	16.000	-P130	12D41	natural	53
120	250	68	250	1.1	3.300	16.000	-P130	09L41	natural	53
120	234	47	234	1.7	2.000	16.000	-P130	09F38	natural	53
120	200	33	200	2.2	1.500	20.000	-P130	09D60	natural	53
120	200	43	200	1.9	1.500	20.000	-P130	09D41	natural	53
120	200	45	200	1.6	1.900	20.000	-P130	09F60	natural	53
120	200	56	200	1.3	2.300	20.000	-P130	09H60	natural	53
120	200	68	200	1.1	3.200	20.000	-P130	09L51	natural	53
120	200	71	200	1.2	2.300	20.000	-P130	09H41	natural	53
120	200	81	200	1.0	4.400	20.000	-P130	12D41	natural	53
120	188	58	188	1.5	1.900	20.000	-P130	09F38	natural	53
120	163	62	163	1.4	4.700	12.000	-P130	12D20	natural	53
120	138	79	138	1.2	4.700	12.000	-P130	12D17	forced	67
120	125	25	125	3.2	0.600	32.000	-P130	06F60	natural	53
120	125	34	125	2.8	0.600	32.000	-P130	06F41	natural	53
120	125	35	125	2.4	0.700	32.000	-P130	06I60	natural	53
120	125	44	125	2.2	0.700	32.000	-P130	06I41	natural	53
120	125	54	125	1.6	1.500	32.000	-P130	09D60	natural	53
120	125	69	125	1.4	1.500	32.000	-P130	09D41	natural	53
120	125	72	125	1.2	1.900	32.000	-P130	09F60	natural	53
120	122	83	122	1.2	4.500	16.000	-P130	12D20	natural	53
120	117	93	117	1.1	1.900	32.000	-P130	09F38	natural	53

g700-P planetary geared motors

Technical data

Selection tables

2-stage gearboxes

Inverter operation						i	Product		Cooling	
$M_{2,max}$ [Nm]	$n_{2,th}$ [r/min]	M_2 [Nm]	$n_{2,eto}$ [r/min]	c	J [kgcm²]		g700	MCS		
120	98	103	98	1.0	4.400	20.000	-P130	12D20	natural	53
120	55	25	55	4.2	2.700	64.000	-P260	06C60	natural	58
120	55	32	55	3.5	2.700	64.000	-P260	06C41	natural	58
120	55	51	55	2.3	2.800	64.000	-P260	06F60	natural	58
120	55	68	55	1.8	2.900	64.000	-P260	06I60	natural	58
120	55	68	55	1.8	2.800	64.000	-P260	06F41	natural	58
120	55	85	55	1.4	2.900	64.000	-P260	06I41	natural	58
120	55	103	55	1.2	3.700	64.000	-P260	09D60	natural	58
127	175	31	175	5.9	2.600	20.000	-P260	09D41	natural	58
127	88	35	88	5.1	1.600	40.000	-P260	06F41	natural	58
130	444	24	444	2.9	2.300	9.000	-P130	09H60	natural	53
130	444	29	444	2.5	3.200	9.000	-P130	09L51	natural	53
130	444	31	444	2.6	2.300	9.000	-P130	09H41	natural	53
130	444	36	444	2.3	4.400	9.000	-P130	12D41	natural	53
130	444	38	444	2.2	3.200	9.000	-P130	09L41	natural	53
130	392	51	392	1.7	4.400	9.000	-P130	12D35	forced	67
130	392	63	392	1.4	7.700	9.000	-P130	12H35	natural	53
130	333	68	333	1.4	7.700	9.000	-P130	12H30	natural	53
130	217	46	217	2.3	4.400	9.000	-P130	12D20	natural	53
130	183	59	183	1.9	4.400	9.000	-P130	12D17	forced	67
130	167	85	167	1.4	7.700	9.000	-P130	12H15	natural	53
131	294	31	294	3.9	5.300	9.000	-P260	12D41	natural	58
131	217	40	217	3.9	5.300	9.000	-P260	12D20	natural	58
133	294	20	294	4.9	3.200	9.000	-P260	09H60	natural	58
135	109	33	109	5.7	1.600	32.000	-P260	06I41	natural	58
136	183	54	183	3.2	5.300	9.000	-P260	12D17	forced	69
139	294	26	294	4.4	3.200	9.000	-P260	09H41	natural	58
139	294	47	294	2.9	5.300	9.000	-P260	12D35	forced	69
154	225	37	225	5.3	6.600	12.000	-P260	12D41	natural	58
159	225	30	225	5.9	4.500	12.000	-P260	09H41	natural	58
162	213	33	213	5.2	4.100	15.000	-P260	09F38	natural	58
167	197	35	197	5.5	3.300	16.000	-P260	09F38	natural	58
167	140	32	140	5.4	2.600	25.000	-P260	09D60	natural	58
171	163	52	163	4.1	6.600	12.000	-P260	12D20	natural	58
173	225	59	225	3.8	6.600	12.000	-P260	12D35	forced	69
179	88	35	88	5.1	1.600	40.000	-P260	06I60	natural	58
181	138	72	138	3.2	6.600	12.000	-P260	12D17	forced	69
186	140	45	140	4.2	2.600	25.000	-P260	09D41	natural	58
197	88	48	88	4.1	1.600	40.000	-P260	06I41	natural	58
206	175	33	175	5.6	3.000	20.000	-P260	09F60	natural	58

6.1.1

g700-P planetary geared motors

Technical data

Selection tables

2-stage gearboxes

Inverter operation						i	Product		Cooling	
$M_{2, max}$ [Nm]	$n_{2, th}$ [r/min]	M_2 [Nm]	$n_{2, eto}$ [r/min]	c	J [kgcm²]		g700	MCS		
210	294	25	294	4.3	4.100	9.000	-P260	09L51	natural	58
210	294	33	294	3.7	4.100	9.000	-P260	09L41	natural	58
210	294	62	294	2.3	8.600	9.000	-P260	12H35	natural	58
210	294	62	294	2.3	9.300	9.000	-P260	14D36	natural	58
210	294	66	294	2.3	8.600	9.000	-P260	12H30	natural	58
210	294	89	294	1.7	8.600	9.000	-P260	12H34	forced	69
210	294	89	294	1.8	9.300	9.000	-P260	14D30	forced	69
210	294	93	294	1.5	12.000	9.000	-P260	12L41	natural	58
210	294	118	294	1.2	12.000	9.000	-P260	12L39	forced	69
210	294	118	294	1.3	15.000	9.000	-P260	14H32	natural	58
210	294	146	294	1.1	25.000	9.000	-P260	14L32	natural	58
210	217	114	217	1.6	12.000	9.000	-P260	12L20	natural	58
210	183	144	183	1.3	12.000	9.000	-P260	12L17	forced	69
210	167	75	167	2.5	9.300	9.000	-P260	14D15	natural	58
210	167	83	167	2.3	8.600	9.000	-P260	12H15	natural	58
210	167	135	167	1.5	15.000	9.000	-P260	14H15	natural	58
210	167	195	167	1.0	25.000	9.000	-P260	14L15	natural	58
210	150	101	150	2.0	8.600	9.000	-P260	12H14	forced	69
210	150	101	150	2.0	9.300	9.000	-P260	14D14	forced	69
212	213	32	213	5.3	4.500	15.000	-P260	09H60	natural	58
221	213	53	213	3.7	6.500	15.000	-P260	12D41	natural	58
221	197	33	197	5.6	3.700	16.000	-P260	09H60	natural	58
227	109	43	109	4.8	2.400	32.000	-P260	09D60	natural	58
230	213	42	213	4.4	5.400	15.000	-P260	09L51	natural	58
230	213	45	213	4.2	4.500	15.000	-P260	09H41	natural	58
230	213	56	213	3.5	5.400	15.000	-P260	09L41	natural	58
230	213	80	213	2.7	6.500	15.000	-P260	12D35	forced	69
230	213	105	213	2.1	9.800	15.000	-P260	12H35	natural	58
230	213	105	213	2.1	11.000	15.000	-P260	14D36	natural	58
230	213	148	213	1.5	9.800	15.000	-P260	12H34	forced	69
230	213	155	213	1.4	13.000	15.000	-P260	12L41	natural	58
230	213	197	213	1.1	13.000	15.000	-P260	12L39	forced	69
230	213	197	213	1.1	17.000	15.000	-P260	14H32	natural	58
230	200	113	200	2.0	9.800	15.000	-P260	12H30	natural	58
230	200	148	200	1.5	11.000	15.000	-P260	14D30	forced	69
230	140	48	140	4.0	3.000	25.000	-P260	09F60	natural	58
230	140	64	140	3.2	3.400	25.000	-P260	09H60	natural	58
230	140	67	140	3.1	3.000	25.000	-P260	09F38	natural	58
230	140	80	140	2.7	4.300	25.000	-P260	09L51	natural	58
230	140	86	140	2.5	3.400	25.000	-P260	09H41	natural	58

6.1.1

g700-P planetary geared motors

Technical data

Selection tables

2-stage gearboxes

Inverter operation						i	Product		Cooling	
$M_{2, max}$ [Nm]	$n_{2, th}$ [r/min]	M_2 [Nm]	$n_{2, eto}$ [r/min]	c	J [kgcm²]		g700	MCS		
230	140	99	140	2.3	5.500	25.000	-P260	12D41	natural	58
230	140	105	140	2.1	4.300	25.000	-P260	09L41	natural	58
230	140	141	140	1.6	5.500	25.000	-P260	12D35	forced	69
230	140	176	140	1.3	8.800	25.000	-P260	12H35	natural	58
230	140	176	140	1.3	9.500	25.000	-P260	14D36	natural	58
230	130	72	130	2.9	6.500	15.000	-P260	12D20	natural	58
230	130	190	130	1.2	13.000	15.000	-P260	12L20	natural	58
230	120	188	120	1.2	8.800	25.000	-P260	12H30	natural	58
230	110	97	110	2.3	6.500	15.000	-P260	12D17	forced	69
230	100	130	100	1.7	11.000	15.000	-P260	14D15	natural	58
230	100	141	100	1.6	9.800	15.000	-P260	12H15	natural	58
230	90	169	90	1.3	9.800	15.000	-P260	12H14	forced	69
230	90	169	90	1.3	11.000	15.000	-P260	14D14	forced	69
230	88	61	88	3.4	2.400	40.000	-P260	09D60	natural	58
230	88	82	88	2.7	2.400	40.000	-P260	09D41	natural	58
230	88	87	88	2.5	2.800	40.000	-P260	09F60	natural	58
230	88	112	88	2.0	3.200	40.000	-P260	09H60	natural	58
230	88	117	88	2.0	2.800	40.000	-P260	09F38	natural	58
230	88	135	88	1.7	4.100	40.000	-P260	09L51	natural	58
230	88	143	88	1.6	3.200	40.000	-P260	09H41	natural	58
230	88	162	88	1.4	5.300	40.000	-P260	12D41	natural	58
230	88	169	88	1.4	4.100	40.000	-P260	09L41	natural	58
230	88	226	88	1.0	5.300	40.000	-P260	12D35	forced	69
230	78	129	78	1.8	5.500	25.000	-P260	12D20	natural	58
230	66	165	66	1.4	5.500	25.000	-P260	12D17	forced	69
230	60	216	60	1.1	9.500	25.000	-P260	14D15	natural	58
230	49	207	49	1.1	5.300	40.000	-P260	12D20	natural	58
232	197	55	197	3.9	5.800	16.000	-P260	12D41	natural	58
232	175	48	175	4.4	3.000	20.000	-P260	09F38	natural	58
235	88	97	88	5.8	20.000	12.000	-P800	14D14	forced	72
235	88	97	88	5.8	20.000	12.000	-P800	12H14	forced	72
235	73	93	73	6.0	11.000	20.000	-P800	12D17	forced	72
240	88	87	88	5.6	20.000	12.000	-P800	14D30	forced	72
245	88	89	88	5.4	20.000	12.000	-P800	12H34	forced	72
246	197	47	197	4.5	3.700	16.000	-P260	09H41	natural	58
249	122	76	122	3.1	5.800	16.000	-P260	12D20	natural	58
249	109	60	109	3.7	2.400	32.000	-P260	09D41	natural	58
250	197	85	197	2.8	5.800	16.000	-P260	12D35	forced	69
255	225	29	225	5.9	5.400	12.000	-P260	09L51	natural	58
258	103	102	103	2.4	5.800	16.000	-P260	12D17	forced	69

6.1.1

g700-P planetary geared motors

Technical data

Selection tables

2-stage gearboxes

Inverter operation						i	Product		Cooling	
$M_{2, max}$ [Nm]	$n_{2, th}$ [r/min]	M_2 [Nm]	$n_{2, eto}$ [r/min]	c	J [kgcm²]		g700	MCS		
260	225	39	225	5.0	5.400	12.000	-P260	09L41	natural	58
260	225	78	225	3.0	9.900	12.000	-P260	12H35	natural	58
260	225	78	225	3.0	11.000	12.000	-P260	14D36	natural	58
260	225	85	225	2.8	9.900	12.000	-P260	12H30	natural	58
260	225	117	225	2.1	9.900	12.000	-P260	12H34	forced	69
260	225	117	225	2.1	11.000	12.000	-P260	14D30	forced	69
260	225	124	225	2.0	13.000	12.000	-P260	12L41	natural	58
260	225	158	225	1.6	13.000	12.000	-P260	12L39	forced	69
260	225	158	225	1.6	17.000	12.000	-P260	14H32	natural	58
260	225	194	225	1.3	26.000	12.000	-P260	14L32	natural	58
260	225	237	225	1.1	70.000	12.000	-P260	19F30	natural	58
260	197	43	197	4.7	4.600	16.000	-P260	09L51	natural	58
260	197	59	197	3.8	4.600	16.000	-P260	09L41	natural	58
260	197	111	197	2.3	9.100	16.000	-P260	12H35	natural	58
260	197	111	197	2.3	9.800	16.000	-P260	14D36	natural	58
260	197	158	197	1.6	9.100	16.000	-P260	12H34	forced	69
260	197	165	197	1.5	12.000	16.000	-P260	12L41	natural	58
260	197	211	197	1.2	12.000	16.000	-P260	12L39	forced	69
260	197	211	197	1.2	16.000	16.000	-P260	14H32	natural	58
260	188	119	188	2.1	9.100	16.000	-P260	12H30	natural	58
260	188	158	188	1.6	9.800	16.000	-P260	14D30	forced	69
260	175	46	175	4.5	3.400	20.000	-P260	09H60	natural	58
260	175	59	175	3.8	4.300	20.000	-P260	09L51	natural	58
260	175	63	175	3.6	3.400	20.000	-P260	09H41	natural	58
260	175	74	175	3.1	5.500	20.000	-P260	12D41	natural	58
260	175	78	175	3.0	4.300	20.000	-P260	09L41	natural	58
260	175	111	175	2.3	5.500	20.000	-P260	12D35	forced	69
260	175	141	175	1.8	8.800	20.000	-P260	12H35	natural	58
260	175	141	175	1.8	9.500	20.000	-P260	14D36	natural	58
260	175	207	175	1.2	12.000	20.000	-P260	12L41	natural	58
260	169	197	169	1.3	8.800	20.000	-P260	12H34	forced	69
260	163	152	163	1.7	13.000	12.000	-P260	12L20	natural	58
260	150	150	150	1.7	8.800	20.000	-P260	12H30	natural	58
260	150	197	150	1.3	9.500	20.000	-P260	14D30	forced	69
260	138	192	138	1.3	13.000	12.000	-P260	12L17	forced	69
260	125	100	125	2.5	11.000	12.000	-P260	14D15	natural	58
260	125	111	125	2.3	9.900	12.000	-P260	12H15	natural	58
260	125	180	125	1.4	17.000	12.000	-P260	14H15	natural	58
260	122	203	122	1.3	12.000	16.000	-P260	12L20	natural	58
260	113	135	113	1.9	9.900	12.000	-P260	12H14	forced	69

6.1.1

g700-P planetary geared motors

Technical data

Selection tables

2-stage gearboxes

Inverter operation						i	Product		Cooling	
$M_{2, max}$ [Nm]	$n_{2, th}$ [r/min]	M_2 [Nm]	$n_{2, eto}$ [r/min]	c	J [kgcm²]		g700	MCS		
260	113	135	113	1.9	11.000	12.000	-P260	14D14	forced	69
260	109	64	109	3.6	2.800	32.000	-P260	09F60	natural	58
260	109	85	109	2.9	3.200	32.000	-P260	09H60	natural	58
260	109	88	109	2.8	2.800	32.000	-P260	09F38	natural	58
260	109	105	109	2.4	4.100	32.000	-P260	09L51	natural	58
260	109	112	109	2.3	3.200	32.000	-P260	09H41	natural	58
260	109	129	109	2.0	5.300	32.000	-P260	12D41	natural	58
260	109	135	109	1.9	4.100	32.000	-P260	09L41	natural	58
260	109	180	109	1.4	5.300	32.000	-P260	12D35	forced	69
260	109	226	109	1.1	8.600	32.000	-P260	12H35	natural	58
260	109	226	109	1.1	9.300	32.000	-P260	14D36	natural	58
260	98	100	98	2.5	5.500	20.000	-P260	12D20	natural	58
260	98	254	98	1.0	12.000	20.000	-P260	12L20	natural	58
260	94	138	94	1.8	9.800	16.000	-P260	14D15	natural	58
260	94	150	94	1.7	9.100	16.000	-P260	12H15	natural	58
260	94	241	94	1.1	8.600	32.000	-P260	12H30	natural	58
260	94	241	94	1.1	16.000	16.000	-P260	14H15	natural	58
260	84	180	84	1.4	9.100	16.000	-P260	12H14	forced	69
260	84	180	84	1.4	9.800	16.000	-P260	14D14	forced	69
260	83	132	83	1.9	5.500	20.000	-P260	12D17	forced	69
260	75	173	75	1.5	9.500	20.000	-P260	14D15	natural	58
260	75	188	75	1.4	8.800	20.000	-P260	12H15	natural	58
260	68	226	68	1.1	8.800	20.000	-P260	12H14	forced	69
260	68	226	68	1.1	9.500	20.000	-P260	14D14	forced	69
260	61	165	61	1.6	5.300	32.000	-P260	12D20	natural	58
260	52	211	52	1.2	5.300	32.000	-P260	12D17	forced	69
309	87	98	87	5.3	20.000	15.000	-P800	14D15	natural	64
317	75	101	75	5.7	16.000	16.000	-P800	14D15	natural	64
317	70	97	70	5.4	9.900	25.000	-P800	12D20	natural	64
322	87	111	87	4.9	20.000	15.000	-P800	12H15	natural	64
326	70	110	70	4.9	9.900	25.000	-P800	12D35	forced	72
329	87	119	87	4.6	20.000	15.000	-P800	14D30	forced	72
332	87	120	87	4.5	20.000	15.000	-P800	12H34	forced	72
332	75	114	75	5.2	15.000	16.000	-P800	12H15	natural	64
346	87	143	87	4.0	20.000	15.000	-P800	14D14	forced	72
346	87	143	87	4.0	20.000	15.000	-P800	12H14	forced	72
347	66	137	66	4.2	9.900	25.000	-P800	12D17	forced	72
352	75	127	75	4.6	16.000	16.000	-P800	14D30	forced	72
357	75	129	75	4.4	15.000	16.000	-P800	12H34	forced	72
360	75	149	75	4.3	16.000	16.000	-P800	14D14	forced	72

6.1.1

g700-P planetary geared motors

Technical data

Selection tables

2-stage gearboxes

| Inverter operation | | | | | | i | Product | | Cooling | |
$M_{2,max}$ [Nm]	$n_{2,th}$ [r/min]	M_2 [Nm]	$n_{2,eto}$ [r/min]	c	J [kgcm²]		g700	MCS		
360	75	149	75	4.3	15.000	16.000	-P800	12H14	forced	72
413	73	107	73	5.3	14.000	20.000	-P800	12H35	natural	64
414	73	107	73	5.2	15.000	20.000	-P800	14D36	natural	64
415	73	114	73	5.2	14.000	20.000	-P800	12H30	natural	64
429	61	131	61	4.8	10.000	32.000	-P800	12D20	natural	64
438	61	148	61	4.4	10.000	32.000	-P800	12D35	forced	72
443	73	140	73	4.5	15.000	20.000	-P800	14D15	natural	64
450	47	248	47	1.8	8.600	64.000	-P800	12D41	natural	64
450	47	346	47	1.3	8.600	64.000	-P800	12D35	forced	72
450	47	432	47	1.0	12.000	64.000	-P800	12H35	natural	64
450	47	432	47	1.0	13.000	64.000	-P800	14D36	natural	64
450	31	317	31	1.4	8.600	64.000	-P800	12D20	natural	64
450	26	403	26	1.1	8.600	64.000	-P800	12D17	forced	72
457	73	158	73	4.2	14.000	20.000	-P800	12H15	natural	64
463	52	183	52	3.8	10.000	32.000	-P800	12D17	forced	72
465	73	168	73	4.0	15.000	20.000	-P800	14D30	forced	72
471	73	171	73	3.8	14.000	20.000	-P800	12H34	forced	72
485	68	201	68	3.5	15.000	20.000	-P800	14D14	forced	72
485	68	201	68	3.5	14.000	20.000	-P800	12H14	forced	72
490	88	118	88	5.0	23.000	12.000	-P800	12L20	natural	64
499	88	98	88	4.8	23.000	12.000	-P800	12L41	natural	64
512	88	149	88	4.3	27.000	12.000	-P800	14H15	natural	64
524	88	133	88	4.1	27.000	12.000	-P800	14H32	natural	64
537	88	162	88	4.1	23.000	12.000	-P800	12L17	forced	72
549	88	136	88	3.8	23.000	12.000	-P800	12L39	forced	72
559	58	134	58	4.3	9.400	40.000	-P800	12D41	natural	64
574	88	246	88	3.0	27.000	12.000	-P800	14H12	forced	72
575	88	215	88	2.9	27.000	12.000	-P800	14H28	forced	72
584	70	151	70	3.9	13.000	25.000	-P800	12H35	natural	64
584	70	151	70	3.9	14.000	25.000	-P800	14D36	natural	64
596	70	164	70	3.7	13.000	25.000	-P800	12H30	natural	64
607	49	185	49	3.4	9.400	40.000	-P800	12D20	natural	64
611	58	207	58	3.1	9.400	40.000	-P800	12D35	forced	72
620	60	197	60	3.2	14.000	25.000	-P800	14D15	natural	64
633	60	218	60	3.0	13.000	25.000	-P800	12H15	natural	64
633	41	250	41	2.7	9.400	40.000	-P800	12D17	forced	72
641	70	232	70	2.8	14.000	25.000	-P800	14D30	forced	72
641	70	232	70	2.8	13.000	25.000	-P800	12H34	forced	72
658	54	272	54	2.5	14.000	25.000	-P800	14D14	forced	72
658	54	272	54	2.5	13.000	25.000	-P800	12H14	forced	72

6.1.1

g700-P planetary geared motors

Technical data

Selection tables

2-stage gearboxes

Inverter operation						i	Product		Cooling	⌀
$M_{2,max}$ [Nm]	$n_{2,th}$ [r/min]	M_2 [Nm]	$n_{2,eto}$ [r/min]	c	J [kgcm²]		g700	MCS		
667	87	131	87	4.1	23.000	15.000	-P800	12L41	natural	64
691	87	176	87	3.5	27.000	15.000	-P800	14H32	natural	64
695	87	168	87	3.6	23.000	15.000	-P800	12L20	natural	64
700	87	179	87	3.2	23.000	15.000	-P800	12L39	forced	72
700	87	208	87	3.0	27.000	15.000	-P800	14H15	natural	64
700	87	224	87	2.9	23.000	15.000	-P800	12L17	forced	72
700	87	228	87	2.8	36.000	15.000	-P800	14L32	natural	64
700	87	281	87	2.4	27.000	15.000	-P800	14H28	forced	72
700	87	289	87	2.3	47.000	15.000	-P800	14P32	natural	64
700	87	289	87	2.3	77.000	15.000	-P800	19F30	natural	64
700	87	322	87	2.1	36.000	15.000	-P800	14L15	natural	64
700	87	360	87	1.9	36.000	15.000	-P800	14L30	forced	72
700	87	381	87	1.8	77.000	15.000	-P800	19F14	natural	64
700	87	409	87	1.7	117.000	15.000	-P800	19J30	natural	64
700	87	423	87	1.6	47.000	15.000	-P800	14P14	natural	64
700	87	430	87	1.6	36.000	15.000	-P800	14L14	forced	72
700	87	451	87	1.5	172.000	15.000	-P800	19P30	natural	64
700	87	458	87	1.5	77.000	15.000	-P800	19F29	forced	72
700	87	465	87	1.5	47.000	15.000	-P800	14P26	forced	72
700	87	564	87	1.2	117.000	15.000	-P800	19J14	natural	64
700	80	330	80	2.1	27.000	15.000	-P800	14H12	forced	72
700	80	536	80	1.3	77.000	15.000	-P800	19F12	forced	72
700	70	245	70	2.7	16.000	25.000	-P800	12L41	natural	64
700	70	313	70	2.2	16.000	25.000	-P800	12L20	natural	64
700	70	326	70	2.1	16.000	25.000	-P800	12L39	forced	72
700	70	326	70	2.1	20.000	25.000	-P800	14H32	natural	64
700	70	404	70	1.7	29.000	25.000	-P800	14L32	natural	64
700	70	482	70	1.4	20.000	25.000	-P800	14H28	forced	72
700	70	494	70	1.4	41.000	25.000	-P800	14P32	natural	64
700	70	494	70	1.4	71.000	25.000	-P800	19F30	natural	64
700	70	592	70	1.2	47.000	15.000	-P800	14P11	forced	72
700	70	599	70	1.2	29.000	25.000	-P800	14L30	forced	72
700	70	682	70	1.0	111.000	25.000	-P800	19J30	natural	64
700	66	400	66	1.7	16.000	25.000	-P800	12L17	forced	72
700	60	376	60	1.8	20.000	25.000	-P800	14H15	natural	64
700	60	541	60	1.3	29.000	25.000	-P800	14L15	natural	64
700	58	272	58	2.5	13.000	40.000	-P800	12H35	natural	64
700	58	272	58	2.5	13.000	40.000	-P800	14D36	natural	64
700	58	293	58	2.3	13.000	40.000	-P800	12H30	natural	64
700	58	395	58	1.8	13.000	40.000	-P800	14D30	forced	72

6.1.1

g700-P planetary geared motors

Technical data

Selection tables

2-stage gearboxes

Inverter operation						i	Product		Cooling	
$M_{2, max}$ [Nm]	$n_{2, th}$ [r/min]	M_2 [Nm]	$n_{2, eto}$ [r/min]	c	J [kgcm²]		g700	MCS		
700	58	395	58	1.8	13.000	40.000	-P800	12H34	forced	72
700	58	414	58	1.7	16.000	40.000	-P800	12L41	natural	64
700	58	526	58	1.3	16.000	40.000	-P800	12L39	forced	72
700	58	526	58	1.3	19.000	40.000	-P800	14H32	natural	64
700	58	647	58	1.1	29.000	40.000	-P800	14L32	natural	64
700	57	635	57	1.1	71.000	25.000	-P800	19F14	natural	64
700	49	508	49	1.4	16.000	40.000	-P800	12L20	natural	64
700	48	552	48	1.3	20.000	25.000	-P800	14H12	forced	72
700	41	639	41	1.1	16.000	40.000	-P800	12L17	forced	72
700	38	345	38	2.0	13.000	40.000	-P800	14D15	natural	64
700	38	376	38	1.9	13.000	40.000	-P800	12H15	natural	64
700	38	602	38	1.2	19.000	40.000	-P800	14H15	natural	64
700	34	451	34	1.6	13.000	40.000	-P800	14D14	forced	72
700	34	451	34	1.6	13.000	40.000	-P800	12H14	forced	72
718	75	141	75	4.0	18.000	16.000	-P800	12L41	natural	64
726	75	175	75	3.9	18.000	16.000	-P800	12L20	natural	64
743	75	189	75	3.4	22.000	16.000	-P800	14H32	natural	64
750	75	218	75	3.3	22.000	16.000	-P800	14H15	natural	64
774	61	200	61	3.5	14.000	32.000	-P800	12H35	natural	64
774	61	200	61	3.5	14.000	32.000	-P800	14D36	natural	64
775	75	192	75	3.2	18.000	16.000	-P800	12L39	forced	72
781	75	235	75	3.1	18.000	16.000	-P800	12L17	forced	72
783	88	175	88	3.3	36.000	12.000	-P800	14L32	natural	64
789	61	218	61	3.3	14.000	32.000	-P800	12H30	natural	64
798	75	299	75	2.4	22.000	16.000	-P800	14H28	forced	72
800	88	223	88	2.8	77.000	12.000	-P800	19F30	natural	64
800	88	224	88	2.7	47.000	12.000	-P800	14P32	natural	64
800	88	240	88	3.0	36.000	12.000	-P800	14L15	natural	64
800	88	281	88	2.3	36.000	12.000	-P800	14L30	forced	72
800	88	292	88	2.6	77.000	12.000	-P800	19F14	natural	64
800	88	327	88	2.0	117.000	12.000	-P800	19J30	natural	64
800	88	330	88	2.3	47.000	12.000	-P800	14P14	natural	64
800	88	337	88	2.3	36.000	12.000	-P800	14L14	forced	72
800	88	361	88	1.8	172.000	12.000	-P800	19P30	natural	64
800	88	367	88	1.8	77.000	12.000	-P800	19F29	forced	72
800	88	372	88	1.9	47.000	12.000	-P800	14P26	forced	72
800	88	429	88	1.8	77.000	12.000	-P800	19F12	forced	72
800	88	451	88	1.7	117.000	12.000	-P800	19J14	natural	64
800	88	474	88	1.6	47.000	12.000	-P800	14P11	forced	72
800	88	570	88	1.2	117.000	12.000	-P800	19J29	forced	72

6.1.1

g700-P planetary geared motors

Technical data

Selection tables

2-stage gearboxes

Inverter operation						i	Product		Cooling	⌀
$M_{2,max}$ [Nm]	$n_{2,th}$ [r/min]	M_2 [Nm]	$n_{2,eto}$ [r/min]	c	J [kgcm²]		g700	MCS		
800	88	575	88	1.4	172.000	12.000	-P800	19P14	natural	64
800	88	598	88	1.1	172.000	12.000	-P800	19P29	forced	72
800	88	705	88	1.1	117.000	12.000	-P800	19J12	forced	72
800	75	244	75	2.7	31.000	16.000	-P800	14L32	natural	64
800	75	309	75	2.3	72.000	16.000	-P800	19F30	natural	64
800	75	310	75	2.3	42.000	16.000	-P800	14P32	natural	64
800	75	339	75	2.3	31.000	16.000	-P800	14L15	natural	64
800	75	348	75	2.2	22.000	16.000	-P800	14H12	forced	72
800	75	384	75	1.9	31.000	16.000	-P800	14L30	forced	72
800	75	406	75	1.9	72.000	16.000	-P800	19F14	natural	64
800	75	436	75	1.7	112.000	16.000	-P800	19J30	natural	64
800	75	451	75	1.7	42.000	16.000	-P800	14P14	natural	64
800	75	459	75	1.7	31.000	16.000	-P800	14L14	forced	72
800	75	481	75	1.5	167.000	16.000	-P800	19P30	natural	64
800	75	489	75	1.5	72.000	16.000	-P800	19F29	forced	72
800	75	496	75	1.5	42.000	16.000	-P800	14P26	forced	72
800	75	572	75	1.4	72.000	16.000	-P800	19F12	forced	72
800	75	602	75	1.3	112.000	16.000	-P800	19J14	natural	64
800	75	767	75	1.0	167.000	16.000	-P800	19P14	natural	64
800	73	185	73	3.4	17.000	20.000	-P800	12L41	natural	64
800	73	233	73	3.1	17.000	20.000	-P800	12L20	natural	64
800	73	245	73	2.9	21.000	20.000	-P800	14H32	natural	64
800	73	249	73	2.7	17.000	20.000	-P800	12L39	forced	72
800	73	287	73	2.6	21.000	20.000	-P800	14H15	natural	64
800	73	309	73	2.5	17.000	20.000	-P800	12L17	forced	72
800	73	315	73	2.4	30.000	20.000	-P800	14L32	natural	64
800	73	384	73	2.0	21.000	20.000	-P800	14H28	forced	72
800	73	395	73	1.9	41.000	20.000	-P800	14P32	natural	64
800	73	395	73	2.0	72.000	20.000	-P800	19F30	natural	64
800	73	432	73	1.8	30.000	20.000	-P800	14L15	natural	64
800	73	479	73	1.6	30.000	20.000	-P800	14L30	forced	72
800	73	545	73	1.4	112.000	20.000	-P800	19J30	natural	64
800	73	602	73	1.3	167.000	20.000	-P800	19P30	natural	64
800	73	611	73	1.3	72.000	20.000	-P800	19F29	forced	72
800	73	620	73	1.3	41.000	20.000	-P800	14P26	forced	72
800	71	508	71	1.5	72.000	20.000	-P800	19F14	natural	64
800	71	752	71	1.0	112.000	20.000	-P800	19J14	natural	64
800	68	564	68	1.4	41.000	20.000	-P800	14P14	natural	64
800	68	573	68	1.4	30.000	20.000	-P800	14L14	forced	72
800	66	632	66	1.2	42.000	16.000	-P800	14P11	forced	72

6.1.1

g700-P planetary geared motors

Technical data

Selection tables

2-stage gearboxes

Inverter operation						i	Product		Cooling	⌀
$M_{2,\,max}$ [Nm]	$n_{2,\,th}$ [r/min]	M_2 [Nm]	$n_{2,\,eto}$ [r/min]	c	J [kgcm²]		g700	MCS		
800	61	304	61	2.5	14.000	32.000	-P800	14D30	forced	72
800	61	304	61	2.5	14.000	32.000	-P800	12H34	forced	72
800	61	321	61	2.4	17.000	32.000	-P800	12L41	natural	64
800	61	406	61	1.9	17.000	32.000	-P800	12L20	natural	64
800	61	421	61	1.9	17.000	32.000	-P800	12L39	forced	72
800	61	421	61	1.9	21.000	32.000	-P800	14H32	natural	64
800	61	517	61	1.5	30.000	32.000	-P800	14L32	natural	64
800	61	617	61	1.3	21.000	32.000	-P800	14H28	forced	72
800	61	632	61	1.3	41.000	32.000	-P800	14P32	natural	64
800	61	632	61	1.3	71.000	32.000	-P800	19F30	natural	64
800	61	767	61	1.0	30.000	32.000	-P800	14L30	forced	72
800	60	442	60	1.8	21.000	20.000	-P800	14H12	forced	72
800	60	714	60	1.1	72.000	20.000	-P800	19F12	forced	72
800	52	511	52	1.6	17.000	32.000	-P800	12L17	forced	72
800	47	259	47	2.9	14.000	32.000	-P800	14D15	natural	64
800	47	287	47	2.6	14.000	32.000	-P800	12H15	natural	64
800	47	481	47	1.6	21.000	32.000	-P800	14H15	natural	64
800	47	692	47	1.1	30.000	32.000	-P800	14L15	natural	64
800	42	356	42	2.2	14.000	32.000	-P800	14D14	forced	72
800	42	356	42	2.2	14.000	32.000	-P800	12H14	forced	72
800	38	707	38	1.1	21.000	32.000	-P800	14H12	forced	72

g700-P planetary geared motors

Technical data

Selection tables

3-stage gearboxes

Inverter operation						i	Product		Cooling	
$M_{2, max}$ [Nm]	$n_{2, th}$ [r/min]	M_2 [Nm]	$n_{2, eto}$ [r/min]	c	J [kgcm²]		g700	MCS		
44	75	27	75	1.6	0.200	60.000	-P44	06C60	natural	50
44	68	32	68	1.3	0.200	60.000	-P44	06C41	natural	50
44	56	36	56	1.2	0.200	80.000	-P44	06C60	natural	50
44	51	43	51	1.0	0.200	80.000	-P44	06C41	natural	50
101	67	21	67	4.0	0.500	60.000	-P130	06C60	natural	55
110	67	28	67	3.3	0.500	60.000	-P130	06C41	natural	55
110	67	47	67	2.2	0.600	60.000	-P130	06F60	natural	55
110	67	65	67	1.7	0.600	60.000	-P130	06F41	natural	55
110	67	65	67	1.7	0.700	60.000	-P130	06I60	natural	55
110	67	81	67	1.3	0.700	60.000	-P130	06I41	natural	55
110	67	97	67	1.1	1.500	60.000	-P130	09D60	natural	55
110	33	53	33	2.1	0.800	120.000	-P130	06C60	natural	55
110	33	64	33	1.7	0.800	120.000	-P130	06C41	natural	55
110	33	96	33	1.1	0.900	120.000	-P130	06F60	natural	55
110	20	85	20	1.3	0.500	200.000	-P130	06C60	natural	55
110	20	102	20	1.1	0.500	200.000	-P130	06C41	natural	55
120	50	31	50	3.3	0.600	80.000	-P130	06C60	natural	55
120	50	40	50	2.8	0.600	80.000	-P130	06C41	natural	55
120	50	65	50	1.8	0.700	80.000	-P130	06F60	natural	55
120	50	86	50	1.4	0.700	80.000	-P130	06F41	natural	55
120	50	86	50	1.4	0.800	80.000	-P130	06I60	natural	55
120	50	108	50	1.1	0.800	80.000	-P130	06I41	natural	55
120	40	42	40	2.7	0.600	100.000	-P130	06C60	natural	55
120	40	53	40	2.2	0.600	100.000	-P130	06C41	natural	55
120	40	81	40	1.5	0.700	100.000	-P130	06F60	natural	55
120	40	108	40	1.1	0.700	100.000	-P130	06F41	natural	55
120	40	108	40	1.1	0.700	100.000	-P130	06I60	natural	55
120	25	70	25	1.7	0.500	160.000	-P130	06C60	natural	55
120	25	84	25	1.4	0.500	160.000	-P130	06C41	natural	55
120	16	108	16	1.1	0.500	256.000	-P130	06C60	natural	55
152	58	31	58	5.2	1.600	60.000	-P260	06F60	natural	60
187	58	51	58	3.9	1.600	60.000	-P260	06F41	natural	60
230	29	92	29	2.5	2.800	120.000	-P260	06F60	natural	60
230	29	125	29	1.8	2.800	120.000	-P260	06F41	natural	60
230	29	125	29	1.8	2.800	120.000	-P260	06I60	natural	60
230	29	157	29	1.5	2.800	120.000	-P260	06I41	natural	60
230	29	188	29	1.2	3.600	120.000	-P260	09D60	natural	60
230	18	101	18	2.3	1.500	200.000	-P260	06C41	natural	60
230	18	151	18	1.5	1.600	200.000	-P260	06F60	natural	60
230	18	202	18	1.1	1.600	200.000	-P260	06F41	natural	60

6.1.1

g700-P planetary geared motors

Technical data

Selection tables

3-stage gearboxes

Inverter operation						i	Product		Cooling	
$M_{2,max}$ [Nm]	$n_{2,th}$ [r/min]	M_2 [Nm]	$n_{2,eto}$ [r/min]	c	J [kgcm²]		g700	MCS		
230	18	202	18	1.1	1.600	200.000	-P260	06I60	natural	60
230	11	126	11	1.8	1.500	320.000	-P260	06C60	natural	60
230	11	152	11	1.5	1.500	320.000	-P260	06C41	natural	60
230	11	228	11	1.0	1.600	320.000	-P260	06F60	natural	60
248	44	51	44	4.0	1.800	80.000	-P260	06F60	natural	60
260	58	51	58	3.9	1.600	60.000	-P260	06I60	natural	60
260	58	71	58	3.1	1.600	60.000	-P260	06I41	natural	60
260	58	91	58	2.6	2.400	60.000	-P260	09D60	natural	60
260	58	124	58	2.0	2.400	60.000	-P260	09D41	natural	60
260	58	130	58	2.0	2.800	60.000	-P260	09F60	natural	60
260	58	162	58	1.6	3.200	60.000	-P260	09H60	natural	60
260	58	167	58	1.5	2.800	60.000	-P260	09F38	natural	60
260	58	194	58	1.3	4.100	60.000	-P260	09L51	natural	60
260	58	205	58	1.2	3.200	60.000	-P260	09H41	natural	60
260	58	232	58	1.1	5.300	60.000	-P260	12D41	natural	60
260	58	243	58	1.1	4.100	60.000	-P260	09L41	natural	60
260	44	77	44	3.0	1.800	80.000	-P260	06F41	natural	60
260	44	77	44	3.0	1.800	80.000	-P260	06I60	natural	60
260	44	103	44	2.4	1.800	80.000	-P260	06I41	natural	60
260	44	130	44	2.0	2.600	80.000	-P260	09D60	natural	60
260	44	166	44	1.6	2.600	80.000	-P260	09D41	natural	60
260	44	173	44	1.5	3.000	80.000	-P260	09F60	natural	60
260	44	216	44	1.2	3.400	80.000	-P260	09H60	natural	60
260	44	223	44	1.1	3.000	80.000	-P260	09F38	natural	60
260	35	70	35	3.2	1.700	100.000	-P260	06F60	natural	60
260	35	103	35	2.4	1.700	100.000	-P260	06F41	natural	60
260	35	103	35	2.4	1.800	100.000	-P260	06I60	natural	60
260	35	135	35	1.9	1.800	100.000	-P260	06I41	natural	60
260	35	162	35	1.6	2.600	100.000	-P260	09D60	natural	60
260	35	207	35	1.3	2.600	100.000	-P260	09D41	natural	60
260	35	216	35	1.2	3.000	100.000	-P260	09F60	natural	60
260	22	76	22	3.1	1.500	160.000	-P260	06C41	natural	60
260	22	125	22	2.1	1.600	160.000	-P260	06F60	natural	60
260	22	167	22	1.6	1.600	160.000	-P260	06F41	natural	60
260	22	167	22	1.6	1.600	160.000	-P260	06I60	natural	60
260	22	209	22	1.3	1.600	160.000	-P260	06I41	natural	60
260	22	251	22	1.0	2.400	160.000	-P260	09D60	natural	60
260	14	106	14	2.5	1.500	256.000	-P260	06C60	natural	60
260	14	127	14	2.0	1.500	256.000	-P260	06C41	natural	60
260	14	191	14	1.4	1.600	256.000	-P260	06F60	natural	60

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Selection tables

3-stage gearboxes

Inverter operation						i	Product		Cooling	
$M_{2, max}$ [Nm]	$n_{2, th}$ [r/min]	M_2 [Nm]	$n_{2, eto}$ [r/min]	c	J [kgcm²]		g700	MCS		
260	14	255	14	1.0	1.600	256.000	-P260	06F41	natural	60
260	14	255	14	1.0	1.600	256.000	-P260	06I60	natural	60

6.1.1

g700-P planetary geared motors

Technical data

Dimensions, notes

Notes on the dimensions

The following legend shows the layout of the dimension sheets.

Product gearbox

Driven shaft design

g700-P44

Abmessungen mit Vollwelle

Product Motor

Produkt			MCS				
			06C41	06F41	06I41	09D41	09F38
Abmessungen							
Gesamtlänge	L	[mm]	238	268	298	296	316
Länge Motor	LB	[mm]	132	162	192	183	203
Länge Motoranbauten	Δ L	[mm]	100			71	
Motordurchmesser	AC	[mm]	86			89	
Abstand Motor/Anschluss	AD	[mm]	77			89.7	

Distance of motor centre to the end of connector

Total length of the drive without built-on accessories

Motor diameter

Motor length without built-on accessories

Additional length of the built-on accessories (longest version)

6.1.1

Dimensions, self-ventilated motors

g700-P20, 1-stage gearboxes

Dimensions with solid shaft and Flange

8800241-02
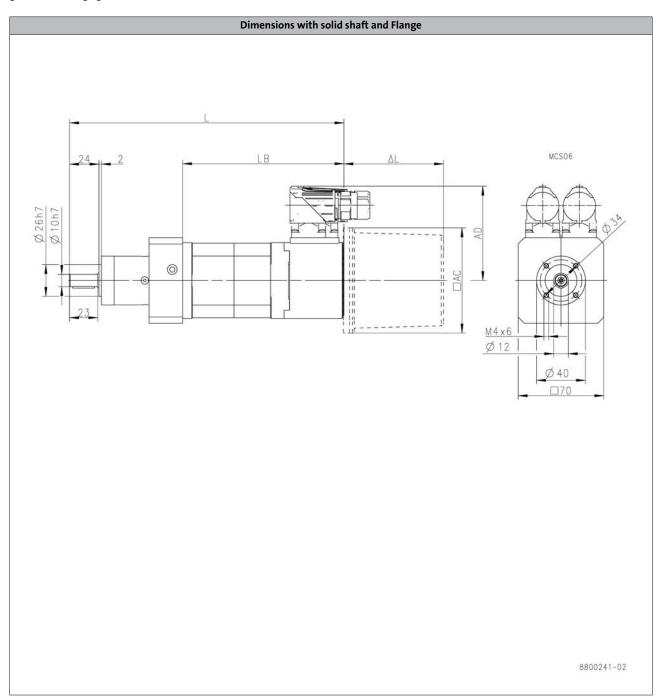
Product			MCS	
			06C41	06C60
Length				
Total length	L	[mm]	225	
Motor length	LB	[mm]	132	
Length of motor options	ΔL	[mm]	100	
Motor diameter	AC	[mm]	86	
Distance motor/connection	AD	[mm]	77	

g700-P planetary geared motors

Technical data

Dimensions, self-ventilated motors

g700-P20, 2-stage gearboxes

Dimensions with solid shaft and Flange

8800241-02
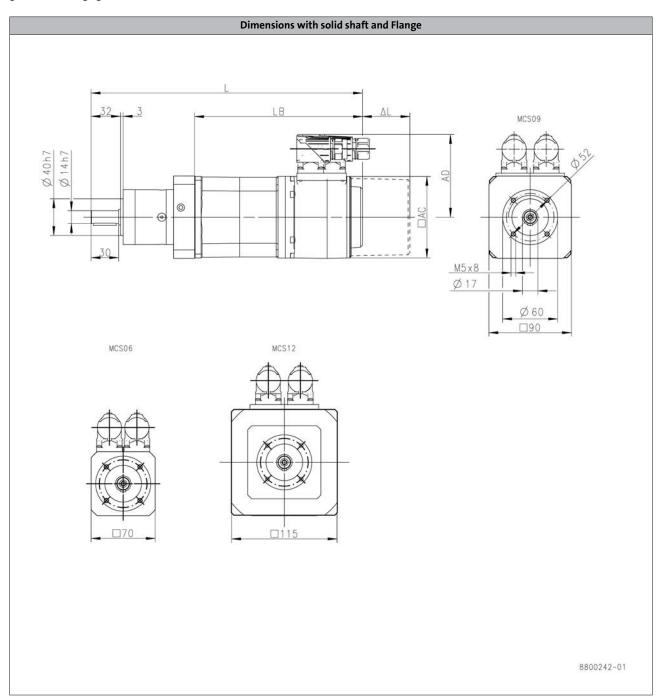
Product			MCS	
			06C41	06C60
Length				
Total length	L	[mm]	238	
Motor length	LB	[mm]	132	
Length of motor options	Δ L	[mm]	100	
Motor diameter	AC	[mm]	86	
Distance motor/connection	AD	[mm]	77	

Dimensions, self-ventilated motors

g700-P44, 1-stage gearboxes
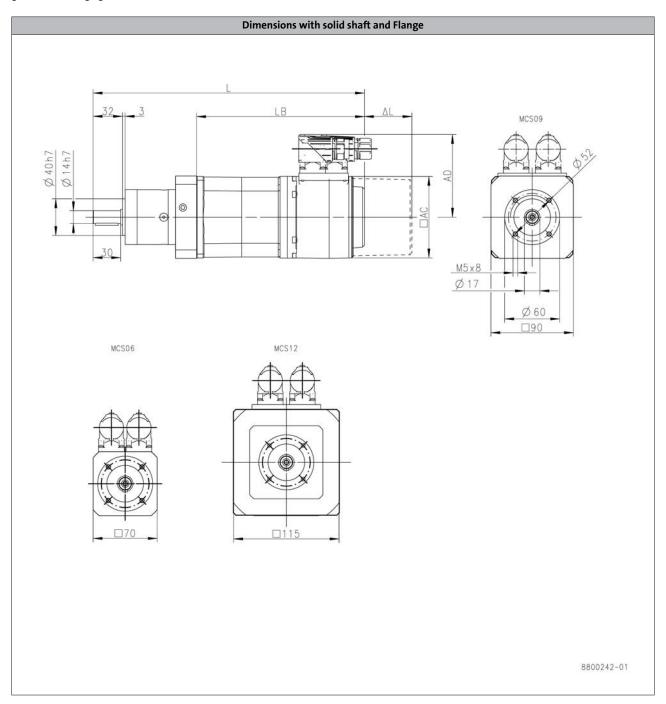
Dimensions with solid shaft and Flange

Product			MCS										
			06C41	06C60	06F41	06F60	06I41	06I60	09D41	09D60	09F38	09F60
Length												
Total length	L	[mm]	238		268		298		296		316	
Motor length	LB	[mm]	132		162		192		183		203	
Length of motor options	△ L	[mm]	100						71			
Motor diameter	AC	[mm]	86						89			
Distance motor/connection	AD	[mm]	77						89.7			

g700-P planetary geared motors

Technical data

Dimensions, self-ventilated motors

g700-P44, 2-stage gearboxes

Dimensions with solid shaft and Flange

8800242-01

Product			MCS									
			06C41	06C60	06F41	06F60	06I41	06I60	09D41	09D60	09F38	09F60
Length												
Total length	L	[mm]	251		281		311		309		329	
Motor length	LB	[mm]	132		162		192		183		203	
Length of motor options	Δ L	[mm]	100						71			
Motor diameter	AC	[mm]	86						89			
Distance motor/connection	AD	[mm]	77						89.7			

g700-P planetary geared motors

Technical data

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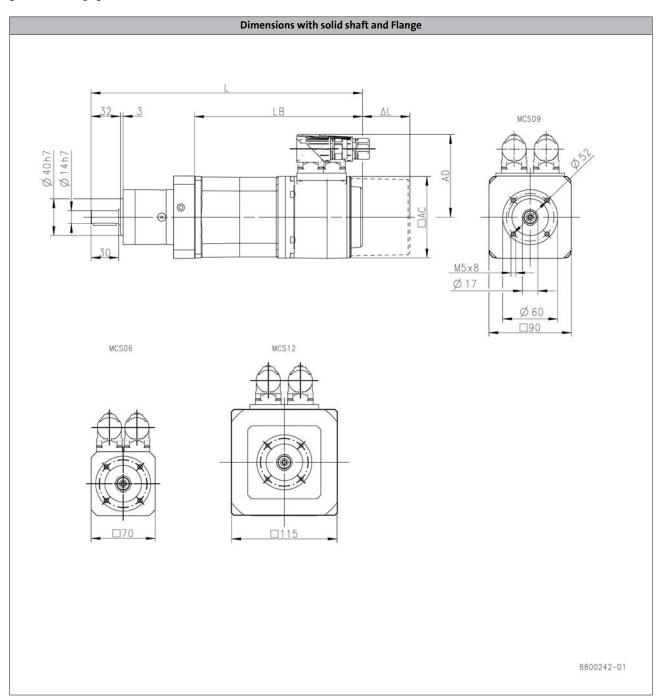
Dimensions, self-ventilated motors

g700-P44, 3-stage gearboxes

Dimensions with solid shaft and Flange

8800242-01
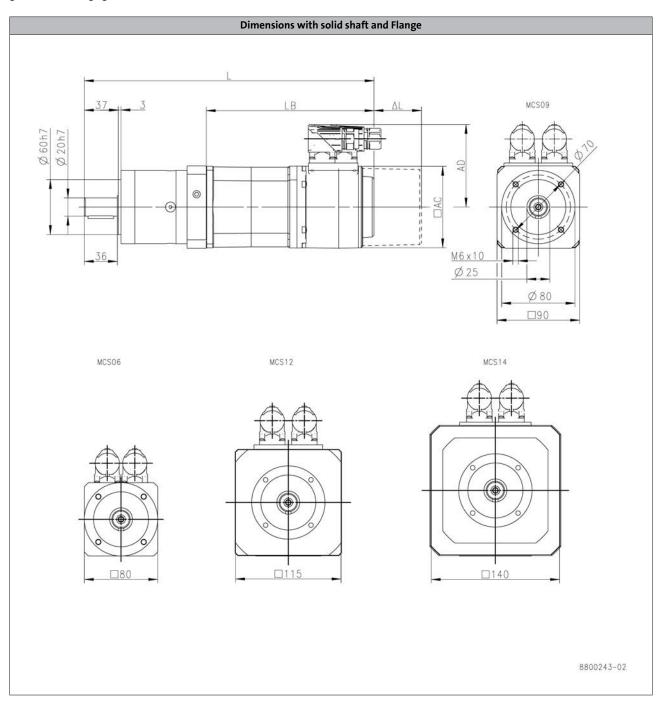
Product			MCS	
			06C41	06C60
Length				
Total length	L	[mm]	263	
Motor length	LB	[mm]	132	
Length of motor options	Δ L	[mm]	100	
Motor diameter	AC	[mm]	86	
Distance motor/connection	AD	[mm]	77	

6.1.1

g700-P planetary geared motors

Technical data

Dimensions, self-ventilated motors

g700-P130, 1-stage gearboxes

Dimensions with solid shaft and Flange

8800243-02
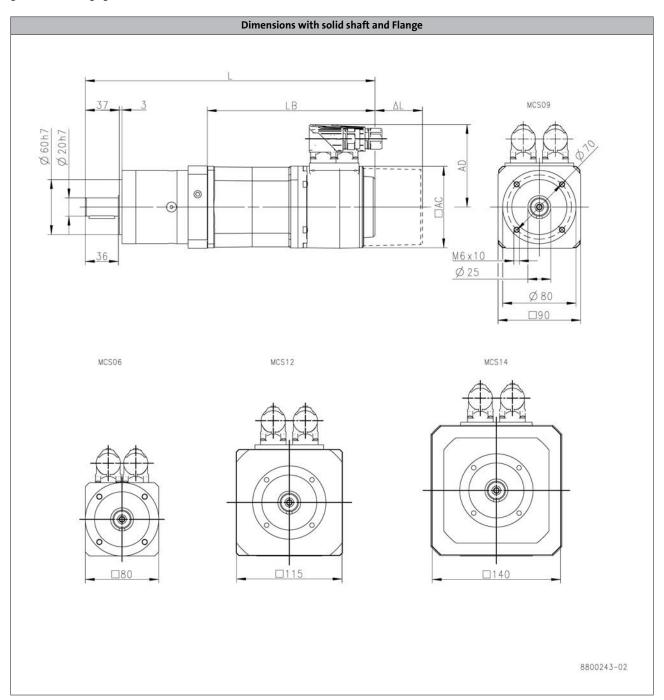
Product			MCS							
			06F41	06F60	06I41	06I60	09D41	09D60	09F38	09F60
Length										
Total length	L	[mm]	295		325		316		336	
Motor length	LB	[mm]	162		192		183		203	
Length of motor options	ΔL	[mm]	100				71			
Motor diameter	AC	[mm]	86				89			
Distance motor/connection	AD	[mm]	77				89.7			

g700-P planetary geared motors

Technical data

Dimensions, self-ventilated motors

g700-P130, 1-stage gearboxes

Dimensions with solid shaft and Flange

8800243-02

Product			MCS								
			09H41	09H60	09L41	09L51	12D20	12D41	12H15	12H30	12H35
Length											
Total length	L	[mm]	356		396		331		371		
Motor length	LB	[mm]	223		263		188		228		
Length of motor options	Δ L	[mm]	71				69				
Motor diameter	AC	[mm]	89				116				
Distance motor/connection	AD	[mm]	89.7				105				

g700-P planetary geared motors

Technical data

Dimensions, self-ventilated motors

g700-P130, 2-stage gearboxes

Dimensions with solid shaft and Flange

8800243-02

Product			MCS								
			06C41	06C60	06F41	06F60	06I41	06I60	09D41	09D60	09F38
Length											
Total length	L	[mm]	283		313		343		334		354
Motor length	LB	[mm]	132		162		192		183		203
Length of motor options	∆ L	[mm]	100						71		
Motor diameter	AC	[mm]	86						89		
Distance motor/connection	AD	[mm]	77						89.7		

6.1.1

g700-P planetary geared motors

Technical data

Dimensions, self-ventilated motors

g700-P130, 2-stage gearboxes

Dimensions with solid shaft and Flange

8800243-02
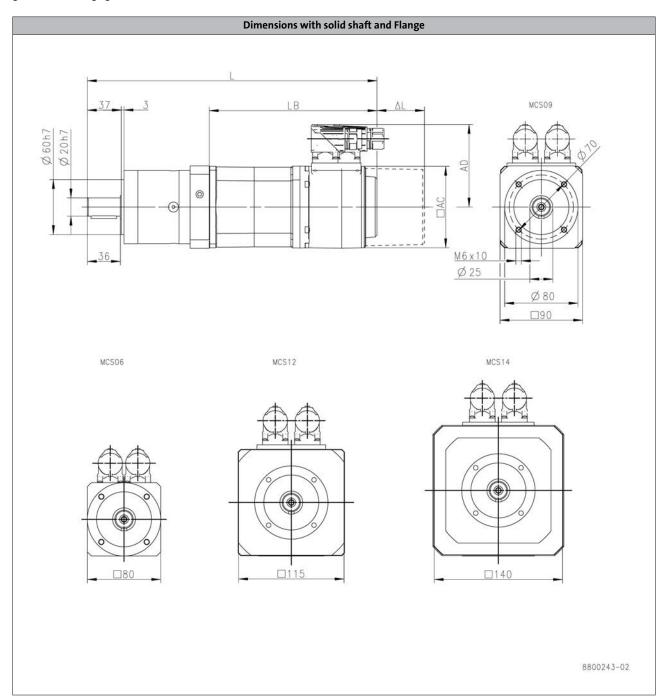
Product			MCS								
			09F60	09H41	09H60	09L41	09L51	12D20	12D41	12H15	12H30	12H35
Length												
Total length	L	[mm]	354	374		414		349		389	
Motor length	LB	[mm]	203	223		263		188		228	
Length of motor options	Δ L	[mm]		71					69		
Motor diameter	AC	[mm]		89					116		
Distance motor/connection	AD	[mm]		89.7					105		

6.1.1

g700-P planetary geared motors

Technical data

Dimensions, self-ventilated motors

g700-P130, 3-stage gearboxes

Dimensions with solid shaft and Flange

8800243-02
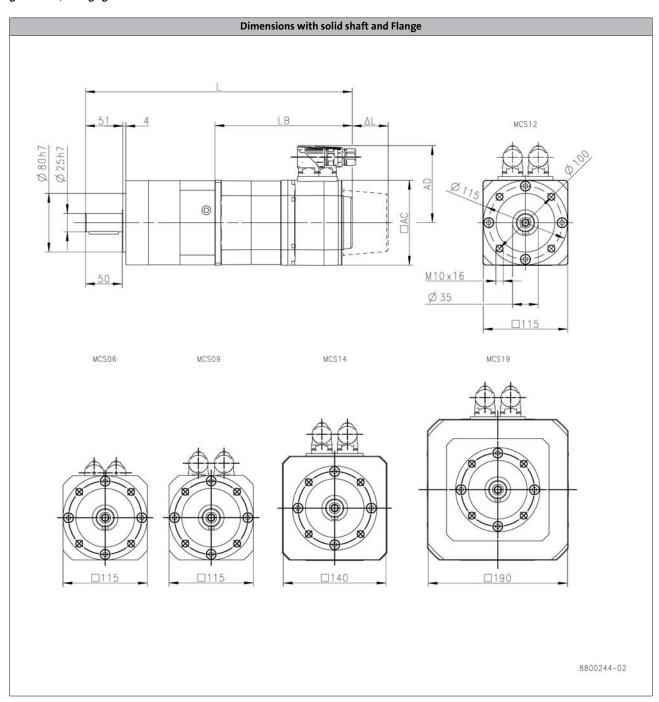
Product			MCS						
			06C41	06C60	06F41	06F60	06I41	06I60	09D60
Length									
Total length	L	[mm]	300		330		360		351
Motor length	LB	[mm]	132		162		192		183
Length of motor options	Δ L	[mm]	100						71
Motor diameter	AC	[mm]	86						89
Distance motor/connection	AD	[mm]	77						89.7

g700-P planetary geared motors

Technical data

Dimensions, self-ventilated motors

g700-P260, 1-stage gearboxes

Dimensions with solid shaft and Flange

8800244-02
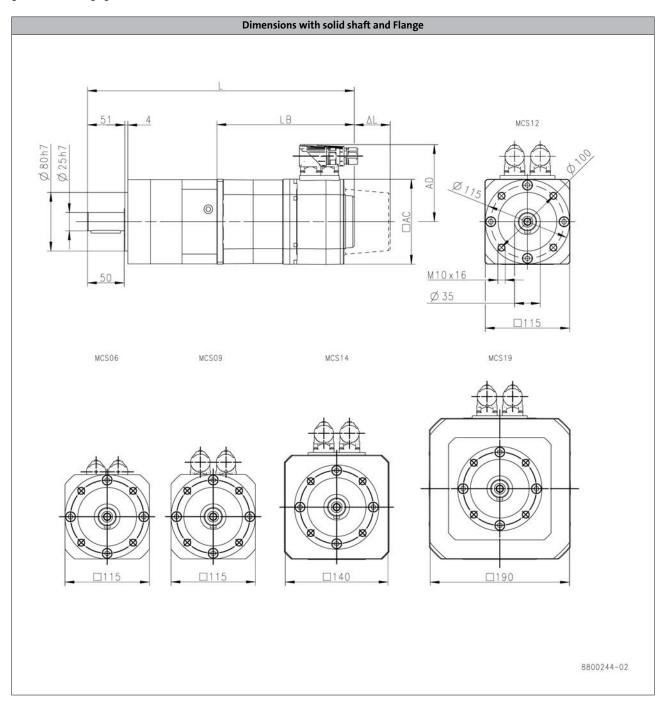
Product			MCS										
			09D41	09D60	09F38	09F60	09H41	09H60	09L41	09L51	12D20	12D41	12H15
Length													
Total length	L	[mm]	359		379		399		439		364		404
Motor length	LB	[mm]	183		203		223		263		188		228
Length of motor options	Δ L	[mm]	71								69		
Motor diameter	AC	[mm]	89								116		
Distance motor/connection	AD	[mm]	89.7								105		

g700-P planetary geared motors

Technical data

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Dimensions, self-ventilated motors

g700-P260, 1-stage gearboxes

Dimensions with solid shaft and Flange

8800244-02
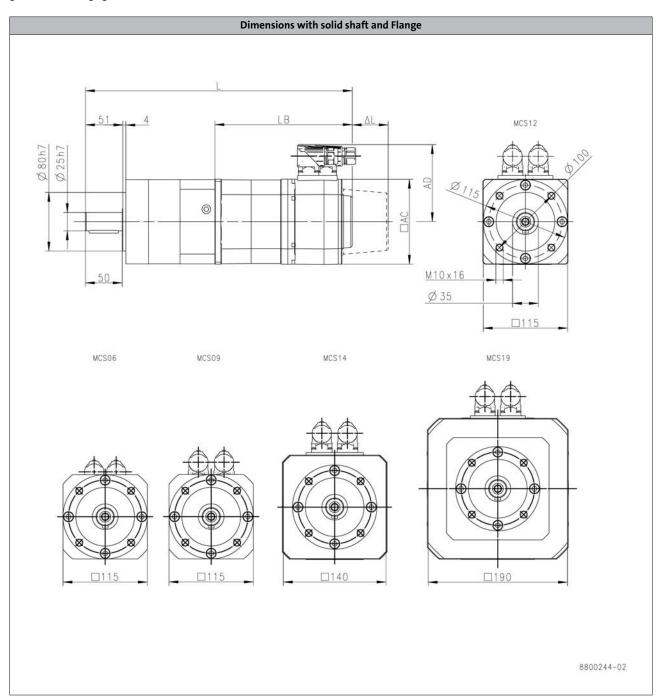
Product			MCS											
			12H30	12H35	12L20	12L41	14D15	14D36	14H15	14H32	14L15	14L32	19F14	19F30
Length														
Total length	L	[mm]	404		444		387		427		467		424	
Motor length	LB	[mm]	228		268		201		241		281		220	
Length of motor options	△L	[mm]	69				78						83	
Motor diameter	AC	[mm]	116				143						192	
Distance motor/connection	AD	[mm]	105				116.5					146	141.5	171

g700-P planetary geared motors

Technical data

Dimensions, self-ventilated motors

g700-P260, 2-stage gearboxes

Dimensions with solid shaft and Flange

8800244-02
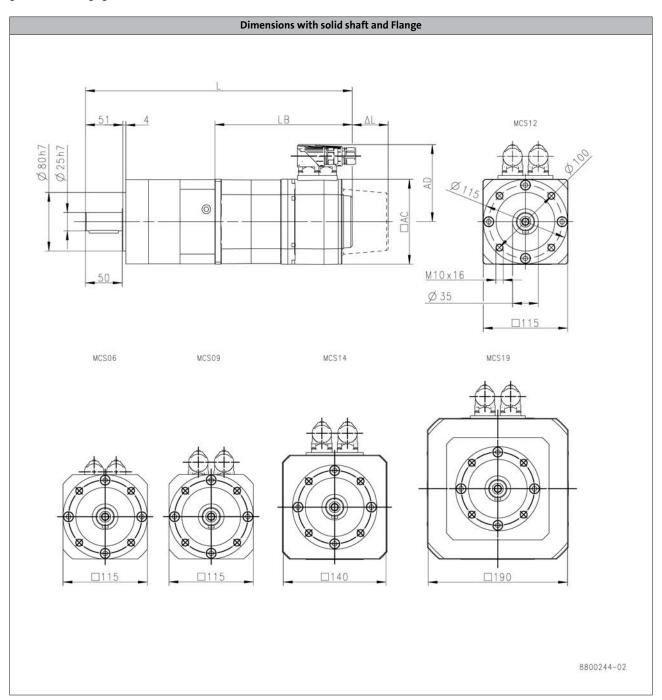
Product			MCS													
			06C41	06C60	06F41	06F60	06I41	06I60	09D41	09D60	09F38	09F60	09H41	09H60	09L41	09L51
Length																
Total length	L	[mm]	336		366		396		387		407		427		467	
Motor length	LB	[mm]	132		162		192		183		203		223		263	
Length of motor options	Δ L	[mm]	100						71							
Motor diameter	AC	[mm]	86						89							
Distance motor/connection	AD	[mm]	77						89.7							

g700-P planetary geared motors

Technical data

Dimensions, self-ventilated motors

g700-P260, 2-stage gearboxes

Dimensions with solid shaft and Flange

8800244-02
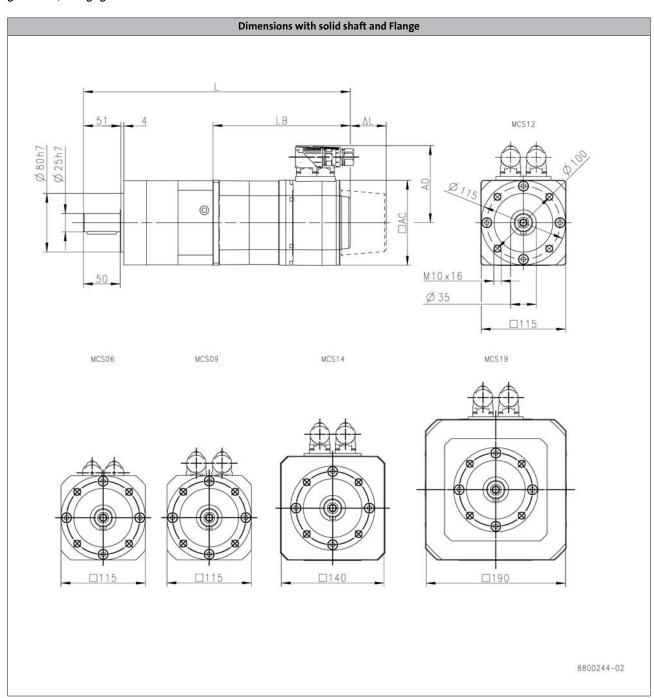
Product			MCS												
			12D20	12D41	12H15	12H30	12H35	12L20	12L41	14D15	14D36	14H15	14H32	14L15	14L32	19F30
Length															
Total length	L	[mm]	392		432		472	415		455		495				452
Motor length	LB	[mm]	188		228		268	201		241		281				220
Length of motor options	△L	[mm]			69					78						83
Motor diameter	AC	[mm]			116					143						192
Distance motor/connection	AD	[mm]			105					116.5					146	171

g700-P planetary geared motors

Technical data

Dimensions, self-ventilated motors

g700-P260, 3-stage gearboxes

Dimensions with solid shaft and Flange
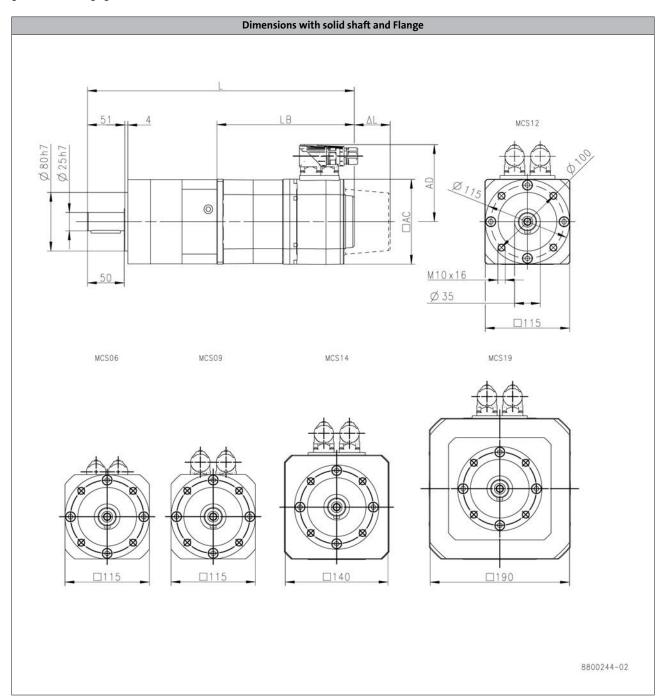
Product			MCS						
			06C41	06C60	06F41	06F60	06I41	06I60	09D41
Length									
Total length	L	[mm]	363		393		423		414
Motor length	LB	[mm]	132		162		192		183
Length of motor options	Δ L	[mm]	100						71
Motor diameter	AC	[mm]	86						89
Distance motor/connection	AD	[mm]	77						89.7

g700-P planetary geared motors

Technical data

Dimensions, self-ventilated motors

g700-P260, 3-stage gearboxes

Dimensions with solid shaft and Flange
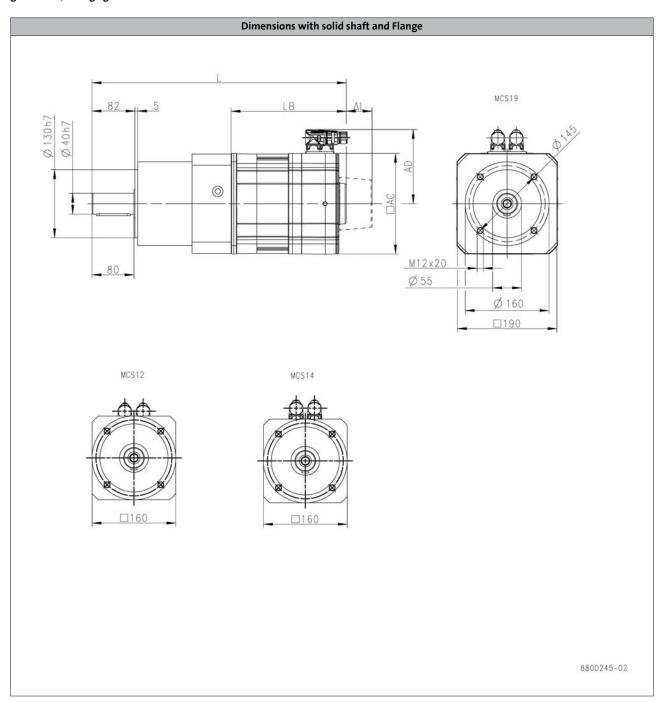
Product			MCS							
			09D60	09F38	09F60	09H41	09H60	09L41	09L51	12D41
Length										
Total length	L	[mm]	414	434		454		494		419
Motor length	LB	[mm]	183	203		223		263		188
Length of motor options	∆ L	[mm]	71							69
Motor diameter	AC	[mm]	89							116
Distance motor/connection	AD	[mm]	89.7							105

g700-P planetary geared motors

Technical data

Dimensions, self-ventilated motors

g700-P800, 1-stage gearboxes

Dimensions with solid shaft and Flange

8800245-02
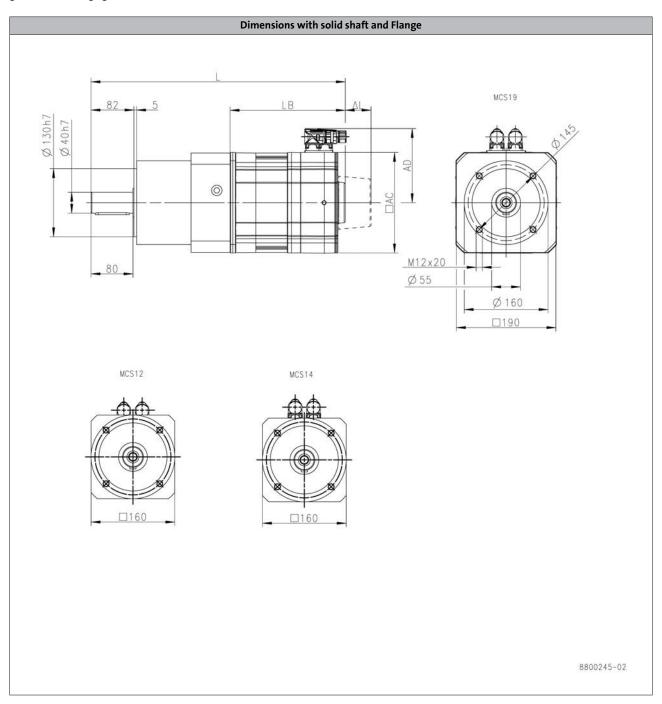
Product			MCS						
			12H15	12L20	12L41	14H15	14H32	14L15	14L32
Length									
Total length	L	[mm]	484	524		497		537	
Motor length	LB	[mm]	228	268		241		281	
Length of motor options	Δ L	[mm]		69			78		
Motor diameter	AC	[mm]		116			143		
Distance motor/connection	AD	[mm]		105			116.5		146

g700-P planetary geared motors

Technical data

Dimensions, self-ventilated motors

g700-P800, 1-stage gearboxes

Dimensions with solid shaft and Flange

8800245-02

Product			MCS							
			14P14	14P32	19F14	19F30	19J14	19J30	19P14	19P30
Length										
Total length	L	[mm]	577		486		526		586	
Motor length	LB	[mm]	321		220		260		320	
Length of motor options	Δ L	[mm]	78		83		93			
Motor diameter	AC	[mm]	143		192					
Distance motor/connection	AD	[mm]	116.5	146	141.5	171	141.5	171	141.5	171
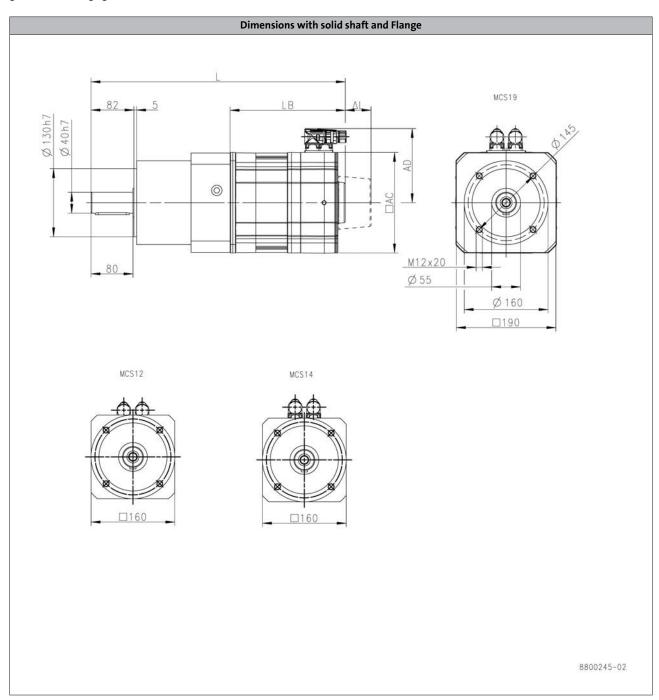
g700-P planetary geared motors

Technical data

Dimensions, self-ventilated motors

g700-P800, 2-stage gearboxes

Dimensions with solid shaft and Flange

Product			MCS									
			12D20	12D41	12H15	12H30	12H35	12L20	12L41	14D15	14D36	14H15
Length												
Total length	L	[mm]	493			533		573		506		546
Motor length	LB	[mm]	188			228		268		201		241
Length of motor options	△L	[mm]	69							78		
Motor diameter	AC	[mm]	116							143		
Distance motor/connection	AD	[mm]	105							116.5		

g700-P planetary geared motors

Technical data

Dimensions, self-ventilated motors

g700-P800, 2-stage gearboxes

Dimensions with solid shaft and Flange

8800245-02

Product			MCS										
			14H32	14L15	14L32	14P14	14P32	19F14	19F30	19J14	19J30	19P14	19P30
Length													
Total length	L	[mm]	546	586		626		535		575		635	
Motor length	LB	[mm]	241	281		321		220		260		320	
Length of motor options	Δ L	[mm]		78				83			93		
Motor diameter	AC	[mm]		143					192				
Distance motor/connection	AD	[mm]	116.5	146	116.5	146		141.5	171	141.5	171	141.5	171

6.1.1

g700-P planetary geared motors

Technical data

Dimensions, forced ventilated motors

g700-P130, 1-stage gearboxes

Dimensions with solid shaft and Flange

Product			MCS	
			12D17	12D35
Length				
Total length	L	[mm]	404	
Motor length	LB	[mm]	261	
Length of motor options	Δ L	[mm]	63	
Motor diameter	AC	[mm]	140	
Distance motor/connection	AD	[mm]	105	

Dimensions, forced ventilated motors

g700-P130, 2-stage gearboxes

Dimensions with solid shaft and Flange

MCS09

MCS06   MCS12   MCS14

□80   □115   □140

8800243-02

Product			MCS	
			12D17	12D35
Length				
Total length	L	[mm]	422	
Motor length	LB	[mm]	261	
Length of motor options	Δ L	[mm]	63	
Motor diameter	AC	[mm]	140	
Distance motor/connection	AD	[mm]	105	

g700-P planetary geared motors

Technical data

Dimensions, forced ventilated motors

g700-P260, 1-stage gearboxes

Dimensions with solid shaft and Flange

8800244-02

Product			MCS							
			12D17	12D35	12H14	12H34	12L17	12L39	14D14	14D30
Length										
Total length	L	[mm]	437		477		517		475	
Motor length	LB	[mm]	261		301		341		289	
Length of motor options	Δ L	[mm]	63						81.5	
Motor diameter	AC	[mm]	140						167	
Distance motor/connection	AD	[mm]	105						116.5	

g700-P planetary geared motors

Technical data

Dimensions, forced ventilated motors

g700-P260, 2-stage gearboxes

Dimensions with solid shaft and Flange

8800244-02

Product			MCS							
			12D17	12D35	12H14	12H34	12L17	12L39	14D14	14D30
Length										
Total length	L	[mm]	465		505		545		503	
Motor length	LB	[mm]	261		301		341		289	
Length of motor options	ΔL	[mm]	63						81.5	
Motor diameter	AC	[mm]	140						167	
Distance motor/connection	AD	[mm]	105						116.5	

g700-P planetary geared motors

Technical data

Dimensions, forced ventilated motors

g700-P800, 1-stage gearboxes

Dimensions with solid shaft and Flange

8800245-02
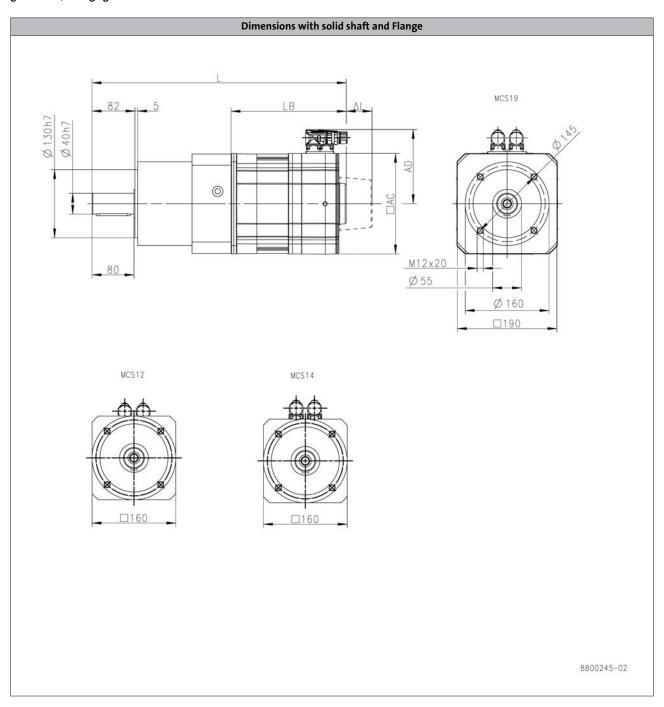
Product			MCS								
			12H14	12H34	12L17	12L39	14D14	14D30	14H12	14H28	14L14
Length											
Total length	L	[mm]	557		597		545		585		625
Motor length	LB	[mm]	301		341		289		329		369
Length of motor options	Δ L	[mm]	63				81.5				
Motor diameter	AC	[mm]	140				167				
Distance motor/connection	AD	[mm]	105				116.5			146	116.5

g700-P planetary geared motors

Technical data

Dimensions, forced ventilated motors

g700-P800, 1-stage gearboxes

Dimensions with solid shaft and Flange

8800245-02
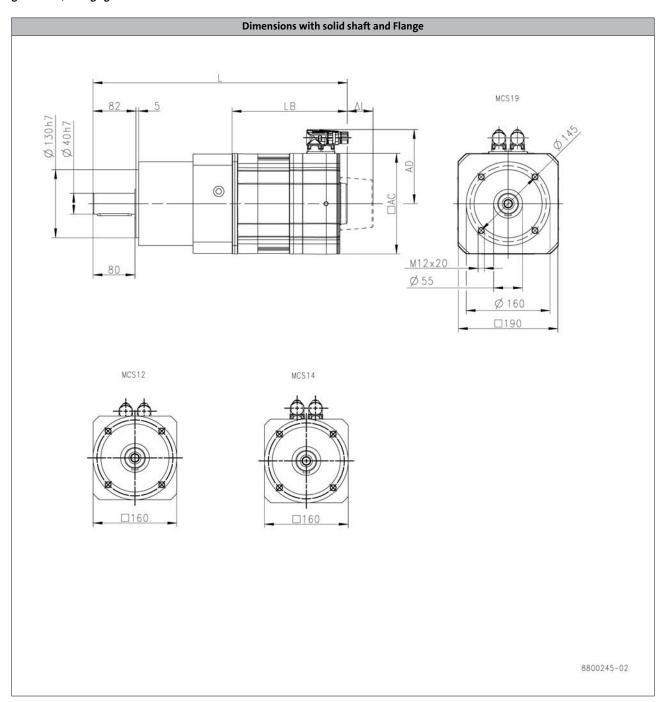
Product			MCS								
			14L30	14P11	14P26	19F12	19F29	19J12	19J29	19P12	19P29
Length											
Total length	L	[mm]	625	665		593		633		693	
Motor length	LB	[mm]	369	409		327		367		427	
Length of motor options	ΔL	[mm]		81.5			72			82	
Motor diameter	AC	[mm]		167				212			
Distance motor/connection	AD	[mm]	146	116.5	146	141.5			171		

g700-P planetary geared motors

Technical data

Dimensions, forced ventilated motors

g700-P800, 2-stage gearboxes

Dimensions with solid shaft and Flange
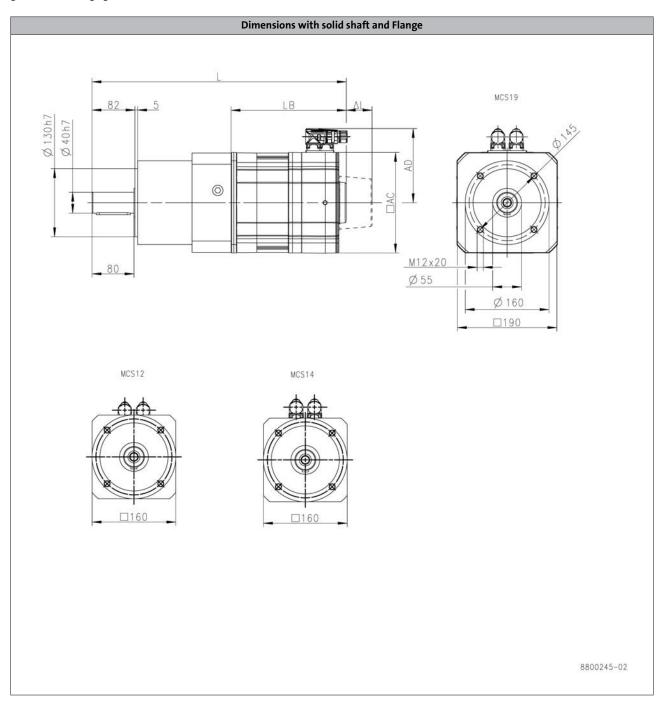
Product			MCS								
			12D17	12D35	12H14	12H34	12L17	12L39	14D14	14D30	14H12
Length											
Total length	L	[mm]	566		606		646		594		634
Motor length	LB	[mm]	261		301		341		289		329
Length of motor options	ΔL	[mm]	63						81.5		
Motor diameter	AC	[mm]	140						167		
Distance motor/connection	AD	[mm]	105						116.5		

Dimensions, forced ventilated motors

g700-P800, 2-stage gearboxes

Dimensions with solid shaft and Flange

Product			MCS									
			14H28	14L14	14L30	14P11	14P26	19F12	19F29	19J12	19J29	19P29
Length												
Total length	L	[mm]	634	674		714		642		682		742
Motor length	LB	[mm]	329	369		409		327		367		427
Length of motor options	∆L	[mm]	81.5					72		82		
Motor diameter	AC	[mm]	167					212				
Distance motor/connection	AD	[mm]	146	116.5	146	116.5	146	141.5	171			

g700-P planetary geared motors

Technical data

Weights, self-ventilated motors

1-stage gearboxes

				MCS								
				06C41 06C60	06F41 06F60	06I41 06I60	09D41 09D60	09F38 09F60	09H41 09H60	09L41 09L51	12D20 12D41	12H15
g700	-P20	m	[kg]	2.2								
	-P44	m	[kg]	2.7	3.1	3.8	5.2	6.1				
	-P130	m	[kg]		4.3	5.0	6.4	7.3	8.2	10	8.5	12
	-P260	m	[kg]				10	11	12	14	12	16
	-P800	m	[kg]									28

				MCS								
				12H30 12H35	12L20 12L41	14D15 14D36	14H15 14H32	14L15 14L32	14P14 14P32	19F14 19F30	19J14 19J30	19P14 19P30
g700	-P130	m	[kg]	12								
	-P260	m	[kg]	16	19	17	22	26		29		
	-P800	m	[kg]		31		34	38	43	41	48	58

2-stage gearboxes

				MCS								
				06C41 06C60	06F41 06F60	06I41 06I60	09D41 09D60	09F38 09F60	09H41 09H60	09L41 09L51	12D20 12D41	12H15 12H30 12H35
g700	-P20	m	[kg]	2.3								
	-P44	m	[kg]	2.9	3.3	4.0	5.4	6.3				
	-P130	m	[kg]	4.4	4.8	5.5	6.9	7.8	8.7	10	9.0	12
	-P260	m	[kg]	9.8	10	11	12	13	14	16	14	18
	-P800	m	[kg]								28	32

				MCS								
				12L20 12L41	14D15 14D36	14H15 14H32	14L15 14L32	14P14 14P32	19F14	19F30	19J14 19J30	19P14 19P30
g700	-P260	m	[kg]	21	19	24	28			31		
	-P800	m	[kg]	35	33	38	42	47	45		52	62

3-stage gearboxes

				MCS								
				06C41 06C60	06F41 06F60	06I41 06I60	09D41	09D60	09F38 09F60	09H41 09H60	09L41 09L51	12D41
g700	-P44	m	[kg]	3.1								
	-P130	m	[kg]	4.9	5.3	6.0		7.4				
	-P260	m	[kg]	12		13	14		15	16	18	16

g700-P planetary geared motors

Technical data

Weights, forced ventilated motors

1-stage gearboxes

				MCS								
				12D17 12D35	12H14 12H34	12L17 12L39	14D14 14D30	14H12 14H28	14L14 14L30	14P11 14P26 19F12 19F29	19J12 19J29	19P12 19P29
g700	-P130	m	[kg]	11								
	-P260	m	[kg]	14	18	21	20					
	-P800	m	[kg]		30	33	32	38	42	47	54	64

2-stage gearboxes

				MCS								
				12D17 12D35	12H14 12H34	12L17 12L39	14D14 14D30	14H12 14H28	14L14 14L30	14P11 14P26 19F12 19F29	19J12 19J29	19P29
g700	-P130	m	[kg]	11								
	-P260	m	[kg]	16	20	23	22					
	-P800	m	[kg]	30	34	37	36	42	46	51	58	68

6.1.1

g700-P planetary geared motors

Technical data

Surface and corrosion protection

For optimum protection of geared motors against ambient conditions, the surface and corrosion protection system (OKS) offers tailor-made solutions.

Various surface coatings combined with other protective measures ensure that the geared motors operate reliably even at high air humidity, in outdoor installations or in the presence of atmospheric impurities. Any colour from the RAL Classic collection can be chosen for the top coat. The geared motors are also available unpainted (no surface and corrosion protection).

Surface and corrosion protection	Applications	Measures
OKS-G (primed)	• Dependent on subsequent top coat applied	• 2K PUR priming coat (grey) • Zinc-coated screws • Rust-free breather elements Optional measures • Stainless steel nameplate
OKS-S (small)	• Standard applications • Internal installation in heated buildings • Air humidity up to 90%	• Surface coating corresponding to corrosivity category C1 (subject to EN 12944-2) • Zinc-coated screws • Rust-free breather elements Optional measures • Stainless steel nameplate
OKS-M (medium)	• Internal installation in non-heated buildings • Covered, protected external installation • Air humidity up to 95%	• Surface coating corresponding to corrosivity category C2 (subject to EN 12944-2) • Zinc-coated screws • Rust-free breather elements Optional measures • Stainless steel shaft • Stainless steel nameplate • Rust-free shrink disc (on request)
OKS-L (large)	• External installation • Air humidity above 95% • Chemical industry plants • Food industry	• Surface coating corresponding to corrosivity category C3 (subject to EN 12944-2) • Blower cover and B end shield additionally primed • Cable glands with gaskets • Corrosion-resistant brake with cover ring, stainless friction plate, and chrome-plated armature plate (on request) • All screws/screw plugs zinc-coated • Stainless breather elements • Threaded holes that are not used are closed by means of plastic plugs Optional measures • Sealed recesses on motor (on request) • Stainless steel shaft • Stainless steel nameplate • Rust-free shrink disc (on request) • Additional priming coat on cast iron fan • Oil expansion tank and torque plates painted separately and supplied loose
OKS-XL (extra Large) [1]	• External installation • Air humidity above 95 % • Chemical industry plants • Food industry • Coastal areas with moderate salinity	• Surface coating corresponding to corrosivity category C4 (subject to EN 12944-2) Additional measures for surface and corrosion protection system L: • Rotor package and stator in the inner area primed with finishing varnish • Feedback in protection class IP65

[1] On request

g700-P planetary geared motors

Technical data

Surface and corrosion protection

Structure of surface coating

Surface and corrosion protection	Corrosivity category	Surface coating	Colour	Coating thickness
	DIN EN ISO 12944-2	Structure		
Without OKS(uncoated)		Dipping primer of the grey iron parts		30 ... 50 µm
OKS-G (primed)		Dipping primer of the grey iron parts 2K PUR priming coat		60 ... 90 µm
OKS-S (small)	Comparable to C1	Dipping primer of the grey iron parts 2K-PUR top coat	Standard: RAL 7012 Optional: RAL Classic	80 ... 120 µm
OKS-M (medium)	Comparable to C2	Dipping primer of the grey iron parts 2K PUR priming coat 2K-PUR top coat		110 ... 160 µm
OKS-L (large)	Comparable to C3			140 ... 200 µm
OKS-XL (extra Large) [1]	Comparable to C4	Dipping primer of the grey iron parts 2K-EP priming coat (two times) 2K-PUR top coat		160 ... 240 µm

[1] On request

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g700-P planetary geared motors

12 ... 647 Nm (asynchronous servo motors)

g700-P planetary geared motors

Contents

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g700-P planetary geared motors

Contents

List of abbreviations

c		Load capacity
i		Ratio
J	[kgcm²]	Moment of inertia
m	[kg]	Mass
M_2	[Nm]	Output torque
$M_{2, max}$	[Nm]	Max. output torque
$n_{2, eto}$	[r/min]	Transition speed
$n_{2, th}$	[r/min]	Thermal limit speed

CCC	China Compulsory Certificate
CE	Communauté Européenne
CSA	Canadian Standards Association
cURus	Combined certification marks of UL for the USA and Canada
DIN	Deutsches Institut für Normung e.V.
EMC	Electromagnetic compatibility
EN	European standard
GOST	Certificate for Russian Federation
IEC	International Electrotechnical Commission
IM	International Mounting Code
IP	International Protection Code
NEMA	National Electrical Manufacturers Association
UL	Underwriters Laboratory Listed Product
UR	Underwriters Laboratory Recognized Product
VDE	Verband deutscher Elektrotechniker (Association of German Electrical Engineers)

6.1.2

g700-P planetary geared motors

General information

Product information

In combination with asynchronous servo motors, our planetary gearbox form a compact and powerful drive unit. Numerous options at the input end provide for the drive to be easily and precisely adapted to your application.

The planetary gearbox g700 is the ideal solution for demanding and dynamic tasks. With its high reliability, long service life and outstanding scalability, it provides everything you need to manage demanding machine tasks.

Versions

- High input speed possible Max. input speed 18000 rpm
- Wide variety of ratios i= 3...512 in 24 ratios
- High rated torque bandwith 20 ... 800 Nm in five sizes
- Lifetime lubrication
- Suitable for any mounting position, hence only one variant
- With MCA asynchronous servo motors, rated torque: 2 Nm ... 61.4 Nm

The product name

Gearbox type	Product range		Type	Rated torque [Nm]	Product
Planetary gearbox	g700	-	P	20	g700-P20
				44	g700-P44
				130	g700-P130
				260	g700-P260
				800	g700-P800

g700-P planetary geared motors

General information

Equipment

Overview

The equipment includes all the options available as standard and all
the built-on accessories of the product.

Motor connection

Connector
Terminal box

Cooling

self-ventilated
forced ventilated

Feedback

Resolver
Incremental encoder
Absolute value encoder

Temperature monitoring

KTY

Permanent magnet brake

Output shaft

Solid shaft with featherkey

Housing design

Threaded pitch circle with centering

The gearbox kit

Geared motor

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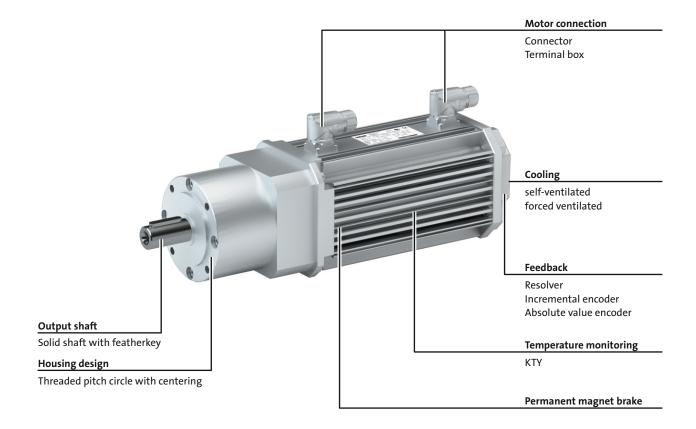
Product	g700-P130	g700-P260	g700-P800	
Motor type				
	Asynchronous servo motor			
Servo motor				
2.0 Nm	MCA10			
4.0 - 6.3 Nm		MCA13		
5.4 - 12 Nm		MCA14		
9.5 - 21 Nm			MCA17	
12 - 36 Nm			MCA19	
17 - 61 Nm				
Technical data				
Output torque	See selection table			
Output speed	See selection table			
Ratio	See selection table			
Load capacity	See selection table			
Moment of inertia	See selection table			
Mounting position				
Standard	Any			
Colour				
	Primed Paint in various corrosion-protection designs in accordance with RAL colours			
Surface and corrosion protection	Without OKS(uncoated) OKS-G (primed) OKS-S (small) OKS-M (medium) OKS-L (large)			

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g700-P planetary geared motors

General information

- -

The gearbox kit

Motor details

Product						
	MCA					
	10I40	13I34 13I41	14L16 14L20 14L35 14L41	17N17 17N23 17N35 17N41	19S17 19S23 19S35 19S42	21X17 21X25 21X35 21X42
Connection type						
	Plug connectors Terminal box					
Permanent magnet holding brake						
Rated torque [Nm]	3.3	12	15	24	46	88
Brake voltage [V]	DC 24 AC 230					
Feedback						
	With absolute value encoder With incremental encoder With resolver					
Cooling						
	Self-ventilated	Self-ventilated Forced-ventilated				
Temperature monitoring						
	KTY83-110 thermal detector					
Approval						
	cURus GOST_R UkrSepro					
Enclosure						
	IP54 IP65					

► Further information and installation feasibilities can be found in the Motors chapter.

The gearbox kit

Motor details

Connection type

Plug connectors   Terminal box

Cooling: self-ventilated

With resolver   With permanent magnet brake   With feedback
With feedback and permanent magnet brake

Cooling: forced ventilated

With resolver   With permanent magnet brake   With feedback
With feedback and permanent magnet brake

6.1.2

g700-P planetary geared motors

General information

The gearbox kit

Gearbox details

Product					
	g700-P20	g700-P44	g700-P130	g700-P260	g700-P800
Driven shaft					
Solid shaft with featherkey [mm]	10x23	14x30	20x36	25x50	40x80
Design	Standard				
Gasket	NBR				
Bearing	Standard				
Housing					
Housing version	Without foot with centering				
Output flange					
flange diameter [mm]	40	60	80	115	160
Lubricant					
Type	Klüberplex BEM34-132				
Breather element	Without				
Backlash					
Backlash	Standard				

► Further information and installation feasibilities can be found in the Gearboxes chapter.

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The gearbox kit

Gearbox details

Solid shaft

With centering

6.1.2

Dimensioning

General information about the data provided in this catalogue

The powers, torques and speeds specified in this catalogue are rounded values and are valid under the following conditions:
- Operating time/day = 8 h (100% OT)
- Duty class I for up to 10 switching operations/h
- Mounting positions and designs in this catalogue
- Standard lubricant
- T_{amb} = 30 °C for gearboxes,
  T_{amb} = 40 °C for motors (in accordance with EN 60034)
- Site altitude < = 1000 m amsl
- The selection tables provide the permissible mechanical powers and torques. For notes on the thermal power limit, see chapter drive dimensioning.
- The rated power specified for motors and geared motors applies to operating mode S1 (in accordance with EN 60034).

Under different operating conditions, the values obtained may vary from those listed here.

In the case of extreme operating conditions, please consult your Lenze sales office.

g700-P planetary geared motors

General information

_____

Dimensioning

Load capacity and application factor

Load capacity c of gearboxes
Rated value for the load capacity of Lenze geared motors.
- c is the ratio of the permissible rated torque of the gearbox to the rated torque supplied by the drive component (e.g. the built-in Lenze motor).
- The value of c must always be greater than the value of the application factor k calculated for the application.

Required: c ≥ k

Application factor k (according to DIN 3990)
Takes into account the influence of temporally variable loads which are actually present during the anticipated operating time of gearboxes and geared motors.
k is determined by:
- the type of load
- the load intensity
- temporal influences

Duty class	Load type
I	Smooth operation, small or light jolts
II	Uneven operation, average jolts
III	Uneven operation, severe jolts and/or alternating load

Application factor k

► S_h = switchings/h

g700-P planetary geared motors

General information

Dimensioning

Weights

The values given in the tables consider the following gearbox/motor combination:
- Gearbox with solid shaft including lubricant amount
- Motor with feedback

For versions deviating from this, additional weights have to be considered.

The respective values can be found for:
- Geared motors with feedback
  > Chapter: Geared motors/Technical data
- Motor options: Brake
  > Chapter: Motors/Accessories

Moments of inertia

The given moments of inertia of the gearbox refer to the drive shaft. The influence of the ratio (i^2) has been considered in the data.

When the total moment of inertia of the geared motor is calculated, the values of the geared motors and the brake have to be added.

The respective values can be found for:
- Geared motors with feedback
  > Chapter: Geared motors/Technical data/Selection tables
- Motor options: Brake
  > Chapter: Motors/Accessories

g700-P planetary geared motors

Technical data

- -

Selection tables, notes

Notes on the selection tables

The selection tables show the available combinations of gearbox type, number of stages, ratio and motor. They are used only to provide basic orientation.
The following legend indicates the structure of the selection tables.

Number of the gear stage of the gearbox

2-stage gearboxes

| Inverter operation | | | | | | i | Product | | Cooling | |
$M_{2, max}$ [Nm]	$n_{2, th}$ [r/min]	M_2 [Nm]	$n_{2, eto}$ [r/min]	c	J [kgcm²]		g700	MCS		
6.7	506	5	506	1.3	0.200	8.000	-P20	06C41	Selbst	27
9.4	579	4	579	2.1	0.200	7.000	-P20	06C41	Selbst	27
15	810	3	810	4.8	0.200	5.000	-P20	06C41	Selbst	27
17	405	6	405	2.6	0.300	10.000	-P44	06C41	Selbst	29

For operating mode S1
Torque M_2 and
thermal output speed $n_{2, th}$

Product Gearbox

Product Motor

Ratio i

Moment of inertia of geared motor

Type of motor cooling

Page number for dimensions

For operating mode S2, S3 und S6
Max. permissible acceleration torque of geared motor $M_{2, max}$ and
output speed $n_{2, eto}$

Load capacity of the gearbox
c is the ratio between the permissible rated torque of the gearbox and the rated torque of the three-phase AC motor (converted to the driven shaft).
c must be always higher than the service factor **k** determined for the application **k**.

$$c = \frac{M_{2, zul}}{M_{1,N} \cdot i \cdot \eta_{Getr}} > k$$

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g700-P planetary geared motors

Technical data

Selection tables

1-stage gearboxes

| Inverter operation | | | | | | i | Product | | Cooling | ⌀ |
$M_{2, max}$ [Nm]	$n_{2, th}$ [r/min]	M_2 [Nm]	$n_{2, eto}$ [r/min]	c	J [kgcm²]		g700	MCA		
38	305	19	305	2.0	3.100	10.000	-P130	10I40	natural	24
41	600	8	600	5.5	2.900	5.000	-P130	10I40	natural	24
50	494	15	494	3.0	2.800	8.000	-P130	10I40	natural	24
60	564	12	564	4.6	2.800	7.000	-P130	10I40	natural	24
84	350	17	350	4.9	5.000	10.000	-P260	10I40	natural	26
95	350	38	350	2.5	11.000	10.000	-P260	13I41	natural	26
95	350	52	350	1.8	22.000	10.000	-P260	14L41	natural	26
95	341	60	341	1.6	11.000	10.000	-P260	13I34	forced	31
95	200	64	200	1.5	22.000	10.000	-P260	14L20	natural	26
115	667	16	667	5.8	22.000	3.000	-P260	14L20	natural	26
120	438	28	438	3.9	9.600	8.000	-P260	13I41	natural	26
120	438	40	438	2.9	20.000	8.000	-P260	14L41	natural	26
120	426	47	426	2.5	9.600	8.000	-P260	13I34	forced	31
120	250	51	250	2.3	20.000	8.000	-P260	14L20	natural	26
135	500	24	500	5.0	9.700	7.000	-P260	13I41	natural	26
135	500	34	500	3.7	21.000	7.000	-P260	14L41	natural	26
135	487	40	487	3.2	9.700	7.000	-P260	13I34	forced	31
135	286	43	286	3.0	21.000	7.000	-P260	14L20	natural	26
155	500	22	500	5.9	21.000	4.000	-P260	14L20	natural	26
195	400	27	400	5.9	21.000	5.000	-P260	14L20	natural	26
266	300	57	300	3.8	48.000	3.000	-P800	17N17	forced	33
271	300	52	300	3.4	48.000	3.000	-P800	17N35	forced	33
331	250	71	250	5.3	44.000	4.000	-P800	17N17	forced	33
396	194	71	194	5.4	24.000	8.000	-P800	14L35	forced	33
400	300	30	300	5.1	84.000	3.000	-P800	19S42	natural	29
400	300	42	300	4.5	84.000	3.000	-P800	19S23	natural	29
406	194	81	194	4.8	24.000	8.000	-P800	14L16	forced	33
423	230	80	230	4.8	42.000	5.000	-P800	17N35	forced	33
435	230	93	230	4.3	42.000	5.000	-P800	17N17	forced	33
450	230	66	230	5.6	78.000	5.000	-P800	19S23	natural	29
450	194	71	194	5.4	41.000	8.000	-P800	17N23	natural	29
450	194	81	194	4.8	77.000	8.000	-P800	19S42	natural	29
450	194	117	194	3.6	77.000	8.000	-P800	19S23	natural	29
450	194	140	194	3.0	41.000	8.000	-P800	17N35	forced	33
450	194	160	194	2.7	41.000	8.000	-P800	17N17	forced	33

g700-P planetary geared motors

Technical data

Selection tables

2-stage gearboxes

Inverter operation						i	Product		Cooling	⟷
$M_{2, max}$ [Nm]	$n_{2, th}$ [r/min]	M_2 [Nm]	$n_{2, eto}$ [r/min]	c	J [kgcm²]		g700	MCA		
66	439	13	439	5.0	2.800	9.000	-P130	10I40	natural	25
103	313	21	313	3.1	3.100	12.000	-P130	10I40	natural	25
110	263	27	263	2.7	3.100	15.000	-P130	10I40	natural	25
110	158	47	158	1.9	2.800	25.000	-P130	10I40	natural	25
110	99	75	99	1.4	2.800	40.000	-P130	10I40	natural	25
120	247	29	247	2.6	2.900	16.000	-P130	10I40	natural	25
120	198	37	198	2.3	2.800	20.000	-P130	10I40	natural	25
120	123	60	123	1.7	2.800	32.000	-P130	10I40	natural	25
120	55	114	55	1.1	5.000	64.000	-P260	10I40	natural	27
185	140	37	140	4.8	3.900	25.000	-P260	10I40	natural	27
210	294	28	294	4.2	9.600	9.000	-P260	13I41	natural	27
210	294	42	294	3.1	20.000	9.000	-P260	14L41	natural	27
210	294	50	294	2.8	9.600	9.000	-P260	13I34	forced	32
210	222	52	222	3.2	20.000	9.000	-P260	14L20	natural	27
230	213	48	213	4.0	11.000	15.000	-P260	13I41	natural	27
230	213	71	213	3.0	22.000	15.000	-P260	14L41	natural	27
230	213	85	213	2.5	11.000	15.000	-P260	13I34	forced	32
230	140	91	140	2.4	9.800	25.000	-P260	13I41	natural	27
230	140	127	140	1.8	21.000	25.000	-P260	14L41	natural	27
230	136	148	136	1.5	9.800	25.000	-P260	13I34	forced	32
230	133	92	133	2.4	22.000	15.000	-P260	14L20	natural	27
230	88	69	88	3.1	3.700	40.000	-P260	10I40	natural	27
230	88	150	88	1.5	9.600	40.000	-P260	13I41	natural	27
230	88	203	88	1.1	20.000	40.000	-P260	14L41	natural	27
230	80	157	80	1.4	21.000	25.000	-P260	14L20	natural	27
250	109	50	109	4.3	3.700	32.000	-P260	10I40	natural	27
260	225	33	225	5.6	11.000	12.000	-P260	13I41	natural	27
260	225	51	225	4.2	22.000	12.000	-P260	14L41	natural	27
260	225	63	225	3.6	11.000	12.000	-P260	13I34	forced	32
260	197	50	197	4.2	10.000	16.000	-P260	13I41	natural	27
260	197	74	197	3.1	21.000	16.000	-P260	14L41	natural	27
260	197	90	197	2.7	10.000	16.000	-P260	13I34	forced	32
260	175	67	175	3.4	9.800	20.000	-P260	13I41	natural	27
260	175	98	175	2.5	21.000	20.000	-P260	14L41	natural	27
260	171	117	171	2.1	9.800	20.000	-P260	13I34	forced	32
260	167	68	167	3.4	22.000	12.000	-P260	14L20	natural	27
260	125	97	125	2.5	21.000	16.000	-P260	14L20	natural	27
260	109	119	109	2.1	9.600	32.000	-P260	13I41	natural	27
260	109	162	109	1.6	20.000	32.000	-P260	14L41	natural	27
260	107	190	107	1.4	9.600	32.000	-P260	13I34	forced	32

6.1.2

g700-P planetary geared motors

Technical data

Selection tables

2-stage gearboxes

Inverter operation						i	Product		Cooling	⌀
$M_{2,max}$ [Nm]	$n_{2,th}$ [r/min]	M_2 [Nm]	$n_{2,eto}$ [r/min]	c	J [kgcm²]		g700	MCA		
260	100	126	100	2.0	21.000	20.000	-P260	14L20	natural	27
260	63	202	63	1.3	20.000	32.000	-P260	14L20	natural	27
450	47	230	47	1.9	13.000	64.000	-P800	13I41	natural	30
450	47	311	47	1.4	24.000	64.000	-P800	14L41	natural	30
450	47	363	47	1.2	13.000	64.000	-P800	13I34	forced	34
450	31	386	31	1.2	24.000	64.000	-P800	14L20	natural	30
486	88	97	88	5.8	32.000	12.000	-P800	14L16	forced	34
517	88	93	88	5.2	32.000	12.000	-P800	14L35	forced	34
602	70	119	70	4.7	14.000	25.000	-P800	13I34	forced	34
696	87	125	87	4.4	32.000	15.000	-P800	14L35	forced	34
700	87	107	87	4.7	48.000	15.000	-P800	17N41	natural	30
700	87	124	87	4.5	48.000	15.000	-P800	17N23	natural	30
700	87	143	87	4.0	32.000	15.000	-P800	14L16	forced	34
700	87	148	87	3.7	84.000	15.000	-P800	19S42	natural	30
700	87	213	87	3.0	84.000	15.000	-P800	19S23	natural	30
700	87	258	87	2.5	48.000	15.000	-P800	17N35	forced	34
700	87	297	87	2.3	48.000	15.000	-P800	17N17	forced	34
700	70	94	70	5.5	25.000	25.000	-P800	14L41	natural	30
700	70	129	70	4.4	25.000	25.000	-P800	14L20	natural	30
700	70	205	70	3.1	42.000	25.000	-P800	17N41	natural	30
700	70	240	70	2.7	25.000	25.000	-P800	14L35	forced	34
700	70	240	70	2.7	42.000	25.000	-P800	17N23	natural	30
700	70	272	70	2.5	78.000	25.000	-P800	19S42	natural	30
700	70	383	70	1.8	78.000	25.000	-P800	19S23	natural	30
700	70	447	70	1.6	42.000	25.000	-P800	17N35	forced	34
700	67	505	67	1.4	42.000	25.000	-P800	17N17	forced	34
700	65	272	65	2.5	25.000	25.000	-P800	14L16	forced	34
700	58	121	58	4.7	14.000	40.000	-P800	13I41	natural	30
700	58	181	58	3.5	24.000	40.000	-P800	14L41	natural	30
700	58	220	58	3.0	14.000	40.000	-P800	13I34	forced	34
700	58	357	58	2.0	41.000	40.000	-P800	17N41	natural	30
700	58	406	58	1.7	24.000	40.000	-P800	14L35	forced	34
700	58	406	58	1.7	41.000	40.000	-P800	17N23	natural	30
700	58	451	58	1.6	77.000	40.000	-P800	19S42	natural	30
700	58	613	58	1.1	77.000	40.000	-P800	19S23	natural	30
700	50	237	50	2.8	24.000	40.000	-P800	14L20	natural	30
700	41	451	41	1.6	24.000	40.000	-P800	14L16	forced	34
745	75	149	75	4.3	27.000	16.000	-P800	14L16	forced	34
750	75	135	75	4.3	27.000	16.000	-P800	14L35	forced	34
798	88	86	88	5.9	48.000	12.000	-P800	17N23	natural	30

6.1.2

g700-P planetary geared motors

Technical data

Selection tables

2-stage gearboxes

| Inverter operation | | | | | | i | Product | | Cooling | |
$M_{2,max}$ [Nm]	$n_{2,th}$ [r/min]	M_2 [Nm]	$n_{2,eto}$ [r/min]	c	J [kgcm²]		g700	MCA		
800	88	79	88	5.5	48.000	12.000	-P800	17N41	natural	30
800	88	111	88	4.4	84.000	12.000	-P800	19S42	natural	30
800	88	158	88	3.9	84.000	12.000	-P800	19S23	natural	30
800	88	199	88	2.9	48.000	12.000	-P800	17N35	forced	34
800	88	220	88	3.2	48.000	12.000	-P800	17N17	forced	34
800	75	115	75	4.6	43.000	16.000	-P800	17N41	natural	30
800	75	128	75	4.8	43.000	16.000	-P800	17N23	natural	30
800	75	159	75	3.6	79.000	16.000	-P800	19S42	natural	30
800	75	223	75	3.2	79.000	16.000	-P800	19S23	natural	30
800	75	277	75	2.4	43.000	16.000	-P800	17N35	forced	34
800	75	313	75	2.4	43.000	16.000	-P800	17N17	forced	34
800	73	153	73	4.0	43.000	20.000	-P800	17N41	natural	30
800	73	175	73	3.9	43.000	20.000	-P800	17N23	natural	30
800	73	178	73	3.7	26.000	20.000	-P800	14L35	forced	34
800	73	201	73	3.5	26.000	20.000	-P800	14L16	forced	34
800	73	207	73	3.1	79.000	20.000	-P800	19S42	natural	30
800	73	294	73	2.6	79.000	20.000	-P800	19S23	natural	30
800	73	355	73	2.1	43.000	20.000	-P800	17N35	forced	34
800	73	404	73	1.9	43.000	20.000	-P800	17N17	forced	34
800	61	128	61	4.9	26.000	32.000	-P800	14L41	natural	30
800	61	159	61	4.2	15.000	32.000	-P800	13I34	forced	34
800	61	173	61	3.9	26.000	32.000	-P800	14L20	natural	30
800	61	269	61	2.8	42.000	32.000	-P800	17N41	natural	30
800	61	314	61	2.4	26.000	32.000	-P800	14L35	forced	34
800	61	314	61	2.4	42.000	32.000	-P800	17N23	natural	30
800	61	356	61	2.2	78.000	32.000	-P800	19S42	natural	30
800	61	490	61	1.6	78.000	32.000	-P800	19S23	natural	30
800	61	572	61	1.4	42.000	32.000	-P800	17N35	forced	34
800	53	647	53	1.2	42.000	32.000	-P800	17N17	forced	34
800	51	356	51	2.2	26.000	32.000	-P800	14L16	forced	34

6.1.2

g700-P planetary geared motors

Technical data

Selection tables

3-stage gearboxes

| Inverter operation | | | | | | i | Product | | Cooling | ↗ |
M$_{2, max}$ [Nm]	n$_{2, th}$ [r/min]	M$_2$ [Nm]	n$_{2, eto}$ [r/min]	c	J [kgcm²]		g700	MCA		
230	29	209	29	1.1	4.900	120.000	-P260	10I40	natural	28
260	58	104	58	2.4	3.700	60.000	-P260	10I40	natural	28
260	58	216	58	1.2	9.600	60.000	-P260	13I41	natural	28
260	44	144	44	1.8	3.900	80.000	-P260	10I40	natural	28
260	35	180	35	1.4	3.900	100.000	-P260	10I40	natural	28

6.1.2

g700-P planetary geared motors

Technical data

Dimensions, notes

Notes on the dimensions

The following legend shows the layout of the dimension sheets.

Product gearbox

Driven shaft design

g700-P44

Abmessungen mit Vollwelle

Product Motor

Produkt			MCS				
			06C41	06F41	06I41	09D41	09F38
Abmessungen							
Gesamtlänge	L	[mm]	238	268	298	296	316
Länge Motor	LB	[mm]	132	162	192	183	203
Länge Motoranbauten	Δ L	[mm]	100			71	
Motordurchmesser	AC	[mm]	86			89	
Abstand Motor/Anschluss	AD	[mm]	77			89.7	

Distance of motor centre to the end of connector

Total length of the drive without built-on accessories

Motor diameter

Motor length without built-on accessories

Additional length of the built-on accessories (longest version)

6.1.2

Dimensions, self-ventilated motors

g700-P130, 1-stage gearboxes

Dimensions with solid shaft and Flange

MCA10

8800252-02

Product			MCA			
			10I40			
Length						
Total length	L	[mm]	395			
Motor length	LB	[mm]	262			
Length of motor options	Δ L	[mm]	78.5			
Motor diameter	AC	[mm]	102			
Distance motor/connection	AD	[mm]	90			

6.1.2

Dimensions, self-ventilated motors

g700-P130, 2-stage gearboxes

Dimensions with solid shaft and Flange

8800252-02
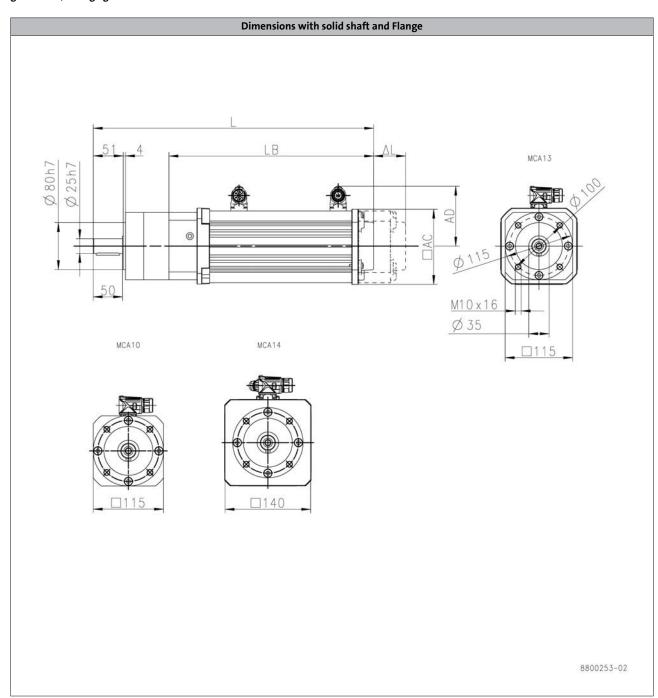
Product			MCA
			10l40
Length			
Total length	L	[mm]	413
Motor length	LB	[mm]	262
Length of motor options	∆ L	[mm]	78.5
Motor diameter	AC	[mm]	102
Distance motor/connection	AD	[mm]	90

g700-P planetary geared motors

Technical data

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Dimensions, self-ventilated motors

g700-P260, 1-stage gearboxes

Dimensions with solid shaft and Flange
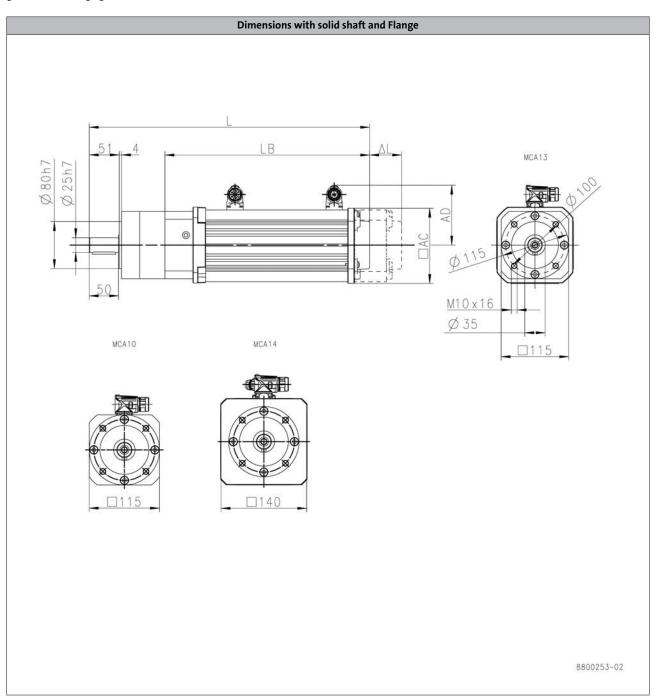
Product			MCA			
			10I40	13I41	14L20	14L41
Length						
Total length	L	[mm]	438	447	478	
Motor length	LB	[mm]	262	270.5	301.5	
Length of motor options	Δ L	[mm]	78.5	89	88.5	
Motor diameter	AC	[mm]	102	130	142	
Distance motor/connection	AD	[mm]	90	102	109	

g700-P planetary geared motors

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Dimensions, self-ventilated motors

g700-P260, 2-stage gearboxes

Dimensions with solid shaft and Flange

8800253-02
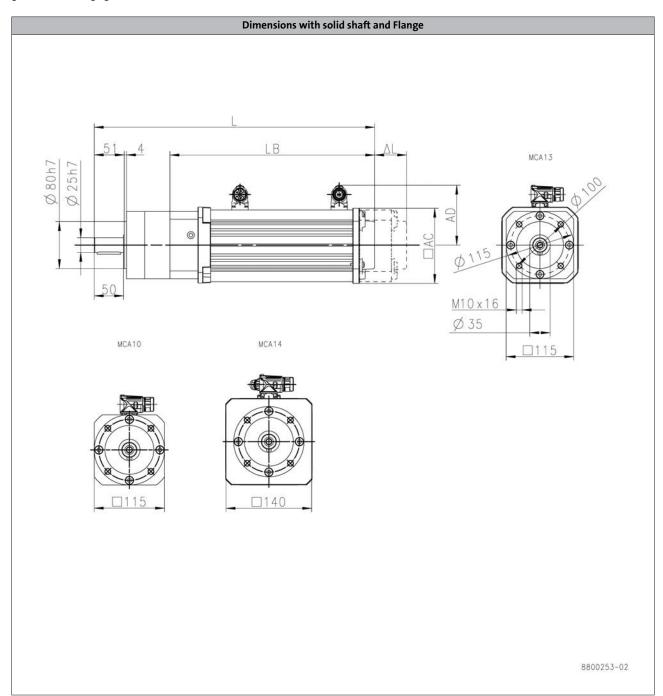
Product			MCA			
			10I40	13I41	14L20	14L41
Length						
Total length	L	[mm]	466	474	505	
Motor length	LB	[mm]	262	270.5	301.5	
Length of motor options	Δ L	[mm]	78.5	89	88.5	
Motor diameter	AC	[mm]	102	130	142	
Distance motor/connection	AD	[mm]	90	102	109	

6.1.2

Dimensions, self-ventilated motors

g700-P260, 3-stage gearboxes

Dimensions with solid shaft and Flange
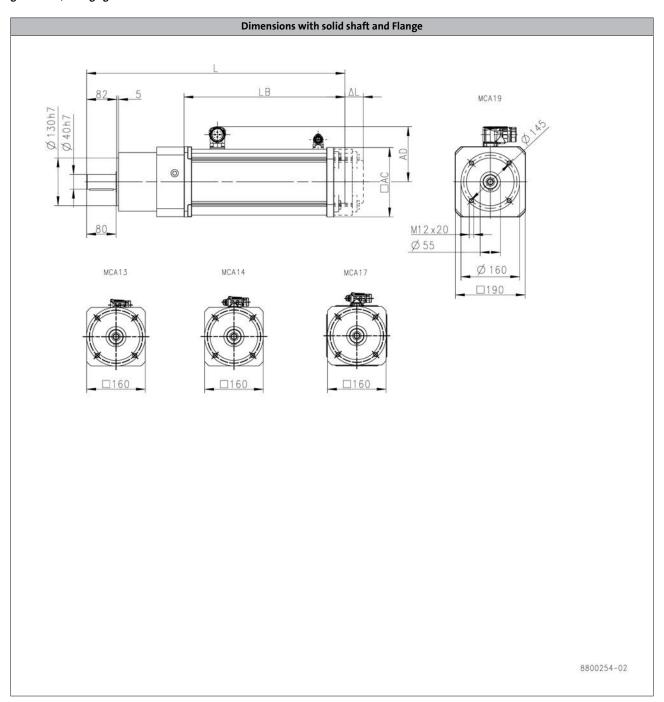
Product			MCA	
			10l40	13l41
Length				
Total length	L	[mm]	493	502
Motor length	LB	[mm]	262	270.5
Length of motor options	Δ L	[mm]	78.5	89
Motor diameter	AC	[mm]	102	130
Distance motor/connection	AD	[mm]	90	102

g700-P planetary geared motors

Technical data

Dimensions, self-ventilated motors

g700-P800, 1-stage gearboxes
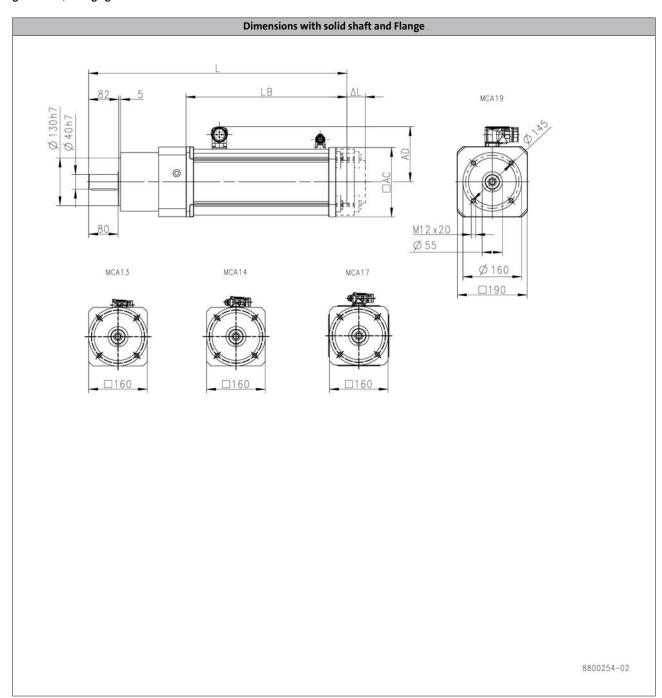
		MCA		
Product		17N23	19S23	19S42
Length				
Total length	L [mm]	595	667	
Motor length	LB [mm]	339.5	401	
Length of motor options	ΔL [mm]	89.2	88.2	
Motor diameter	AC [mm]	165	192	
Distance motor/connection	AD [mm]	117.5	151	

g700-P planetary geared motors

Technical data

Dimensions, self-ventilated motors

g700-P800, 2-stage gearboxes

Dimensions with solid shaft and Flange

8800254-02
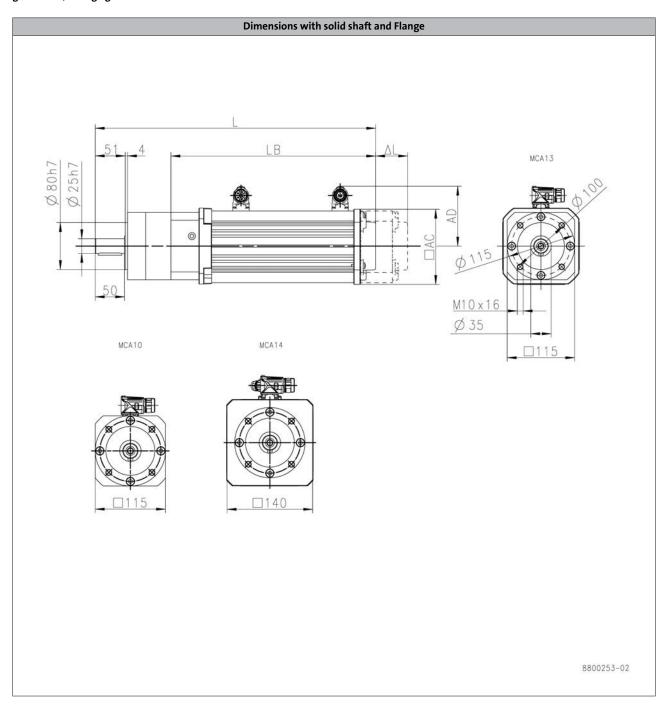
Product			MCA						
			13I41	14L20	14L41	17N23	17N41	19S23	19S42
Length									
Total length	L	[mm]	576	607		645		716	
Motor length	LB	[mm]	270.5	301.5		339.5		401	
Length of motor options	Δ L	[mm]	89	88.5		89.2		88.2	
Motor diameter	AC	[mm]	130	142		165		192	
Distance motor/connection	AD	[mm]	102	109		117.5		151	

g700-P planetary geared motors

Technical data

Dimensions, forced ventilated motors

g700-P260, 1-stage gearboxes

Dimensions with solid shaft and Flange

8800253-02
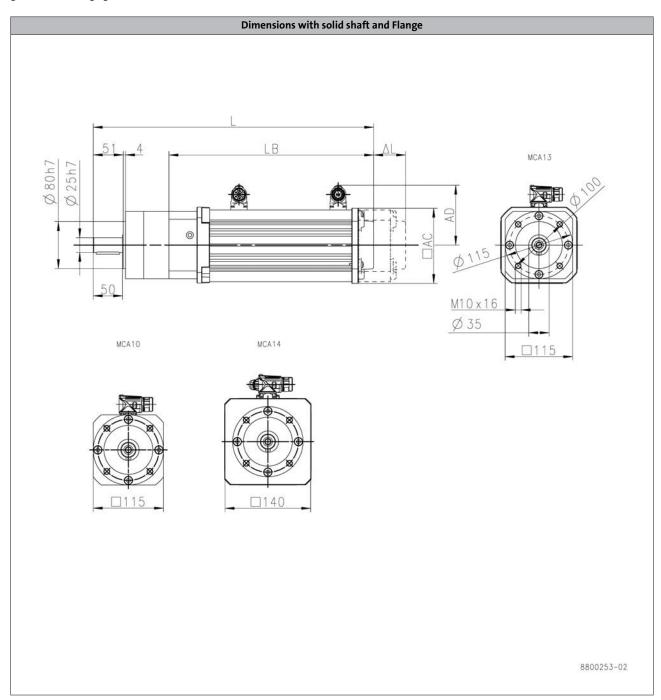
Product			MCA
			13I34
Length			
Total length	L	[mm]	515
Motor length	LB	[mm]	338.5
Length of motor options	∆ L	[mm]	89.5
Motor diameter	AC	[mm]	130
Distance motor/connection	AD	[mm]	102

- -

Dimensions, forced ventilated motors

g700-P260, 2-stage gearboxes

Dimensions with solid shaft and Flange

8800253-02

Product			MCA		
			13I34		
Length					
Total length	L	[mm]	542		
Motor length	LB	[mm]	338.5		
Length of motor options	Δ L	[mm]	89.5		
Motor diameter	AC	[mm]	130		
Distance motor/connection	AD	[mm]	102		

Dimensions, forced ventilated motors

g700-P800, 1-stage gearboxes

Dimensions with solid shaft and Flange
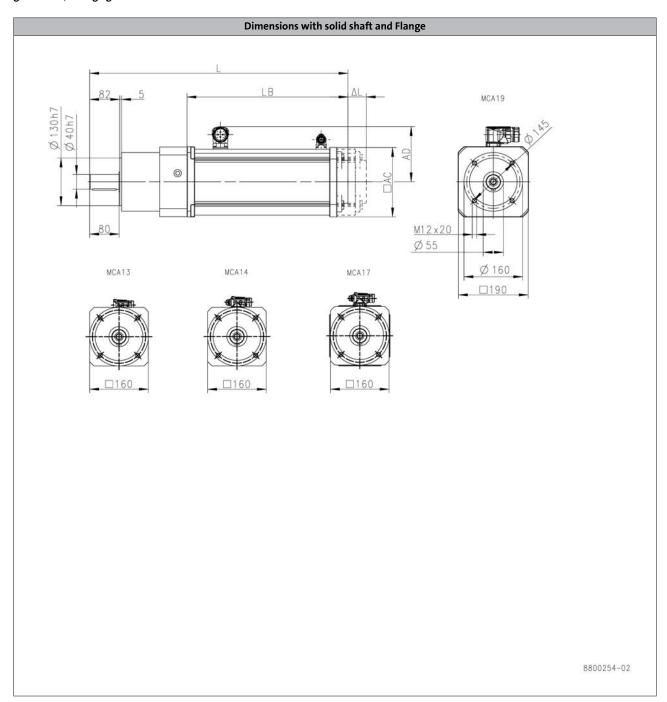
Product			MCA			
			14L16	14L35	17N17	17N35
Length						
Total length	L	[mm]	619		681	
Motor length	LB	[mm]	363.5		425.5	
Length of motor options	Δ L	[mm]	88.5		89	
Motor diameter	AC	[mm]	142		165	
Distance motor/connection	AD	[mm]	109		117.5	

g700-P planetary geared motors

Technical data

Dimensions, forced ventilated motors

g700-P800, 2-stage gearboxes

Dimensions with solid shaft and Flange

MCA19

MCA13   MCA14   MCA17

8800254-02

Product			MCA				
			13I34	14L16	14L35	17N17	17N35
Length							
Total length	L	[mm]	644	669		731	
Motor length	LB	[mm]	338.5	363.5		425.5	
Length of motor options	Δ L	[mm]	89.5	88.5		89	
Motor diameter	AC	[mm]	130	142		165	
Distance motor/connection	AD	[mm]	102	109		117.5	

g700-P planetary geared motors

Technical data

Weights, self-ventilated motors

1-stage gearboxes

				MCA				
				10I40	13I41	14L20 14L41	17N23	19S23 19S42
g700	-P130	m	[kg]	8.5				
	-P260	m	[kg]	12	16	21		
	-P800	m	[kg]				41	63

2-stage gearboxes

				MCA				
				10I40	13I41	14L20 14L41	17N23 17N41	19S23 19S42
g700	-P130	m	[kg]	9.0				
	-P260	m	[kg]	14	18	23		
	-P800	m	[kg]		32	37	45	67

3-stage gearboxes

				MCA	
				10I40	13I41
g700	-P260	m	[kg]	16	20

6.1.2

g700-P planetary geared motors

Technical data

Weights, forced ventilated motors

1-stage gearboxes

				MCA		
				13I34	14L16 14L35	17N17 17N35
g700	-P260	m	[kg]	18		
	-P800	m	[kg]		35	44

2-stage gearboxes

				MCA		
				13I34	14L16 14L35	17N17 17N35
g700	-P260	m	[kg]	20		
	-P800	m	[kg]	34	39	48

g700-P planetary geared motors

Technical data

Surface and corrosion protection

For optimum protection of geared motors against ambient conditions, the surface and corrosion protection system (OKS) offers tailor-made solutions.

Various surface coatings combined with other protective measures ensure that the geared motors operate reliably even at high air humidity, in outdoor installations or in the presence of atmospheric impurities. Any colour from the RAL Classic collection can be chosen for the top coat. The geared motors are also available unpainted (no surface and corrosion protection).

Surface and corrosion protection	Applications	Measures
OKS-G (primed)	• Dependent on subsequent top coat applied	• 2K PUR priming coat (grey) • Zinc-coated screws • Rust-free breather elements Optional measures • Stainless steel nameplate
OKS-S (small)	• Standard applications • Internal installation in heated buildings • Air humidity up to 90%	• Surface coating corresponding to corrosivity category C1 (subject to EN 12944-2) • Zinc-coated screws • Rust-free breather elements Optional measures • Stainless steel nameplate
OKS-M (medium)	• Internal installation in non-heated buildings • Covered, protected external installation • Air humidity up to 95%	• Surface coating corresponding to corrosivity category C2 (subject to EN 12944-2) • Zinc-coated screws • Rust-free breather elements Optional measures • Stainless steel shaft • Stainless steel nameplate • Rust-free shrink disc (on request)
OKS-L (large)	• External installation • Air humidity above 95% • Chemical industry plants • Food industry	• Surface coating corresponding to corrosivity category C3 (subject to EN 12944-2) • Blower cover and B end shield additionally primed • Cable glands with gaskets • Corrosion-resistant brake with cover ring, stainless friction plate, and chrome-plated armature plate (on request) • All screws/screw plugs zinc-coated • Stainless breather elements • Threaded holes that are not used are closed by means of plastic plugs Optional measures • Sealed recesses on motor (on request) • Stainless steel shaft • Stainless steel nameplate • Rust-free shrink disc (on request) • Additional priming coat on cast iron fan • Oil expansion tank and torque plates painted separately and supplied loose
OKS-XL (extra Large) [1]	• External installation • Air humidity above 95 % • Chemical industry plants • Food industry • Coastal areas with moderate salinity	• Surface coating corresponding to corrosivity category C4 (subject to EN 12944-2) Additional measures for surface and corrosion protection system L: • Rotor package and stator in the inner area primed with finishing varnish • Feedback in protection class IP65

[1] On request

g700-P planetary geared motors

Technical data

Surface and corrosion protection

Structure of surface coating

Surface and corrosion protection	Corrosivity category	Surface coating	Colour	Coating thickness
	DIN EN ISO 12944-2	Structure		
Without OKS(uncoated)		Dipping primer of the grey iron parts		30 ... 50 μm
OKS-G (primed)		Dipping primer of the grey iron parts 2K PUR priming coat		60 ... 90 μm
OKS-S (small)	Comparable to C1	Dipping primer of the grey iron parts 2K-PUR top coat	Standard: RAL 7012 Optional: RAL Classic	80 ... 120 μm
OKS-M (medium)	Comparable to C2	Dipping primer of the grey iron parts 2K PUR priming coat 2K-PUR top coat		110 ... 160 μm
OKS-L (large)	Comparable to C3			140 ... 200 μm
OKS-XL (extra Large) [1]	Comparable to C4	Dipping primer of the grey iron parts 2K-EP priming coat (two times) 2K-PUR top coat		160 ... 240 μm

[1] On request

6.1.2

g700-P planetary gearboxes

20 to 800 Nm

g700-P planetary gearbox

Contents

6.1.3

g700-P planetary gearbox

General information

List of abbreviations

$F_{ax,max}$	[N]	Max. axial force
$F_{rad,max}$	[N]	Max. radial force
i		Ratio
J	[kgcm²]	Moment of inertia
m	[kg]	Mass

g700-P planetary gearbox

General information

Product information

The planetary gearbox g700 is the ideal solution for demanding and dynamic tasks. With its high reliability, long service life and outstanding scalability, it provides everything you need to manage demanding machine tasks.

Versions

- High input speed possible Max. input speed 18000 rpm
- Wide variety of ratios i= 3...512 in 24 ratios
- High rated torque bandwidth 20 ... 800 Nm in five sizes
- Lifetime lubrication
- Suitable for any mounting position, hence only one variant

The product name

Gearbox type	Product range		Type	Rated torque [Nm]	Product
Planetary gearbox	g700	-	P	20	g700-P20
				44	g700-P44
				130	g700-P130
				260	g700-P260
				800	g700-P800

6.1.3

g700-P planetary gearbox

General information

Equipment

Overview

The equipment includes all the options available as standard and all
the built-on accessories of the product.

Output shaft

Solid shaft with featherkey

Housing design

Threaded pitch circle with centering

g700-P planetary gearbox

General information

The gearbox kit

Gearbox details

Product	g700-P20	g700-P44	g700-P130	g700-P260	g700-P800
Driven shaft					
Solid shaft with featherkey [mm]	10x23	14x30	20x36	25x50	40x80
Design	Standard				
Gasket	NBR				
Bearing	Standard				
Housing					
Housing version	Without foot with centering				
Output flange					
flange diameter [mm]	40	60	80	115	160
Lubricant					
Type	Klüberplex BEM34-132				
Breather element	Without				
Backlash					
Backlash	Standard				

► Further information and installation feasibilities can be found in
   the Gearboxes chapter.

- -

The gearbox kit

Gearbox details

Solid shaft
With centering

g700-P planetary gearbox

General information

Functions and features

Product					
	g700-P20	g700-P44	g700-P130	g700-P260	g700-P800
Housing					
Design	Cylindrical shape				
Solid shaft					
Design	with keyway to DIN 6885				
Tolerance	h7				
Toothed parts					
Design	Spur-toothed				
Ratios	Mathematically precise				
Shaft-hub joint					
	Force-fit, motor gearbox connected via clamping hub				
Lubricants					
Changing interval	Lubricated for life				
Quantities	Can be installed in any orientation				
Mechanical efficiency					
1-stage gearboxes [$\eta_{c=1}$]	0.96				
2-stage gearboxes [$\eta_{c=1}$]	0.94				
3-stage gearboxes [$\eta_{c=1}$]	0.90				

Direction of rotation

6.1.3

g700-P planetary gearbox

Technical data

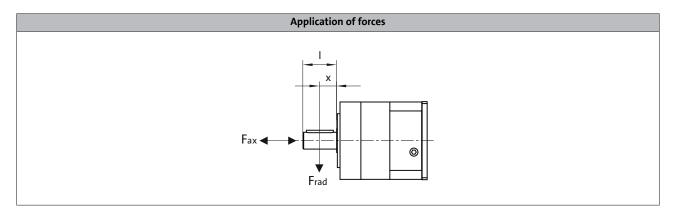
Permissible radial and axial forces at output

Permissible radial force
$F_{rad,per} = F_{radmax}$ if $F_{ax} = 0$

Permissible axial force
$F_{ax,per} = F_{ax,max}$ if $F_{rad} = 0$

▶ If F_{rad} **and** $F_{ax} \neq 0$, please contact Lenze.

Application of forces

Product	n_2 [r/min]
	100

	Max. radial force, Solid shaft with flange	Max. axial force, Solid shaft with flange
	$F_{rad,max}$	$F_{ax,max}$
	[N]	[N]
g700-P20	200	200
g700-P44	500	400
g700-P130	1000	750
g700-P260	2500	1750
g700-P800	7000	5000

▶ Application of force F_{rad}: centre of shaft journal (x = l/2)
▶ $F_{ax,max}$ only valid with $F_{rad} = 0$

6.1.3

g700-P planetary gearbox

Technical data

Backlash and torsional rigidity

1-stage gearboxes

Product	Backlash	Torsional stiffness
	[arcmin]	[Nm/arcmin]
g700-P20	15.0	1.00
g700-P44	10.0	2.30
g700-P130	7.00	6.00
g700-P260		12.0
g700-P800	6.00	38.0

2-stage gearboxes

Product	Backlash	Torsional stiffness
	[arcmin]	[Nm/arcmin]
g700-P20	19.0	1.10
g700-P44	12.0	2.50
g700-P130	9.00	6.50
g700-P260		13.0
g700-P800	10.0	41.0

3-stage gearboxes

Product	Backlash	Torsional stiffness
	[arcmin]	[Nm/arcmin]
g700-P20	22.0	1.00
g700-P44	15.0	2.50
g700-P130	11.0	6.30
g700-P260		12.0

► The backlash is measured with 1 % of the rated torque, at least 1 Nm.

6.1.3

g700-P planetary gearbox

Technical data

- -

Speeds and torques

► **Rated torque M$_{2, GN}$**
At rated speed, ambient temperature 30 °C and duty type S1.
► **Max. output torque M$_{2, max}$**
At output speed 100 r/min , duty type S1, uniform and shock-free motion.
► **Emergency off torque M$_{2, not}$**
Max.1000 emergency switching off actions during gearbox service life

► **Max. gearbox input speed**
n$_{1, max 50\%}$
Max. medium speed at 50 % rated torque
n$_{1, max 100\%}$
Max. medium speed at 100 % rated torque
n$_{1, max}$
Max. permissible speed

1-stage gearboxes

Product	Ratio	Rated torque	Max. output torque	Max. gearbox input speed			Emergency off-torque
	i	M$_{2, GN}$	M$_{2, max}$	n$_{1, max 50\%}$	n$_{1, max 100\%}$	n$_{1, max}$	M$_{2, not}$
		[Nm]	[Nm]	[r/min]	[r/min]	[r/min]	[Nm]
g700-P20	3.000	11	18	5000	5000		23
	4.000	15	24	5000	5000		30
	5.000	14	22	5000	5000	18000	36
	7.000	9	14	5000	5000		26
	8.000	6	10	5000	5000		27
	10.000	5	8	5000	5000		27
g700-P44	3.000	28	45	4500	4500		66
	4.000	38	61	4500	4500		88
	5.000	40	64	4500	4500	13000	80
	7.000	25	40	4500	4500		80
	8.000	18	29	4500	4500		80
	10.000	15	24	4500	4500		80
g700-P130	3.000	85	136	4000	2700		180
	4.000	115	184	3850	2500		240
	5.000	110	176	4000	3000	7000	220
	7.000	65	104	4000	4000		178
	8.000	50	80	4000	4000		190
	10.000	38	61	4000	4000		200
g700-P260	3.000	115	184	3350	2550		390
	4.000	155	248	3400	2500		520
	5.000	195	312	3500	2500	6500	500
	7.000	135	216	3500	3500		340
	8.000	120	192	3500	3500		380
	10.000	95	152	3500	3500		480
g700-P800	3.000	400	640	1350	900		800
	4.000	450	720	1450	1000	6500	900
	5.000	450	720	1650	1150		900
	8.000	450	720	2150	1550		900

6.1.3

g700-P planetary gearbox

Technical data

Speeds and torques

2-stage gearboxes

Product	Ratio	Rated torque	Max. output torque	Max. gearbox input speed			Emergency off-torque
	i	$M_{2, GN}$	$M_{2, max}$	$n_{1, max\ 50\%}$	$n_{1, max\ 100\%}$	$n_{1, max}$	$M_{2, not}$
		[Nm]	[Nm]	[r/min]	[r/min]	[r/min]	[Nm]
g700-P20	9.000	17	26	5000	5000		33
	12.000	20	32	5000	5000		40
	15.000	18	29	5000	5000		36
	16.000	20	32	5000	5000		40
	20.000	20	32	5000	5000	18000	40
	25.000	18	29	5000	5000		36
	32.000	20	32	5000	5000		40
	40.000	18	29	5000	5000		36
	64.000	8	12	5000	5000		27
g700-P44	9.000	44	70	4500	4500		88
	12.000	44	70	4500	4500		88
	15.000	44	70	4500	4500		88
	16.000	44	70	4500	4500		88
	20.000	44	70	4500	4500	13000	88
	25.000	40	64	4500	4500		80
	32.000	44	70	4500	4500		88
	40.000	40	64	4500	4500		80
	64.000	18	29	4500	4500		80
g700-P130	9.000	130	208	4000	3050		260
	12.000	120	192	4000	3750		240
	15.000	110	176	4000	4000		220
	16.000	120	192	4000	4000		240
	20.000	120	192	4000	4000	7000	240
	25.000	110	176	4000	4000		220
	32.000	120	192	4000	4000		240
	40.000	110	176	4000	4000		220
	64.000	50	80	4000	4000		190
g700-P260	9.000	210	336	3500	2650		500
	12.000	260	416	3500	2650		520
	15.000	230	368	3500	3200		500
	16.000	260	416	3500	3100		520
	20.000	260	416	3500	3500	6500	520
	25.000	230	368	3500	3500		500
	32.000	260	416	3500	3500		520
	40.000	230	368	3500	3500		500
	64.000	120	192	3500	3500		380
g700-P800	12.000	800	1280	1550	1000		1600
	15.000	700	1120	1850	1300		1400
	16.000	800	1280	1750	1200		1600
	20.000	800	1280	2050	1400		1600
	25.000	700	1120	2350	1700	6500	1400
	32.000	800	1280	2650	1900		1600
	40.000	700	1120	2950	2300		1400
	64.000	450	720	3000	3000		900

g700-P planetary gearbox

Technical data

Speeds and torques

3-stage gearboxes

Product	Ratio	Rated torque	Max. output torque	Max. gearbox input speed			Emergency off-torque
	i	$M_{2, GN}$	$M_{2, max}$	$n_{1, max\ 50\%}$	$n_{1, max\ 100\%}$	$n_{1, max}$	$M_{2, not}$
		[Nm]	[Nm]	[r/min]	[r/min]	[r/min]	[Nm]
g700-P20	60.000	20	32	5000	5000		40
	80.000	20	32	5000	5000		40
	100.000	20	32	5000	5000		40
	120.000	18	29	5000	5000		36
	160.000	20	32	5000	5000	18000	40
	200.000	18	29	5000	5000		36
	256.000	20	32	5000	5000		40
	320.000	18	29	5000	5000		36
	512.000	8	12	5000	5000		27
g700-P44	60.000	44	70	4500	4500		88
	80.000	44	70	4500	4500		88
	100.000	44	70	4500	4500		88
	120.000	44	70	4500	4500		88
	160.000	44	70	4500	4500	13000	88
	200.000	40	64	4500	4500		80
	256.000	44	70	4500	4500		88
	320.000	40	64	4500	4500		80
	512.000	18	29	4500	4500		80
g700-P130	60.000	110	176	4000	4000		220
	80.000	120	192	4000	4000		240
	100.000	120	192	4000	4000		240
	120.000	110	176	4000	4000		220
	160.000	120	192	4000	4000	7000	240
	200.000	110	176	4000	4000		220
	256.000	120	192	4000	4000		240
	320.000	110	176	4000	4000		220
	512.000	50	80	4000	4000		190
g700-P260	60.000	260	416	3500	3500		520
	80.000	260	416	3500	3500		520
	100.000	260	416	3500	3500		520
	120.000	230	368	3500	3500		500
	160.000	260	416	3500	3500	6500	520
	200.000	230	368	3500	3500		500
	256.000	260	416	3500	3500		520
	320.000	230	368	3500	3500		500
	512.000	120	192	3500	3500		380

6.1.3

g700-P planetary gearbox

Technical data

- -

Moments of inertia

► The moments of inertia relate to the drive shaft of the gearbox.
► The total moment of inertia is calculated by adding the values of the gearbox, motor and accessories.

1-stage gearboxes

Product	Dimensions	Ratio	Moment of inertia
	Motor shaft diameter		
	d	i	J
	[mm]		[kgcm²]
g700-P20	11	3.000	0.065
	11	4.000	0.056
	11	5.000	0.053
	11	7.000	0.052
	11	8.000	0.051
	11	10.000	0.043
g700-P44	11	3.000	0.134
	11	4.000	0.092
	11	5.000	0.077
	11	7.000	0.071
	11	8.000	0.064
	11	10.000	0.130
	14	3.000	0.108
	14	4.000	0.066
	14	5.000	0.051
	14	7.000	0.014
	14	8.000	0.038
	14	10.000	0.014
g700-P130	11	3.000	0.770
	11	4.000	0.520
	11	5.000	0.450
	11	7.000	0.420
	11	8.000	0.390
	11	10.000	0.740
	14	3.000	0.770
	14	4.000	0.520
	14	5.000	0.450
	14	7.000	0.420
	14	8.000	0.390
	14	10.000	0.740
	19	3.000	0.770
	19	4.000	0.520
	19	5.000	0.450
	19	7.000	0.420
	19	8.000	0.390
	19	10.000	0.740
g700-P260	11	3.000	2.662
	11	4.000	1.822
	11	5.000	1.562
	11	7.000	1.442
	11	8.000	1.352
	11	10.000	2.652

Product	Dimensions	Ratio	Moment of inertia
	Motor shaft diameter		
	d	i	J
	[mm]		[kgcm²]
g700-P260	14	3.000	2.655
	14	4.000	1.815
	14	5.000	1.555
	14	7.000	1.435
	14	8.000	1.345
	14	10.000	2.645
	19	3.000	2.630
	19	4.000	1.790
	19	5.000	1.530
	19	7.000	1.410
	19	8.000	1.320
	19	10.000	2.620
	24	3.000	2.574
	24	4.000	1.734
	24	5.000	1.474
	24	7.000	1.354
	24	8.000	1.264
	24	10.000	2.564
	28	3.000	4.897
	28	4.000	4.057
	28	5.000	3.797
	28	7.000	3.687
	28	8.000	3.587
	28	10.000	4.887
g700-P800	19	3.000	12.211
	19	4.000	7.851
	19	5.000	6.141
	19	8.000	4.701
	24	3.000	12.140
	24	4.000	7.780
	24	5.000	6.070
	24	8.000	4.630
	28	3.000	12.040
	28	4.000	7.680
	28	5.000	5.970
	28	8.000	4.530

6.1.3

g700-P planetary gearbox

Technical data

Moments of inertia

2-stage gearboxes

Product	Dimensions	Ratio	Moment of inertia
	Motor shaft diameter		
	d	i	J
	[mm]		[kgcm²]
g700-P20	11	9.000	0.064
	11	12.000	0.063
	11	15.000	0.057
	11	16.000	0.056
	11	20.000	0.053
	11	25.000	0.053
	11	32.000	0.051
	11	40.000	0.050
	11	64.000	0.063
g700-P44	11	9.000	0.063
	11	12.000	0.126
	11	15.000	0.076
	11	16.000	0.087
	11	20.000	0.074
	11	25.000	0.074
	11	32.000	0.063
	11	40.000	0.063
	11	64.000	0.075
	14	9.000	0.064
	14	12.000	0.100
	14	15.000	0.050
	14	16.000	0.061
	14	20.000	0.048
	14	25.000	0.048
	14	32.000	0.014
	14	40.000	0.037
	14	64.000	0.049
g700-P130	11	9.000	0.390
	11	12.000	0.720
	11	15.000	0.710
	11	16.000	0.500
	11	20.000	0.440
	11	25.000	0.440
	11	32.000	0.390
	11	40.000	0.390
	11	64.000	0.510
	14	9.000	0.390
	14	12.000	0.720
	14	15.000	0.710
	14	16.000	0.500
	14	20.000	0.440
	14	25.000	0.440
	14	32.000	0.390
	14	40.000	0.390
	14	64.000	0.510
	19	9.000	0.390
	19	12.000	0.720
	19	15.000	0.710
	19	16.000	0.500
	19	20.000	0.440
	19	25.000	0.440
	19	32.000	0.390
	19	40.000	0.390
	19	64.000	0.510

Product	Dimensions	Ratio	Moment of inertia
	Motor shaft diameter		
	d	i	J
	[mm]		[kgcm²]
g700-P260	11	9.000	1.332
	11	12.000	2.592
	11	15.000	2.562
	11	16.000	1.782
	11	20.000	1.532
	11	25.000	1.522
	11	32.000	1.332
	11	40.000	1.332
	11	64.000	2.602
	14	9.000	1.325
	14	12.000	2.585
	14	15.000	2.555
	14	16.000	1.775
	14	20.000	1.525
	14	25.000	1.515
	14	32.000	1.325
	14	40.000	1.325
	14	64.000	2.595
	19	9.000	1.300
	19	12.000	2.560
	19	15.000	2.530
	19	16.000	1.750
	19	20.000	1.500
	19	25.000	1.490
	19	32.000	1.300
	19	40.000	1.300
	19	64.000	2.570
	24	9.000	1.244
	24	12.000	2.504
	24	15.000	2.474
	24	16.000	1.694
	24	20.000	1.444
	24	25.000	1.434
	24	32.000	1.244
	24	40.000	1.244
	24	64.000	2.514
	28	9.000	3.567
	28	12.000	4.827
	28	15.000	4.797
	28	16.000	4.017
	28	20.000	3.767
	28	25.000	3.757
	28	32.000	3.567
	28	40.000	3.567
	28	64.000	4.837

6.1.3

Moments of inertia

2-stage gearboxes

Product	Dimensions	Ratio	Moment of iner-tia
	Motor shaft diameter		
	d	i	J
	[mm]		[kgcm²]
g700-P800	19	12.000	12.441
	19	15.000	12.421
	19	16.000	7.541
	19	20.000	6.721
	19	25.000	5.881
	19	32.000	6.431
	19	40.000	5.351
	19	64.000	4.571
	24	12.000	12.370
	24	15.000	12.350
	24	16.000	7.470
	24	20.000	6.650
	24	25.000	5.810
	24	32.000	6.360
	24	40.000	5.280
	24	64.000	4.500
	28	12.000	12.270
	28	15.000	12.250
	28	16.000	7.370
	28	20.000	6.550
	28	25.000	5.710
	28	32.000	6.260
	28	40.000	5.180
	28	64.000	4.400

6.1.3

g700-P planetary gearbox

Technical data

Moments of inertia

3-stage gearboxes

Product	Dimensions	Ratio	Moment of iner-tia	Product	Dimensions	Ratio	Moment of iner-tia
	Motor shaft diameter				Motor shaft diameter		
	d	i	J		d	i	J
	[mm]		[kgcm²]		[mm]		[kgcm²]
g700-P20	11	60.000	0.050		11	60.000	1.332
	11	80.000	0.053		11	80.000	1.532
	11	100.000	0.053		11	100.000	1.522
	11	120.000	0.063		11	120.000	2.532
	11	160.000	0.050		11	160.000	1.332
	11	200.000	0.050		11	200.000	1.332
	11	256.000	0.050		11	256.000	1.332
	11	320.000	0.050		11	320.000	1.332
	11	512.000	0.050		11	512.000	1.332
g700-P44	11	60.000	0.063		14	60.000	1.325
	11	80.000	0.074		14	80.000	1.525
	11	100.000	0.074		14	100.000	1.515
	11	120.000	0.063		14	120.000	2.525
	11	160.000	0.063		14	160.000	1.325
	11	200.000	0.063		14	200.000	1.325
	11	256.000	0.063		14	256.000	1.325
	11	320.000	0.063		14	320.000	1.325
	11	512.000	0.063		14	512.000	1.325
	14	60.000	0.037		19	60.000	1.300
	14	80.000	0.048		19	80.000	1.500
	14	100.000	0.048		19	100.000	1.490
	14	120.000	0.037		19	120.000	2.500
	14	160.000	0.037	g700-P260	19	160.000	1.300
	14	200.000	0.037		19	200.000	1.300
	14	256.000	0.037		19	256.000	1.300
	14	320.000	0.037		19	320.000	1.300
	14	512.000	0.037		19	512.000	1.300
g700-P130	11	60.000	0.390		24	60.000	1.244
	11	80.000	0.500		24	80.000	1.444
	11	100.000	0.440		24	100.000	1.434
	11	120.000	0.700		24	120.000	2.444
	11	160.000	0.390		24	160.000	1.244
	11	200.000	0.390		24	200.000	1.244
	11	256.000	0.390		24	256.000	1.244
	11	320.000	0.390		24	320.000	1.244
	11	512.000	0.390		24	512.000	1.244
	14	60.000	0.390		28	60.000	3.567
	14	80.000	0.500		28	80.000	3.767
	14	100.000	0.440		28	100.000	3.757
	14	120.000	0.700		28	120.000	4.767
	14	160.000	0.390		28	160.000	3.567
	14	200.000	0.390		28	200.000	3.567
	14	256.000	0.390		28	256.000	3.567
	14	320.000	0.390		28	320.000	3.567
	14	512.000	0.390		28	512.000	3.567
	19	60.000	0.390				
	19	80.000	0.500				
	19	100.000	0.440				
	19	120.000	0.700				
	19	160.000	0.390				
	19	200.000	0.390				
	19	256.000	0.390				
	19	320.000	0.390				
	19	512.000	0.390				

MCS synchronous servo motors

0.5 ... 190 Nm

MCS synchronous servo motors

Contents

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MCS synchronous servo motors

General information

List of abbreviations

$\eta_{100\%}$	[%]	Efficiency
$\cos\varphi$		Power factor
du/dt	[kV/µs]	Insulation resistance
$F_{ax,-}$	[N]	Min. axial force
$F_{ax,+}$	[N]	Max. axial force
$f_{in,max}$	[Hz]	Max. input frequency
f_{max}	[kHz]	Limit frequency
f_{max}	[kHz]	Max. switching frequency
f_N	[Hz]	Rated frequency
F_{rad}	[N]	Max. radial force
H_{max}	[m]	Site altitude
I_0	[A]	Standstill current
I_{max}	[A]	Max. short-time DC-bus current
I_{max}	[A]	Max. current
I_{max}	[A]	Max. current consumption
I_{max}	[A]	Max. current
I_{max}	[A]	Max. DC-bus current
I_N	[A]	Rated current
J	[kgcm²]	Moment of inertia
J_{MB}	[kgcm²]	Moment of inertia
$KE_{LL\ 150\,°C}$	[V /(1000 r/min)]	Voltage constant
$Kt_{0\ 150\,°C}$	[Nm/A]	Torque constant
L	[mH]	Mutual inductance
$L_{1\sigma}$	[mH]	Stator leakage inductance
$L_{2\sigma}$	[mH]	Rotor leakage inductance
L_N	[mH]	Rated inductance
m	[kg]	Mass
M_0	[Nm]	Stall torque
$M_{0,\,max}$	[Nm]	Max. standstill torque
M_{av}	[Nm]	Average dynamic torque
M_{max}	[Nm]	Max. torque
M_N	[Nm]	Rated torque
n_{eto}	[r/min]	Transition speed
n_k	[r/min]	Speed
n_{max}	[r/min]	Max. speed

n_N	[r/min]	Rated speed
P_N	[kW]	Rated power
Q_E	[J]	Maximum switching energy
R	[Ω]	Insulation resistance
R	[Ω]	Min. insulation resistance
R_1	[Ω]	Stator impedance
R_2	[Ω]	Charging resistor
R_2	[Ω]	Rotor impedance
$R_{UV\ 150\,°C}$	[Ω]	Stator impedance
$R_{UV\ 20\,°C}$	[Ω]	Stator impedance
$S_{hü}$	[1/h]	Transition operating frequency
T	[°C]	Operating temperature
T	[°C]	Rated temperature
T	[°C]	Max. ambient temperature of bearing
T	[°C]	Max. surface temperature
T	[°C]	Max. ambient temperature for transport
T	[°C]	Min. ambient storage temperature
T	[°C]	Min. ambient temperature for transport
T	[°C]	Ambient temperature
t_1	[ms]	Engagement time
t_2	[ms]	Disengagement time
$T_{opr,max}$	[°C]	Max. ambient operating temperature
$T_{opr,min}$	[°C]	Min. ambient operating temperature
$U_{in,max}$	[V]	Max. input voltage
$U_{in,min}$	[V]	Min. input voltage
U_{max}	[V]	Max. mains voltage
U_{max}	[V]	Min. input voltage
U_{min}	[V]	Min. mains voltage
$U_{N,\ AC}$	[V]	Rated voltage
$U_{N,\ DC}$	[V]	Rated voltage
Z_{ro}	[Ω]	Rotor impedance
Z_{rs}	[Ω]	Impedance
Z_{so}	[Ω]	Stator impedance

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MCS synchronous servo motors

General information

List of abbreviations

CE	Communauté Européenne
CSA	Canadian Standards Association
DIN	Deutsches Institut für Normung e.V.
EMC	Electromagnetic compatibility
EN	European standard
EAC	Customs union Russia / Belarus / Kazakhstan certificate
IEC	International Electrotechnical Commission
IM	International Mounting Code
IP	International Protection Code
NEMA	National Electrical Manufacturers Association
UkrSEPRO	Certificate for Ukraine
UL	Underwriters Laboratory Listed Product
UR	Underwriters Laboratory Recognized Product
VDE	Verband deutscher Elektrotechniker (Association of German Electrical Engineers)

Product key

Motor type	Motor size	Rated speed	Mains voltage	Speed/angle sensor	Brake	Standard design	Shaft diameter	Concentricity / vibration level

M C S

Synchronous servo motor

(Example: 14L)

value in 100 rpm (example: 2000 = 20)

400 V **-**

230 V **L**

R S 0 Resolver

S K M SinCos absolute encoder multi-turn, Hiperface, AM128-8V-H (SKM36)

S R S SinCos absolute encoder single-turn, Hiperface, AS1024-8V-H (SRS50)

S R M SinCos absolute encoder multi-turn, Hiperface, AM1024-8V-H (SRM50)

E C N SinCcos absolute encoder single-turn, EnDat, AS2048-5V-E (ECN 1313)

E Q N SinCcos absolute encoder multi-turn, EnDat, AM2048-5V-E (EQN 1325)

E Q I SinCos absolute encoder multi-turn, EnDat, AM32-5V-E (EQI 1331)

C 4 0 TTL incremental encoder with communications signal, IK4096-5V-T (Renco R35i)

R V 0 Safety resolver RV03

S V S Safety SinCos absolute encoder single-turn, Hiperface®, AS1024-8V-K2

S V M Safety SinCos absolute encoder multi-turn, Hiperface®, AM1024-8V-K2

B 0 No brake

P 1 PM brake DC 24V

P 2 PM brake DC 24V, heavy-duty

A Standard flange form A / FF (B5), shaft without keyway

B Standard flange form A / FF (B5), shaft with keyway

(Example: 24)

normal vibrational severity standard bearing **N**

reduced vibrational severity standard bearing **R**

6.6

MCS synchronous servo motors

General information

Product key

| Electrical connection | | Degree of protection | Cooling | | | Load flywheel | Temperature protection | Nameplate | Colour | Specification |

S T — Separate round plugs for power+brake, encoder + thermal sensor

K K — Terminal box for power+brake+encoder + thermal sensor

ST

KK

5 IP54
6 IP65

S 0 0 Natural ventilation, no fan
F 1 0 Forced ventilation with blower 230 V
F 5 0 Forced ventilation with blower 115 V

N Without

R KTY temperature sensor
D KTY temperature sensor + PTC thermistor

0 International
1 International + electronic
2 International + second supplied loose
3 International + electronic + second supplied loose

S Black
X Other colours

U UL / CSA cURus approval

MCS synchronous servo motors

General information

Product information

When space is limited, but strict requirements in terms of dynamics and precision still have to be met, the MCS synchronous servo motors are the right choice.

With a power range from 0.25 kW to 15.8 kW and a rated torque range from 0.5 Nm to 72 Nm and peak torques of up to 190 Nm, these motors leave nothing to be desired in installations requiring compact and dynamic drive technology.
The stator winding of the MCS motors employs innovative Single Element Pole Technology – SEPT – and is made up of individual coils. High-quality magnetic materials and specially developed pole shapes set the conditions for their excellent drive characteristics. This results in a significant increase in power density, while at the same time reducing moments of inertia. The minimum detent torques offer exceptional smooth running characteristics and thereby secure excellent control behaviour.

The robust mechanical structure with reinforced bearings, the high degree of protection and the full stator encapsulation increase operational reliability, even in harsh ambient conditions.

Advantages
- High dynamic performance thanks to low moments of inertia
- Compact size with high power density
- Cooling with or without axial external fan
- Robust regenerative resolver system as standard
- Alternatively sin/cos encoder for the highest precision
- Easy to install and service friendly thanks to use of SpeedTec connectors
- Optional terminal box
- Protection: IP54, IP65 optional
- cURus-approved, GOST-certified, CE, RoHS compliant
- Smooth surface
- Single Element Pole Technology
- Optimum rotation characteristics
- Virtually free of detent torque
- Electronic nameplate

MCS09 synchronous servo motor

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MCS synchronous servo motors

General information

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Functions and features

	MCS06	MCS09	MCS12	MCS14	MCS19
Design					
	B5-FF75	B5-FF100	B5-FF130	B5-FF165	B5-FF215
Shaft end (with and without keyway)					
	11 x 23	14 x 30	19 x 40	24 x 50	28 x 60
A end shield					
	Not oil-tight				
Brake					
Permanent magnetic brake	DC 24 V	DC 24 V 24 V DC, reinforced			
Speed and angle encoder					
	Resolver SinCos single-turn/multi-turn				
Cooling					
Without blower	Naturally ventilated				
Axial blower, 1 phase			230 V; 50 Hz 115 V; 60 Hz		
Thermal sensor					
Thermal detector	KTY				
PTC thermistor		2x PTC additional (3-phase monitoring)			
Motor connection: plug connector					
	Power + brake Encoder + thermal sensor		Power + brake Encoder + thermal sensor Blower		
Motor connection: terminal box					
	Power + brake + encoder + thermal sensor				
Shaft bearings					
Bearing type	Deep-groove ball bearing with high-temperature resistant grease, sealing disc or cover plate				
Position of the locating bearing	Non-drive end				
Colour					
	RAL9005M				

► Terminal boxes not possible if blower is fitted.

Dimensioning

Speed-dependent safety functions

Single encoder concepts with resolvers

Servo motors can perform speed-dependent safety functions for safe speed and / or safe relative position monitoring in a drive system with the Servo Drives 9400. The SM301 safety module, which can be integrated in the Servo Drives 9400, is used to implement these functions. When planning systems/installations of this kind, the following must always be observed:

When using just one single feedback system in the environment of these safety applications, the applicable safety engineering standard IEC 61800-5-2 [Adjustable speed electrical power drive systems - Part: 5-2: Safety requirements - Functional] stipulates special requirements for the connection between feedback system and motor shaft. This is due to the fact that two-channel safety systems at this point in the mechanical system are actually designed as single-channel systems. If this mechanical connection is designed with considerable overdimensioning, the standard permits exclusion of the fault "encoder-shaft breakage" or "encoder-shaft slip".
As such, acceleration limit values must not be exceeded for the individual drive solutions. You can find the limit values in the corresponding feedback data of the individual motor ranges.

Speed-dependent safety functions in connection with the SM301 safety module

For the following speed-dependent safety functions, the motor-feedback system combinations listed in the following table are available:
- Safe stop 1 (SS1)
- Safe operational stop (SOS)
- Safely Limited Speed (SLS)
- Safe Maximum Speed (SMS)

- Safe direction (SDI)
- Operation mode selector (OMS) with confirmation (ES)
- Safe speed monitor (SSM)
- Safely limited increment (SLI).

Encoder type	Encoder type	Product key	Feedback	Safe speed monitoring
			Design	
SinCos absolute value	Single-turn	AS1024-8V-K2		PL d/SIL 2
	Multi-turn	AM1024-8V-K2		
Resolver		RV03		PL e/SIL 3
			2-encoder concept	up to PL e / SIL 3

6.6

MCS synchronous servo motors

General information

Dimensioning

Cooling effect of mounting flange

Mounting on a thermally conducting / insulating plate or machine chassis has an influence on heating up the motor, particularly when using naturally ventilated motors.

The motor rating data specified in the catalogue applies when mounting on a steel plate with free convection with the following dimensions:
- MCS06: 270 x 270 mm
- MCS09: 330 x 330 mm
- MCS12 / 14 / 19: 450 x 450 mm

Vibrational severity

		MCS06	MCS09	MCS12	MCS14	MCS19
Vibrational severity						
IEC/EN 60034-14				A		
Maximum r.m.s. value of the vibration velocity [1]	[mm/s]			1.60		

[1] Free suspension
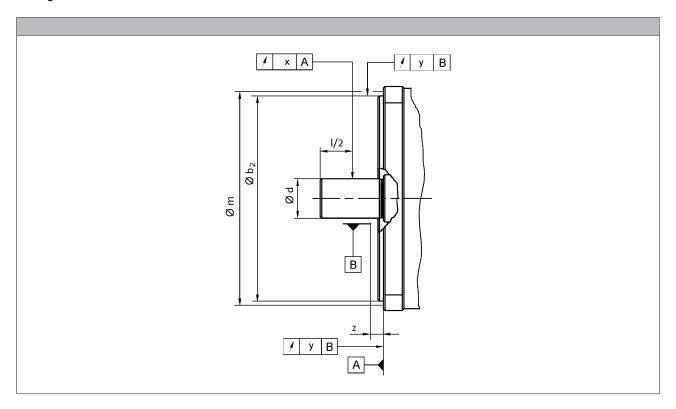
▶ at n = 600 to 3,600 rpm

Dimensioning

Concentricity and axial run-out of the mounting flanges and smooth running of the shaft ends

			MCS06	MCS09	MCS12	MCS14	MCS19
Flange size							
			FF75	FF100	FF130	FF165	FF215
Dimensions							
	b_2	j6	[mm]	60	80	110	130	180
	d	k6	[mm]	11	14	19	24	28
Distance							
Measuring diameter	m		[mm]	65.0	85.0	115	135	185
Dial gauge holder for flange check	z	+/- 1	[mm]			10.0		
Concentricity							
IEC 60072						Normal class		
Value	y		[mm]		0.080		0.10	
Linear movement							
IEC 60072						Normal class		
Value	y		[mm]		0.080		0.10	
Smooth running							
IEC 60072						Normal class		
Value	x		[mm]		0.035		0.040	

► Limit values for checking the smooth running of the shaft ends
as well as the concentricity and axial run-out of the mounting
flange to IEC 60072

6.6

MCS synchronous servo motors

General information

- -

Dimensioning

Notes on the selection tables

Graphical display of the operating points

Please note:
- In case of an active load (e.g. vertical drive axes, hoists, test benches, unwinders), $M_{0\,max}$ has to be considered
- In case of a passive load (e.g. horizontal drive axes), M_{max} can be usually used
- In case of a speed < n_k and inverter-specifically, the achievable torque $M_{0\,max}$ is smaller than M_{max}
- In case of a speed n = 0, the standstill torque M_0 and the standstill current I_0 have to be reduced by 30% after 2 seconds. In case of applications which require a longer holding of M_0, we recommend the drive to be held via the holding brake and reduce the current, e.g. by controller inhibit.
- In case of servo inverters, the switching frequency dependent overload capacity is considered in the default setting. For more information, see the servo inverter catalogue.
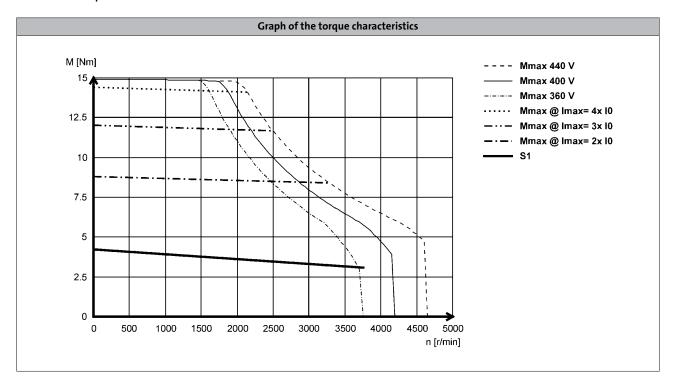
	n_k
	[r/min]
MCS	75.0
MDSKS	100
MDFKS	

Further selection tables with different switching frequencies are available with the following codes:
- DS_ZT_MCS_0001
- DS_ZT_MCA_0001
- DS_ZT_MDSKS_0001
- DS_ZT_MDFKS_0001

Simply enter this code (e.g. DS_ZT_MCS_0001) as a search string at **www.lenze.de/dsc** and you will be given the information immediately in the form of a PDF format.

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MCS synchronous servo motors

General information

Dimensioning

Notes on the torque characteristics

Graph of the torque characteristics

With synchronous servo motors, the limit torque characteristics that result from the selection of servo inverters with maximum currents are also shown alongside the characteristics for continuous operation (S1). These correspond to a multiple of the motor standstill current (2x I0 to 4x I0).

Characteristics in the Internet

You can find the torque characteristic for inverter-motor combinations on the Internet at **www.lenze.de/dsc**. This lists all useful combinations with the servo inverters 9400, 9300, ECS and Inverter Drives 8400 TopLine. These characteristics are each determined using the factory default settings of the inverters:
- 9400 with variables switching frequency.
  This means that up to 6-fold overcurrent can be applied in borderline cases.
- 9300 and ECS with fixed switching frequency.
- 8400 TopLine with variables switching frequency.

The continuous operation characteristics (S1) show the inverter-independent motor rating values

Further information on the terms switching frequency and factory default settings can be found in the operating manual of the respective servo inverter.

MCS synchronous servo motors

General information

Dimensioning

Influence of ambient temperature and site altitude

The information relating to the servo motors in the tables and graphs is valid for a maximum ambient temperature (T_{opr}) of 40 °C and a site altitude (H) up to 1000 m above sea level. The torque correction factor (k_{M1}) shall be applied to the S1 torque characteristic ($M_0...M_N$) in the event of differing installation conditions.

▶ The maximum permissible ambient temperature (T_{opr}) for servo motors with blowers is 40 °C

Torque correction factor k_{m1}

Legend:
- H ≤ 1000 m
- H ≤ 2000 m
- H ≤ 3000 m
- H ≤ 4000 m

Y-axis: k_{M1}
X-axis: T_{opr} [°C]

MCS synchronous servo motors

Technical data

Standards and operating conditions

			MCS	
Cooling type			Naturally ventilated	Blower
Enclosure				
EN 60529			IP54 IP65	IP54
Temperature class				
IEC/EN 60034-1; utilisation			F	
IEC/EN 60034-1; insulation system (enamel-insulated wire)			H	
Conformity				
CE			Low-Voltage Directive	
			2006/95/EC	
EAC			TP TC 004/2011 (TR CU 004/2011)	
Approval				
			UkrSEPRO	
CSA			CSA 22.2 No. 100	
cURus			UL 1004-1 UL 1004-6 Power Conversion Equipment (File-No. E210321)	
Max. voltage load				
IEC/TS 60034-25			Pulse voltage limiting curve A	
Smooth running				
IEC 60072			Normal class	
Linear movement				
IEC 60072			Normal class	
Concentricity				
IEC 60072			Normal class	
Mechanical ambient conditions (vibration)				
IEC/EN 60721-3-3			3M6	
Min. ambient operating temperature				
Without brake	$T_{opr,min}$	[°C]	-20	-15
With brake	$T_{opr,min}$	[°C]	-10	
Max. ambient temperature for operation				
	$T_{opr,max}$	[°C]	40	
Max. surface temperature				
	T	[°C]	140	110
Mechanical tolerance				
Flange centring diameter			$b_2 \leq 230$ mm = j6 $b_2 > 230$ mm = h6	
Shaft diameter			$d \leq 50$ mm = k6 $d > 50$ mm = m6	
Site altitude				
Amsl	H_{max}	[m]	4 000	

6.6

Permissible radial and axial forces

Application of forces

Application of force at l/2

	Bearing service life L_{10}														
	5000 h			10000 h			20000 h			30000 h			50000 h		
	F_{rad}	$F_{ax,-}$	$F_{ax,+}$	F_{rad}	$F_{ax,-}$	$F_{ax,+}$	F_{rad}	$F_{ax,-}$	$F_{ax,+}$	F_{rad}	$F_{ax,-}$	$F_{ax,+}$	F_{rad}	$F_{ax,-}$	$F_{ax,+}$
	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]
MCS06	740	-260	140	590	-210	80	470	-170	40	410	-150	30	340	-140	10
MCS09	1040	-700	470	830	-550	310	660	-440	200	580	-380	150	490	-330	90
MCS12	1030	-880	560	820	-690	370	650	-550	230	570	-490	160	480	-420	100
MCS14	1830	-1150	720	1450	-900	470	1150	-720	290	1010	-640	200	850	-550	120
MCS19	3840	-1550	950	3050	-1210	620	2430	-960	360	2120	-840	250	1790	-730	130

Application of force at l

	Bearing service life L_{10}														
	5000 h			10000 h			20000 h			30000 h			50000 h		
	F_{rad}	$F_{ax,-}$	$F_{ax,+}$	F_{rad}	$F_{ax,-}$	$F_{ax,+}$	F_{rad}	$F_{ax,-}$	$F_{ax,+}$	F_{rad}	$F_{ax,-}$	$F_{ax,+}$	F_{rad}	$F_{ax,-}$	$F_{ax,+}$
	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]
MCS06	630	-210	90	500	-170	50	400	-140	20	350	-130	0	290	-120	-10
MCS09	900	-630	400	710	-500	260	570	-400	160	500	-350	120	420	-300	70
MCS12	890	-820	490	710	-640	320	560	-520	190	490	-460	130	420	-400	70
MCS14	1590	-1040	610	1260	-820	390	1000	-660	230	880	-580	150	740	-510	
MCS19	3330	-1320	730	2650	-1040	450	2100	-830	240	1840	-740	140	1550	-640	40

▶ The values for the bearing service life L_{10} refer to an average speed of 4000 r/min. Depending on the ambient temperatures, the service life of the bearings is also reduced by the grease lifetime.

Rated data, non-ventilated

► The data applies to a mains connection voltage of 3 x 400 V.

	n_N	M_0	M_N	M_{max}	P_N	I_0	I_N	I_{max}	$U_{N, AC}$	f_N
	[r/min]	[Nm]	[Nm]	[Nm]	[kW]	[A]	[A]	[A]	[V]	[Hz]
MCS06C41-	4050	0.80	0.60	2.40	0.25	1.30	1.30	5.40	225	270
MCS06C60-	6000	0.80	0.50	2.40	0.31	2.50	2.40	10.8	135	400
MCS06F41-	4050	1.50	1.20	4.40	0.51	1.50	1.50	5.30	320	270
MCS06F60-	6000	1.50	0.90	4.40	0.57	2.90	2.50	10.5	180	400
MCS06I41-	4050	2.00	1.50	6.20	0.64	1.70	1.60	5.90	325	270
MCS06I60-	6000	2.00	1.20	6.20	0.75	3.40	2.90	11.8	190	400
MCS09D41-	4050	3.30	2.30	9.50	1.00	2.60	2.30	10.0	320	270
MCS09D60-	6000	3.30	1.80	9.50	1.10	5.30	3.80	20.0	210	400
MCS09F38-	3750	4.20	3.10	15.0	1.20	3.00	2.50	15.0	330	250
MCS09F60-	6000	4.20	2.40	15.0	1.50	6.00	4.50	30.0	230	400
MCS09H41-	4050	5.50	3.80	20.0	1.60	4.30	3.40	20.0	300	270
MCS09H60-	6000	5.50	3.00	20.0	1.90	8.50	6.00	40.0	190	400
MCS09L41-	4050	7.50	4.50	32.0	1.90	6.20	4.20	32.0	295	270
MCS09L51-	5100	7.50	3.60	32.0	1.90	12.4	6.90	64.0	180	340

	$\eta_{100\%}$	J [1]	$KE_{LL\,150\,°C}$	$R_{UV\,20\,°C}$	$R_{UV\,150\,°C}$	L_N	$Kt_{0\,150\,°C}$	n_{max} [2]	m [1]
	[%]	[kgcm²]	[V /(1000 r/min)]	[Ω]	[Ω]	[mH]	[Nm/A]	[r/min]	[kg]
MCS06C41-	65.0	0.14	36.6	27.1	36.5	51.0	0.66	8000	1.80
MCS06C60-	70.0	0.14	18.3	6.80	9.10	12.8	0.33	8000	1.80
MCS06F41-	77.0	0.22	60.1	21.9	29.5	63.5	1.05	8000	2.20
MCS06F60-	81.0	0.22	30.0	5.50	7.40	15.9	0.53	8000	2.20
MCS06I41-	81.0	0.30	73.4	18.8	25.4	60.2	1.21	8000	2.90
MCS06I60-	84.0	0.30	36.7	4.70	6.30	15.1	0.60	8000	2.90
MCS09D41-	87.0	1.10	71.2	7.00	9.40	25.1	1.25	7000	4.30
MCS09D60-	87.0	1.10	35.6	1.80	2.40	6.30	0.62	7000	4.30
MCS09F38-	91.0	1.50	79.8	5.20	7.00	24.6	1.40	7000	5.20
MCS09F60-	91.0	1.50	39.9	1.30	1.80	6.20	0.70	7000	5.20
MCS09H41-	91.0	1.90	75.7	3.20	4.30	16.1	1.29	7000	6.10
MCS09H60-	91.0	1.90	37.8	0.80	1.10	4.00	0.65	7000	6.10
MCS09L41-	91.0	2.80	71.7	1.80	2.40	9.90	1.21	7000	7.90
MCS09L51-	91.0	2.80	35.9	0.44	0.59	2.50	0.60	7000	7.90

[1] Without brake.
[2] Mechanically permissible maximum speed.

6.6

MCS synchronous servo motors

Technical data

Rated data, non-ventilated

► The data applies to a mains connection voltage of 3 x 400 V.

	n_N	M_0	M_N	M_{max}	P_N	I_0	I_N	I_{max}	$U_{N, AC}$	f_N
	[r/min]	[Nm]	[Nm]	[Nm]	[kW]	[A]	[A]	[A]	[V]	[Hz]
MCS12D20-	1950	6.40	5.50	18.0	1.10	2.70	2.60	10.0	345	130
MCS12D41-	4050	6.40	4.30	18.0	1.80	5.50	4.50	20.0	310	270
MCS12H15-	1500	11.4	10.0	29.0	1.60	4.10	3.80	12.0	300	100
MCS12H35-	3525	11.4	7.50	29.0	2.80	8.20	5.70	24.0	325	235
MCS12L20-	1950	15.0	13.5	56.0	2.80	6.20	5.90	28.0	330	130
MCS12L41-	4050	15.0	11.0	56.0	4.70	12.4	10.2	57.0	300	270
MCS14D15-	1500	11.0	9.20	29.0	1.45	5.00	4.50	17.0	305	100
MCS14D36-	3600	11.0	7.50	29.0	2.80	10.0	7.50	33.0	295	240
MCS14H15-	1500	21.0	16.0	55.0	2.50	8.50	6.60	26.0	325	100
MCS14H32-	3225	21.0	14.0	55.0	4.70	16.9	11.9	52.0	295	215
MCS14L15-	1500	28.0	23.0	77.0	3.60	12.0	9.70	37.0	315	100
MCS14L32-	3225	28.0	17.2	77.0	5.80	24.0	15.0	75.0	275	215
MCS14P14-	1350	37.0	30.0	105	4.20	12.2	10.8	46.0	340	90
MCS14P32-	3225	37.0	21.0	105	7.10	24.3	15.6	92.0	315	215

	$\eta_{100\%}$	J [1]	$KE_{LL\,150\,°C}$	$R_{UV\,20\,°C}$	$R_{UV\,150\,°C}$	L_N	$Kt_{0\,150\,°C}$	n_{max} [2]	m [1]
	[%]	[kgcm²]	[V /(1000 r/min)]	[Ω]	[Ω]	[mH]	[Nm/A]	[r/min]	[kg]
MCS12D20-	79.0	4.00	137	8.70	11.8	52.2	2.34	6000	6.40
MCS12D41-	84.0	4.00	68.6	2.20	2.90	13.0	1.17	6000	6.40
MCS12H15-	88.0	7.30	173	5.70	7.70	42.1	2.79	6000	9.50
MCS12H35-	91.0	7.30	86.5	1.40	1.90	10.5	1.40	6000	9.50
MCS12L20-	90.0	10.6	149	2.20	3.00	21.8	2.42	6000	12.6
MCS12L41-	91.0	10.6	74.6	0.55	0.75	5.50	1.21	6000	12.6
MCS14D15-	88.0	8.10	129	4.00	5.40	49.8	2.19	6000	10.7
MCS14D36-	92.0	8.10	64.2	1.00	1.35	12.5	1.09	6000	10.7
MCS14H15-	92.0	14.2	153	2.08	2.81	34.1	2.48	6000	15.5
MCS14H32-	93.0	14.2	76.3	0.52	0.70	8.50	1.24	6000	15.5
MCS14L15-	90.0	23.4	152	1.21	1.64	22.0	2.33	6000	20.1
MCS14L32-	93.0	23.4	76.2	0.30	0.41	5.50	1.16	6000	20.1
MCS14P14-	90.0	34.7	179	1.10	1.49	23.9	3.04	6000	24.9
MCS14P32-	93.0	34.7	89.4	0.28	0.37	6.00	1.52	6000	24.9

[1] Without brake.
[2] Mechanically permissible maximum speed.

Rated data, non-ventilated

► The data applies to a mains connection voltage of 3 x 400 V.

	n_N	M_0	M_N	M_{max}	P_N	I_0	I_N	I_{max}	$U_{N, AC}$	f_N
	[r/min]	[Nm]	[Nm]	[Nm]	[kW]	[A]	[A]	[A]	[V]	[Hz]
MCS19F14-	1425	32.0	27.0	86.0	4.00	9.90	8.60	31.0	335	95
MCS19F30-	3000	32.0	21.0	86.0	6.60	19.8	14.0	63.0	300	200
MCS19J14-	1425	51.0	40.0	129	6.00	15.2	12.3	45.0	330	95
MCS19J30-	3000	51.0	29.0	129	9.10	30.5	18.5	90.0	300	200
MCS19P14-	1350	64.0	51.0	190	7.20	17.5	14.3	60.0	330	90
MCS19P30-	3000	64.0	32.0	190	10.0	34.9	19.0	120	320	200

	$\eta_{100\%}$	J [1]	$KE_{LL\,150\,°C}$	$R_{UV\,20\,°C}$	$R_{UV\,150\,°C}$	L_N	$Kt_{0\,150\,°C}$	n_{max} [2]	m [1]
	[%]	[kgcm²]	[V /(1000 r/min)]	[Ω]	[Ω]	[mH]	[Nm/A]	[r/min]	[kg]
MCS19F14-	92.0	65.0	195	1.30	1.75	20.8	3.23	4000	23.0
MCS19F30-	93.0	65.0	97.2	0.32	0.44	5.20	1.62	4000	23.0
MCS19J14-	92.0	105	199	0.65	0.88	12.8	3.31	4000	30.0
MCS19J30-	93.0	105	99.5	0.16	0.22	3.20	1.65	4000	30.0
MCS19P14-	92.0	160	216	0.54	0.73	9.60	3.66	4000	40.0
MCS19P30-	93.0	160	108	0.14	0.18	2.40	1.83	4000	40.0

[1] Without brake.
[2] Mechanically permissible maximum speed.

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Rated data, non-ventilated

► The data applies to a mains connection voltage of 3 x 230 V.

	n_N	M_0	M_N	M_{max}	P_N	I_0	I_N	I_{max}	$U_{N, AC}$	f_N
	[r/min]	[Nm]	[Nm]	[Nm]	[kW]	[A]	[A]	[A]	[V]	[Hz]
MCS06C41L	4050	0.80	0.60	2.40	0.25	2.50	2.50	10.8	125	270
MCS06C60L	6000	0.80	0.50	2.40	0.31	4.30	4.00	18.5	85	400
MCS06F41L	4050	1.50	1.20	4.40	0.51	2.90	2.90	10.5	165	270
MCS06F60L	6000	1.50	0.90	4.40	0.57	3.80	3.40	16.5	125	400
MCS06I41L	4050	2.00	1.50	6.20	0.64	3.10	2.90	11.8	175	270
MCS06I60L	6000	2.00	1.20	6.20	0.75	4.20	3.60	16.0	150	400
MCS09D41L	4050	3.30	2.30	9.50	1.00	5.30	4.60	20.0	165	270
MCS09D60L	6000	3.30	1.80	9.50	1.10	10.3	7.00	39.0	110	400
MCS09F38L	3750	4.20	3.10	15.0	1.20	6.00	5.00	30.0	160	250
MCS09F60L	6000	4.20	2.40	15.0	1.50	10.5	7.90	53.0	125	400
MCS09H41L	4050	5.50	3.80	20.0	1.60	8.50	6.80	40.0	160	270
MCS09H60L	6000	5.50	3.00	20.0	1.90	12.0	8.00	57.0	145	400
MCS09L41L	4050	7.50	4.50	32.0	1.90	12.4	8.40	64.0	145	270

	$\eta_{100\%}$	J [1]	$KE_{LL\,150°C}$	$R_{UV\,20°C}$	$R_{UV\,150°C}$	L_N	$Kt_{0\,150°C}$	n_{max} [2]	m [1]
	[%]	[kgcm²]	[V /(1000 r/min)]	[Ω]	[Ω]	[mH]	[Nm/A]	[r/min]	[kg]
MCS06C41L	65.0	0.14	21.5	6.00	8.00	12.8	0.33	8000	1.80
MCS06C60L	70.0	0.14	12.5	2.20	2.90	4.30	0.19	8000	1.80
MCS06F41L	81.0	0.22	34.5	5.50	7.40	15.9	0.62	8000	2.20
MCS06F60L	82.0	0.22	22.2	2.30	3.00	6.90	0.40	8000	2.20
MCS06I41L	81.0	0.30	38.0	4.70	6.20	15.1	0.64	8000	2.90
MCS06I60L	84.0	0.30	28.5	2.50	3.40	9.30	0.48	8000	2.90
MCS09D41L	87.0	1.10	35.6	1.80	2.40	6.30	0.62	7000	4.30
MCS09D60L	87.0	1.10	18.3	0.45	0.61	1.70	0.32	7000	4.30
MCS09F38L	90.0	1.50	39.9	1.30	1.80	6.20	0.70	7000	5.20
MCS09F60L	91.0	1.50	22.8	0.42	0.56	2.00	0.40	7000	5.20
MCS09H41L	91.0	1.90	37.8	0.80	1.10	4.00	0.65	7000	6.10
MCS09H60L	91.0	1.90	26.6	0.36	0.48	2.00	0.46	7000	6.10
MCS09L41L	91.0	2.80	35.9	0.44	0.59	2.50	0.60	7000	7.90

[1] Without brake.
[2] Mechanically permissible maximum speed.

MCS synchronous servo motors

Technical data

Rated data, non-ventilated

► The data applies to a mains connection voltage of 3 x 230 V.

	n_N	M_0	M_N	M_{max}	P_N	I_0	I_N	I_{max}	$U_{N, AC}$	f_N
	[r/min]	[Nm]	[Nm]	[Nm]	[kW]	[A]	[A]	[A]	[V]	[Hz]
MCS12D20L	1950	6.40	5.50	18.0	1.10	5.50	5.20	20.0	175	130
MCS12D41L	4050	6.40	4.30	18.0	1.80	10.7	8.80	40.0	155	270
MCS12H15L	1500	11.4	10.0	29.0	1.60	8.20	7.80	24.0	158	100
MCS12H30L	3000	11.4	8.00	29.0	2.50	13.5	10.5	39.0	165	200
MCS12L20L	1950	15.0	13.5	56.0	2.80	12.4	11.8	57.0	165	130

	$\eta_{100\%}$	J [1]	$KE_{LL\,150\,°C}$	$R_{UV\,20\,°C}$	$R_{UV\,150\,°C}$	L_N	$Kt_{0\,150\,°C}$	n_{max} [2]	m [1]
	[%]	[kgcm²]	[V /(1000 r/min)]	[Ω]	[Ω]	[mH]	[Nm/A]	[r/min]	[kg]
MCS12D20L	79.0	4.00	68.6	2.20	2.90	13.0	1.17	6 000	6.40
MCS12D41L	84.0	4.00	35.0	0.55	0.75	3.40	0.60	6 000	6.40
MCS12H15L	82.0	7.30	86.5	1.41	1.90	10.5	1.40	6 000	9.50
MCS12H30L	87.0	7.30	53.0	0.50	0.67	4.00	0.86	6 000	9.50
MCS12L20L	90.0	10.6	76.9	0.55	0.75	5.50	1.21	6 000	12.6

[1] Without brake.
[2] Mechanically permissible maximum speed.

Rated data, forced ventilated

► The data applies to a mains connection voltage of 3 x 400 V.

	n_N	M_0	M_N	M_{max}	P_N	I_0	I_N	I_{max}	$U_{N, AC}$	f_N
	[r/min]	[Nm]	[Nm]	[Nm]	[kW]	[A]	[A]	[A]	[V]	[Hz]
MCS12D17-	1650	7.50	7.00	17.7	1.20	3.20	3.00	10.0	330	110
MCS12D35-	3525	7.50	6.00	17.7	2.20	6.40	5.60	20.0	300	235
MCS12H14-	1350	12.8	12.0	29.0	1.70	4.30	4.10	12.0	310	90
MCS12H34-	3375	12.8	10.5	29.0	3.70	8.50	7.50	24.0	320	225
MCS12L17-	1650	19.0	17.0	56.4	2.90	7.20	6.70	28.0	300	110
MCS12L39-	3900	19.0	14.0	56.4	5.70	14.4	11.7	57.0	295	260
MCS14D14-	1350	12.5	12.0	29.0	1.70	5.70	5.40	17.0	345	90
MCS14D30-	3000	12.5	10.5	29.0	3.30	11.4	9.70	33.0	325	200
MCS14H12-	1200	25.5	23.5	54.8	3.00	9.30	8.30	26.0	335	80
MCS14H28-	2775	25.5	20.5	54.8	6.00	18.4	15.0	52.0	325	185
MCS14L14-	1350	34.5	30.5	77.1	4.30	13.4	11.8	37.0	335	90
MCS14L30-	3000	34.5	25.5	77.1	8.00	26.7	20.8	75.0	310	200
MCS14P11-	1050	43.5	42.0	105	4.60	14.1	13.4	46.0	330	70
MCS14P26-	2625	43.5	33.0	105	9.10	28.3	21.9	92.0	325	175

	$\eta_{100\%}$	J [1]	$KE_{LL\,150\,°C}$	$R_{UV\,20\,°C}$	$R_{UV\,150\,°C}$	L_N	$Kt_{0\,150\,°C}$	n_{max} [2]	m [1]
	[%]	[kgcm²]	[V /(1000 r/min)]	[Ω]	[Ω]	[mH]	[Nm/A]	[r/min]	[kg]
MCS12D17-	75.0	4.00	137	8.72	11.8	52.2	2.34	6000	8.50
MCS12D35-	82.0	4.00	68.6	2.18	2.94	13.0	1.17	6000	8.50
MCS12H14-	80.0	7.30	173	5.72	7.72	42.1	2.98	6000	11.6
MCS12H34-	86.0	7.30	86.5	1.39	1.88	10.5	1.51	6000	11.6
MCS12L17-	90.0	10.6	149	2.22	2.99	21.8	2.64	6000	14.7
MCS12L39-	94.0	10.6	74.6	0.55	0.75	5.50	1.32	6000	14.7
MCS14D14-	84.0	8.10	129	4.00	5.40	49.8	2.19	6000	14.5
MCS14D30-	92.0	8.10	64.2	1.00	1.35	12.5	1.09	6000	14.5
MCS14H12-	87.0	14.2	153	2.08	2.81	34.1	2.75	6000	19.5
MCS14H28-	93.0	14.2	76.3	0.52	0.70	8.50	1.39	6000	19.5
MCS14L14-	88.0	23.4	152	1.21	1.64	22.0	2.57	6000	24.0
MCS14L30-	92.0	23.4	76.2	0.30	0.41	5.50	1.29	6000	24.0
MCS14P11-	86.0	34.7	179	1.10	1.49	23.9	3.08	6000	29.0
MCS14P26-	92.0	34.7	89.4	0.28	0.37	6.00	1.54	6000	29.0

[1] Without brake.
[2] Mechanically permissible maximum speed.

6.6

MCS synchronous servo motors

Technical data

Rated data, forced ventilated

► The data applies to a mains connection voltage of 3 x 400 V.

	n_N	M_0	M_N	M_{max}	P_N	I_0	I_N	I_{max}	$U_{N, AC}$	f_N
	[r/min]	[Nm]	[Nm]	[Nm]	[kW]	[A]	[A]	[A]	[V]	[Hz]
MCS19F12-	1200	41.5	38.0	86.0	4.80	12.2	11.3	31.0	320	80
MCS19F29-	2850	41.5	32.5	86.0	9.70	24.5	20.1	63.0	320	190
MCS19J12-	1200	70.5	62.5	129	7.90	20.3	18.3	45.0	320	80
MCS19J29-	2850	70.5	50.5	129	15.1	40.6	31.0	90.0	315	190
MCS19P12-	1200	86.0	72.0	190	9.00	22.4	21.3	60.0	310	80
MCS19P29-	2850	86.0	53.0	190	15.8	44.7	29.5	120	315	190

	$\eta_{100\%}$	J [1]	$KE_{LL\,150\,°C}$	$R_{UV\,20\,°C}$	$R_{UV\,150\,°C}$	L_N	$Kt_{0\,150\,°C}$	n_{max} [2]	m [1]
	[%]	[kgcm²]	[V /(1000 r/min)]	[Ω]	[Ω]	[mH]	[Nm/A]	[r/min]	[kg]
MCS19F12-	90.4	65.0	195	1.30	1.75	20.8	3.40	4000	29.0
MCS19F29-	94.7	65.0	97.2	0.32	0.44	5.20	1.69	4000	29.0
MCS19J12-	89.3	105	199	0.65	0.88	12.8	3.47	4000	36.0
MCS19J29-	92.8	105	99.5	0.16	0.22	3.20	1.74	4000	36.0
MCS19P12-	90.3	160	216	0.54	0.73	9.60	3.84	4000	46.0
MCS19P29-	93.4	160	108	0.14	0.18	2.40	1.92	4000	46.0

[1] Without brake.
[2] Mechanically permissible maximum speed.

6.6

Technical data

Selection tables, Servo Drives 9400 HighLine

Non-ventilated motors

► The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 4 kHz.

					E94A□□	E0024	E0034	E0044	E0074	E0094	E0134	E0174	E0244	E0324	E0474	E0594
					I_N	1.9	3.1	5.0	8.8	11.7	16.3	20.6	29.4	38.4	47.0	59.0
					$I_{0,max}$	6.0	10.0	16.0	21.0	28.0	39.0	49.5	58.8	76.8	94.0	118.0
MCS	M_N	n_N	I_N	P_N	I_{max}	6.0	10.0	16.0	21.0	28.0	39.0	49.5	58.8	76.8	94.0	118.0
06C41-	0.6	4050	1.3	0.25	M_0	0.8										
					M_N	0.6										
					$M_{0,max}$	2.4										
					M_{max}	2.4										
					n_{eto}	-										
06C60-	0.5	6000	2.4	0.31	M_0	0.6	0.8									
					M_N	0.4	0.5									
					$M_{0,max}$	1.5	2.3									
					M_{max}	1.5	2.3									
					n_{eto}	-	-									
06F41-	1.2	4050	1.5	0.51	M_0	1.5										
					M_N	1.2										
					$M_{0,max}$	4.4										
					M_{max}	4.4										
					n_{eto}	-										
06F60-	0.9	6000	2.5	0.57	M_0	1.0	1.5									
					M_N	0.7	0.9									
					$M_{0,max}$	3.0	4.3									
					M_{max}	3.0	4.3									
					n_{eto}	-	-									
06I41-	1.5	4050	1.6	0.64	M_0	2.0										
					M_N	1.5										
					$M_{0,max}$	6.2										
					M_{max}	6.2										
					n_{eto}	-										
06I60-	1.2	6000	2.9	0.75	M_0	1.1	1.8	2.0								
					M_N	0.8	1.2	1.2								
					$M_{0,max}$	3.3	5.5	6.2								
					M_{max}	3.3	5.5	6.2								
					n_{eto}	-	-	-								
09D41-	2.3	4050	2.3	1.00	M_0	2.4	3.3									
					M_N	1.9	2.3									
					$M_{0,max}$	6.3	9.5									
					M_{max}	6.3	9.5									
					n_{eto}	-	-									
09D60-	1.8	6000	3.8	1.10	M_0			3.1	3.3							
					M_N			1.8	1.8							
					$M_{0,max}$			8.0	9.5							
					M_{max}			8.0	9.5							
					n_{eto}			-	-							
09F38-	3.1	3750	2.5	1.20	M_0		4.2	4.2								
					M_N		3.1	3.1								
					$M_{0,max}$		11.6	14.9								
					M_{max}		11.6	14.9								
					n_{eto}		-	-								

► I... [A], M... [Nm], n... [r/min], P... [kW]

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Selection tables, Servo Drives 9400 HighLine

Non-ventilated motors

► The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 4 kHz.

MCS	M_N	n_N	I_N	P_N	E94A□□	E0024	E0034	E0044	E0074	E0094	E0134	E0174	E0244	E0324	E0474	E0594
					I_N	1.9	3.1	5.0	8.8	11.7	16.3	20.6	29.4	38.4	47.0	59.0
					$I_{0,max}$	6.0	10.0	16.0	21.0	28.0	39.0	49.5	58.8	76.8	94.0	118.0
					I_{max}	6.0	10.0	16.0	21.0	28.0	39.0	49.5	58.8	76.8	94.0	118.0
09F60-	2.4	6000	4.5	1.50	M_0			3.5	4.2	4.2	4.2					
					M_N			2.4	2.4	2.4	2.4					
					$M_{0,max}$			9.8	12.0	14.4	14.9					
					M_{max}			9.8	12.0	14.4	14.9					
					n_{eto}			-	-	-	-					
09H41-	3.8	4050	3.4	1.60	M_0		4.0	5.5	5.5							
					M_N		3.5	3.8	3.8							
					$M_{0,max}$		12.0	17.5	20.4							
					M_{max}		12.0	17.5	20.4							
					n_{eto}		-	-	-							
09H60-	3.0	6000	6.0	1.90	M_0				5.5	5.5	5.5	5.5				
					M_N				3.0	3.0	3.0	3.0				
					$M_{0,max}$				12.5	15.8	20.1	20.4				
					M_{max}				12.5	15.8	20.1	20.4				
					n_{eto}				-	-	-	-				
09L41-	4.5	4050	4.2	1.90	M_0			6.0	7.5	7.5						
					M_N			4.5	4.5	4.5						
					$M_{0,max}$			17.4	22.2	28.5						
					M_{max}			17.4	22.2	28.5						
					n_{eto}			-	-	-						
09L51-	3.6	5100	6.9	1.90	M_0				5.3	7.0	7.5	7.5	7.5			
					M_N				3.6	3.6	3.6	3.6	3.6			
					$M_{0,max}$				11.9	15.5	20.9	25.8	29.7			
					M_{max}				11.9	15.5	20.9	25.8	29.7			
					n_{eto}				-	-	-	-	-			
12D20-	5.5	1950	2.6	1.10	M_0	4.4	6.4									
					M_N	4.0	5.5									
					$M_{0,max}$	11.8	17.7									
					M_{max}	11.8	17.7									
					n_{eto}	-	-									
12D41-	4.3	4050	4.5	1.80	M_0			5.9	6.4							
					M_N			4.3	4.3							
					$M_{0,max}$			14.7	17.7							
					M_{max}			14.7	17.7							
					n_{eto}			-	-							
12H15-	10.0	1500	3.8	1.60	M_0		8.7	11.4								
					M_N		8.2	10.0								
					$M_{0,max}$		24.6	29.0								
					M_{max}		24.6	29.0								
					n_{eto}		-	-								
12H35-	7.5	3525	5.7	2.80	M_0			7.0	11.4	11.4	11.4					
					M_N			6.6	7.5	7.5	7.5					
					$M_{0,max}$			20.1	25.8	29.0	29.0					
					M_{max}			20.1	25.8	29.0	29.0					
					n_{eto}			-	-	-	-					

► I... [A], M... [Nm], n... [r/min], P... [kW]

6.6

Selection tables, Servo Drives 9400 HighLine

Non-ventilated motors

► The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 4 kHz.

E94A□□				E0024	E0034	E0044	E0074	E0094	E0134	E0174	E0244	E0324	E0474	E0594
I_N				1.9	3.1	5.0	8.8	11.7	16.3	20.6	29.4	38.4	47.0	59.0
$I_{0,max}$				6.0	10.0	16.0	21.0	28.0	39.0	49.5	58.8	76.8	94.0	118.0

MCS	M_N	n_N	I_N	P_N	I_{max}	E0024 (6.0)	E0034 (10.0)	E0044 (16.0)	E0074 (21.0)	E0094 (28.0)	E0134 (39.0)	E0174 (49.5)	E0244 (58.8)	E0324 (76.8)	E0474 (94.0)	E0594 (118.0)
12L20-	13.5	1950	5.9	2.80	M_0			12.1	15.0	15.0	15.0					
					M_N			11.4	13.5	13.5	13.5					
					$M_{0,max}$			35.5	44.6	55.7	56.4					
					M_{max}			35.5	44.6	55.7	56.4					
					n_{eto}			-	-	-	-					
12L41-	11.0	4050	10.2	4.70	M_0				10.6	14.0	15.0	15.0	15.0			
					M_N				9.5	11.0	11.0	11.0	11.0			
					$M_{0,max}$				24.4	31.6	41.9	50.8	56.4			
					M_{max}				24.4	31.6	41.9	50.8	56.4			
					n_{eto}				-	-	-	-	-			
14D15-	9.2	1500	4.5	1.45	M_0			11.0	11.0							
					M_N			9.2	9.2							
					$M_{0,max}$			28.3	29.0							
					M_{max}			28.3	29.0							
					n_{eto}			-								
14D36-	7.5	3600	7.5	2.80	M_0				9.6	11.0	11.0					
					M_N				7.5	7.5	7.5					
					$M_{0,max}$				20.2	25.6	29.0					
					M_{max}				20.2	25.6	29.0					
					n_{eto}				-	-	-					
14H15-	16.0	1500	6.6	2.50	M_0			12.4	21.0	21.0	21.0					
					M_N			12.1	16.0	16.0	16.0					
					$M_{0,max}$			37.1	46.6	54.8	54.8					
					M_{max}			37.1	46.6	54.8	54.8					
					n_{eto}			-	-	-	-					
14H32-	14.0	3225	11.9	4.70	M_0					14.4	20.3	21.0	21.0			
					M_N					13.6	14.0	14.0	14.0			
					$M_{0,max}$					33.0	43.9	53.2	54.8			
					M_{max}					33.0	43.9	53.2	54.8			
					n_{eto}					-	-	-	-			
14L15-	23.0	1500	9.7	3.60	M_0				20.5	27.1	28.0					
					M_N				20.9	23.0	23.0					
					$M_{0,max}$				48.0	61.4	77.1					
					M_{max}				48.0	61.4	77.1					
					n_{eto}				-	-	-					
14L32-	17.2	3225	15.0	5.80	M_0						19.0	24.0	28.0	28.0	28.0	
					M_N						17.2	17.2	17.2	17.2	17.2	
					$M_{0,max}$						45.0	55.3	63.9	77.1	77.1	
					M_{max}						45.0	55.3	63.9	77.1	77.1	
					n_{eto}						-	-	-	-	-	
14P14-	30.0	1350	10.8	4.20	M_0				26.7	35.2	37.0	37.0				
					M_N				24.4	30.0	30.0	30.0				
					$M_{0,max}$				56.1	71.7	93.3	105.1				
					M_{max}				56.1	71.7	93.3	105.1				
					n_{eto}				-	-	-	-				

► I... [A], M... [Nm], n... [r/min], P... [kW]

6.6

Selection tables, Servo Drives 9400 HighLine

Non-ventilated motors

► The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 4 kHz.

					E94A□□	E0024	E0034	E0044	E0074	E0094	E0134	E0174	E0244	E0324	E0474	E0594
					I_N	1.9	3.1	5.0	8.8	11.7	16.3	20.6	29.4	38.4	47.0	59.0
					$I_{0,max}$	6.0	10.0	16.0	21.0	28.0	39.0	49.5	58.8	76.8	94.0	118.0
MCS	M_N	n_N	I_N	P_N	I_{max}	6.0	10.0	16.0	21.0	28.0	39.0	49.5	58.8	76.8	94.0	118.0
14P32-	21.0	3225	15.6	7.10	M_0						24.8	31.4	37.0	37.0	37.0	
					M_N						21.0	21.0	21.0	21.0	21.0	
					$M_{0,max}$						52.5	64.6	74.7	92.2	105.1	
					M_{max}						52.5	64.6	74.7	92.2	105.1	
					n_{eto}						-	-	-	-	-	
19F14-	27.0	1425	8.6	4.00	M_0				28.4	32.0	32.0					
					M_N				27.0	27.0	27.0					
					$M_{0,max}$				62.1	78.9	86.0					
					M_{max}				62.1	78.9	86.0					
					n_{eto}				-	-	-					
19F30-	21.0	3000	14.0	6.60	M_0						26.3	32.0	32.0	32.0		
					M_N						21.0	21.0	21.0	21.0		
					$M_{0,max}$						56.6	70.2	81.6	86.0		
					M_{max}						56.6	70.2	81.6	86.0		
					n_{eto}						-	-	-	-		
19J14-	40.0	1425	12.3	6.00	M_0					38.9	51.0	51.0				
					M_N					37.7	40.0	40.0				
					$M_{0,max}$					85.0	114.4	129.0				
					M_{max}					85.0	114.4	129.0				
					n_{eto}					-	-	-				
19J30-	29.0	3000	18.5	9.10	M_0						27.3	34.4	49.2	51.0	51.0	
					M_N						25.6	29.0	29.0	29.0	29.0	
					$M_{0,max}$						60.8	75.9	88.9	112.9	129.0	
					M_{max}						60.8	75.9	88.9	112.9	129.0	
					n_{eto}						-	-	-	-	-	
19P14-	51.0	1350	14.3	7.20	M_0						59.6	64.0	64.0	64.0		
					M_N						51.0	51.0	51.0	51.0		
					$M_{0,max}$						128.4	159.9	186.6	190.0		
					M_{max}						128.4	159.9	186.6	190.0		
					n_{eto}						-	-	-	-		
19P30-	32.0	3000	19.0	10.00	M_0						29.9	37.8	53.9	64.0	64.0	64.0
					M_N						27.5	32.0	32.0	32.0	32.0	32.0
					$M_{0,max}$						65.7	83.6	98.5	126.6	152.5	187.2
					M_{max}						65.7	83.6	98.5	126.6	152.5	187.2
					n_{eto}						-	-	-	-	-	-

► I... [A], M... [Nm], n... [r/min], P... [kW]

Selection tables, Servo Drives 9400 HighLine

Non-ventilated motors

► The data applies to a mains connection voltage of 3x230V and an inverter switching frequency of 4 kHz.

MCS	M_N	n_N	I_N	P_N	E94A□□	E0024	E0034	E0044	E0074	E0094	E0134	E0174	E0244	E0324
					I_N	1.9	3.1	5.0	8.8	11.7	16.3	20.6	29.4	38.4
					$I_{0,max}$	6.0	10.0	16.0	21.0	28.0	39.0	49.5	58.8	76.8
					I_{max}	6.0	10.0	16.0	21.0	28.0	39.0	49.5	58.8	76.8
06C41L	0.6	4050	2.6	0.25	M_0	0.6	0.8							
					M_N	0.5	0.6							
					$M_{0,max}$	1.5	2.3							
					M_{max}	1.5	2.3							
					n_{eto}	-	-							
06C60L	0.5	6000	4.0	0.31	M_0		0.6	0.8	0.8					
					M_N		0.4	0.5	0.5					
					$M_{0,max}$		1.5	2.2	2.4					
					M_{max}		1.5	2.2	2.4					
					n_{eto}		-	-	-					
06F41L	1.2	4050	2.9	0.51	M_0	1.0	1.5	1.5						
					M_N	0.8	1.2	1.2						
					$M_{0,max}$	2.7	4.2	4.4						
					M_{max}	2.7	4.2	4.4						
					n_{eto}	-	-	-						
06F60L	0.9	6000	3.8	0.57	M_0		1.2	1.5	1.5					
					M_N		0.8	0.9	0.9					
					$M_{0,max}$		3.1	4.3	4.4					
					M_{max}		3.1	4.3	4.4					
					n_{eto}		-	-	-					
06I41L	1.5	4050	3.2	0.64	M_0		2.0	2.0						
					M_N		1.5	1.5						
					$M_{0,max}$		5.4	6.2						
					M_{max}		5.4	6.2						
					n_{eto}		-	-						
06I60L	1.2	6000	3.8	0.75	M_0		1.5	2.0						
					M_N		1.0	1.2						
					$M_{0,max}$		4.4	6.2						
					M_{max}		4.4	6.2						
					n_{eto}		-	-						
09D41L	2.3	4050	4.6	1.00	M_0			3.1	3.3					
					M_N			2.3	2.3					
					$M_{0,max}$			8.0	9.5					
					M_{max}			8.0	9.5					
					n_{eto}			-	-					
09D60L	1.8	6000	7.0	1.10	M_0				2.8	3.3	3.3			
					M_N				1.8	1.8	1.8			
					$M_{0,max}$				5.7	7.3	9.5			
					M_{max}				5.7	7.3	9.5			
					n_{eto}				-	-	-			
09F38L	3.1	3750	5.0	1.20	M_0			3.5	4.2	4.2	4.2			
					M_N			3.1	3.1	3.1	3.1			
					$M_{0,max}$			9.8	12.0	13.8	15.0			
					M_{max}			9.8	12.0	13.8	15.0			
					n_{eto}			-	-	-	-			

► I... [A], M... [Nm], n... [r/min], P... [kW]

6.6

MCS synchronous servo motors

Technical data

Selection tables, Servo Drives 9400 HighLine

Non-ventilated motors

► The data applies to a mains connection voltage of 3x230V and an inverter switching frequency of 4 kHz.

				E94A□□	E0024	E0034	E0044	E0074	E0094	E0134	E0174	E0244	E0324
				I_N	1.9	3.1	5.0	8.8	11.7	16.3	20.6	29.4	38.4
				$I_{0,max}$	6.0	10.0	16.0	21.0	28.0	39.0	49.5	58.8	76.8
MCS	M_N	n_N	I_N	P_N	I_{max}								
				6.0	10.0	16.0	21.0	28.0	39.0	49.5	58.8	76.8
09F60L	2.4	6000	7.9	1.50	M_0				3.5	4.2	4.2	4.2	4.2	
					M_N				2.4	2.4	2.4	2.4	2.4	
					$M_{0,max}$				7.8	9.8	12.6	14.5	15.0	
					M_{max}				7.8	9.8	12.6	14.5	15.0	
					n_{eto}				-	-	-	-	-	
09H41L	3.8	4050	6.8	1.60	M_0				5.5	5.3	5.5	5.5		
					M_N				3.8	3.0	3.8	3.8		
					$M_{0,max}$				12.4	11.8	19.7	20.0		
					M_{max}				12.4	11.8	19.7	20.0		
					n_{eto}				-	-	-	-		
09H60L	3.0	6000	8.0	1.90	M_0				4.0	5.5	5.5	5.5	5.5	
					M_N				3.0	3.8	3.0	3.0	3.0	
					$M_{0,max}$				9.2	15.6	15.4	18.3	20.0	
					M_{max}				9.2	15.6	15.4	18.3	20.0	
					n_{eto}				-	-	-	-	-	
09L41L	4.5	4050	8.4	1.90	M_0				5.3	7.0	7.5	7.5	7.5	7.5
					M_N				4.5	4.5	4.5	4.5	4.5	4.5
					$M_{0,max}$				11.9	15.5	20.9	25.8	29.7	31.9
					M_{max}				11.9	15.5	20.9	25.8	29.7	31.9
					n_{eto}				-	-	-	-	-	-
12D20L	5.5	1950	5.2	1.10	M_0			5.9	6.4					
					M_N			5.3	5.5					
					$M_{0,max}$			14.9	17.7					
					M_{max}			14.9	17.7					
					n_{eto}			-	-					
12D41L	4.3	4050	8.8	1.80	M_0				5.3	6.4	6.4	6.4		
					M_N				4.3	4.3	4.3	4.3		
					$M_{0,max}$				10.6	13.6	17.7	17.9		
					M_{max}				10.6	13.6	17.7	17.9		
					n_{eto}				-	-	-	-		
12H15L	10.0	1500	7.6	1.60	M_0				11.4	11.4	10.0			
					M_N				10.0	10.0	11.4			
					$M_{0,max}$				25.8	29.0	29.0			
					M_{max}				25.8	29.0	29.0			
					n_{eto}				-	-	-			
12H30L	8.0	3000	10.5	2.50	M_0				7.4	9.8	11.4			
					M_N				6.7	8.0	8.0			
					$M_{0,max}$				16.4	21.5	29.0			
					M_{max}				16.4	21.5	29.0			
					n_{eto}				-	-	-			
12L20L	13.5	1950	11.8	2.80	M_0				10.6	14.0	15.0	15.0	15.0	
					M_N				10.1	13.3	13.5	13.5	13.5	
					$M_{0,max}$				24.4	31.5	41.8	50.5	56.0	
					M_{max}				24.4	31.5	41.8	50.5	56.0	
					n_{eto}				-	-	-	-	-	

► I... [A], M... [Nm], n... [r/min], P... [kW]

6.6

Selection tables, Servo Drives 9400 HighLine

Forced ventilated IP54 motors

► The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 4 kHz.

MCS	M_N	n_N	I_N	P_N	E94A□□	E0024	E0034	E0044	E0074	E0094	E0134	E0174	E0244	E0324	E0474	E0594
					I_N	1.9	3.1	5.0	8.8	11.7	16.3	20.6	29.4	38.4	47.0	59.0
					$I_{0,max}$	6.0	10.0	16.0	21.0	28.0	39.0	49.5	58.8	76.8	94.0	118.0
					I_{max}	6.0	10.0	16.0	21.0	28.0	39.0	49.5	58.8	76.8	94.0	118.0
12D17-	7.0	1650	3.0	1.20	M_0	4.4	7.3									
					M_N	4.0	7.0									
					$M_{0,max}$	11.8	17.7									
					M_{max}	11.8	17.7									
					n_{eto}	-	-									
12D35-	6.0	3525	5.6	2.20	M_0			5.9	7.5							
					M_N			5.4	6.0							
					$M_{0,max}$			14.7	17.7							
					M_{max}			14.7	17.7							
					n_{eto}			-	-							
12H14-	12.0	1350	4.1	1.70	M_0		8.7	12.8								
					M_N		8.2	12.0								
					$M_{0,max}$		24.6	29.0								
					M_{max}		24.6	29.0								
					n_{eto}		-	-								
12H34-	10.5	3375	7.5	3.70	M_0			7.0	12.8	12.8	12.8					
					M_N			6.6	10.5	10.5	10.5					
					$M_{0,max}$			20.1	25.8	29.0	29.0					
					M_{max}			20.1	25.8	29.0	29.0					
					n_{eto}			-	-	-	-					
12L17-	17.0	1650	6.7	2.90	M_0			12.1	19.0	19.0	19.0					
					M_N			11.4	17.0	17.0	17.0					
					$M_{0,max}$			35.5	44.6	55.7	56.4					
					M_{max}			35.5	44.6	55.7	56.4					
					n_{eto}			-	-	-	-					
12L39-	14.0	3900	11.7	5.70	M_0				10.6	15.3	19.0	19.0	19.0			
					M_N				9.5	13.9	14.0	14.0	14.0			
					$M_{0,max}$				24.4	31.6	41.9	50.8	56.4			
					M_{max}				24.4	31.6	41.9	50.8	56.4			
					n_{eto}				-	-	-	-	-			
14D14-	12.0	1350	5.4	1.70	M_0			11.0	12.5							
					M_N			11.0	12.0							
					$M_{0,max}$			28.3	29.0							
					M_{max}			28.3	29.0							
					n_{eto}			-	-							
14D30-	10.5	3000	9.7	3.30	M_0				9.6	12.5	12.5					
					M_N				9.5	10.5	10.5					
					$M_{0,max}$				20.2	25.6	29.0					
					M_{max}				20.2	25.6	29.0					
					n_{eto}				-	-	-					
14H12-	23.5	1200	8.3	3.00	M_0				12.4	24.1	25.5	25.5				
					M_N				12.1	23.5	23.5	23.5				
					$M_{0,max}$				37.1	46.6	54.8	54.8				
					M_{max}				37.1	46.6	54.8	54.8				
					n_{eto}				-	-	-	-				

► I... [A], M... [Nm], n... [r/min], P... [kW]

6.6

- -

Selection tables, Servo Drives 9400 HighLine

Forced ventilated IP54 motors

► The data applies to a mains connection voltage of 3 x 400 V and
an inverter switching frequency of 4 kHz.

					E94A□□	E0024	E0034	E0044	E0074	E0094	E0134	E0174	E0244	E0324	E0474	E0594
					I_N	1.9	3.1	5.0	8.8	11.7	16.3	20.6	29.4	38.4	47.0	59.0
					$I_{0,max}$	6.0	10.0	16.0	21.0	28.0	39.0	49.5	58.8	76.8	94.0	118.0
MCS	M_N	n_N	I_N	P_N	I_{max}	6.0	10.0	16.0	21.0	28.0	39.0	49.5	58.8	76.8	94.0	118.0
14H28-	20.5	2775	15.0	6.00	M_0					16.1	20.5	25.5	25.5			
					M_N					15.9	20.5	20.5	20.5			
					$M_{0,max}$					33.0	43.9	53.2	54.8			
					M_{max}					33.0	43.9	53.2	54.8			
					n_{eto}					-	-	-	-			
14L14-	30.5	1350	11.8	4.30	M_0				20.5	30.0	34.5					
					M_N				20.5	30.0	30.5					
					$M_{0,max}$				48.0	61.4	77.1					
					M_{max}				48.0	61.4	77.1					
					n_{eto}				-	-	-					
14L30-	25.5	3000	20.8	8.00	M_0						21.0	26.6	34.5	34.5	34.5	
					M_N						20.0	25.3	25.5	25.5	25.5	
					$M_{0,max}$						45.0	55.3	63.9	77.1	77.1	
					M_{max}						45.0	55.3	63.9	77.1	77.1	
					n_{eto}						-	-	-	-	-	
14P11-	42.0	1050	13.4	4.60	M_0				26.7	36.4	43.5	43.5				
					M_N				24.4	36.4	42.0	42.0				
					$M_{0,max}$				56.1	71.7	93.3	105.1				
					M_{max}				56.1	71.7	93.3	105.1				
					n_{eto}				-	-	-	-				
14P26-	33.0	2625	21.9	9.10	M_0						24.8	31.4	43.5	43.5	43.5	
					M_N						24.6	31.0	33.0	33.0	33.0	
					$M_{0,max}$						52.5	64.6	74.7	92.2	105.1	
					M_{max}						52.5	64.6	74.7	92.2	105.1	
					n_{eto}						-	-	-	-	-	
19F12-	38.0	1200	11.3	4.80	M_0				29.9	39.5	41.5					
					M_N				29.3	38.0	38.0					
					$M_{0,max}$				62.1	78.9	86.0					
					M_{max}				62.1	78.9	86.0					
					n_{eto}				-	-	-					
19F29-	32.5	2850	20.1	9.70	M_0						26.3	34.9	41.5	41.5		
					M_N						26.0	32.5	32.5	32.5		
					$M_{0,max}$						56.6	70.2	81.6	86.0		
					M_{max}						56.6	70.2	81.6	86.0		
					n_{eto}						-	-	-	-		
19J12-	62.5	1200	18.3	7.90	M_0						56.6	70.5				
					M_N						55.7	62.5				
					$M_{0,max}$						114.4	129.0				
					M_{max}						114.4	129.0				
					n_{eto}						-	-				
19J29-	50.5	2850	31.0	15.10	M_0								49.2	66.7	70.5	
					M_N								47.9	50.5	50.5	
					$M_{0,max}$								88.9	112.9	129.0	
					M_{max}								88.9	112.9	129.0	
					n_{eto}								-	-	-	

► I... [A], M... [Nm], n... [r/min], P... [kW]

6.6

Selection tables, Servo Drives 9400 HighLine

Forced ventilated IP54 motors

► The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 4 kHz.

					E94A□□	E0024	E0034	E0044	E0074	E0094	E0134	E0174	E0244	E0324	E0474	E0594
					I_N	1.9	3.1	5.0	8.8	11.7	16.3	20.6	29.4	38.4	47.0	59.0
					$I_{0,max}$	6.0	10.0	16.0	21.0	28.0	39.0	49.5	58.8	76.8	94.0	118.0
MCS	M_N	n_N	I_N	P_N	I_{max}	6.0	10.0	16.0	21.0	28.0	39.0	49.5	58.8	76.8	94.0	118.0
19P12-	72.0	1200	21.3	9.00	M_0							79.1	86.0	86.0		
					M_N							69.6	72.0	72.0		
					$M_{0,max}$							159.9	186.6	190.0		
					M_{max}							159.9	186.6	190.0		
					n_{eto}							-	-	-		
19P29-	53.0	2850	29.5	15.80	M_0								56.5	73.9	86.0	86.0
					M_N								52.8	53.0	53.0	53.0
					$M_{0,max}$								98.5	126.6	152.5	187.2
					M_{max}								98.5	126.6	152.5	187.2
					n_{eto}								-	-	-	-

► I... [A], M... [Nm], n... [r/min], P... [kW]

Selection tables, Inverter Drives 8400 TopLine

Non-ventilated motors

► The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 8 kHz.

					E84AVTC	□3714	□5514	□7514	□1124	□1524	□2224	□3024
					I_N	1.3	1.8	2.4	3.2	3.9	5.9	7.3
					$I_{0,max}$	2.0	2.7	3.6	4.8	5.9	8.4	11.0
MCS	M_N	n_N	I_N	P_N	I_{max}	2.6	3.6	4.8	6.4	7.8	11.2	14.6
06C41-	0.6	4050	1.3	0.25	M_0	0.8	0.8	0.8	0.8	0.8		
					M_N	0.6	0.6	0.6	0.6	0.6		
					$M_{0,max}$	1.4	1.7	2.3	2.4	2.4		
					M_{max}	1.4	1.7	2.3	2.4	2.4		
					n_{eto}	-	-	-	-	-		
06C60-	0.5	6000	2.4	0.31	M_0			0.8	0.8	0.8	0.8	0.8
					M_N			0.5	0.5	0.5	0.5	0.5
					$M_{0,max}$			1.3	1.6	2.0	2.4	2.4
					M_{max}			1.3	1.6	2.0	2.4	2.4
					n_{eto}			-	-	-	-	-
06F41-	1.2	4050	1.5	0.51	M_0	1.3	1.5	1.5	1.5	1.5		
					M_N	1.0	1.2	1.2	1.2	1.2		
					$M_{0,max}$	2.3	3.2	4.3	4.4	4.4		
					M_{max}	2.3	3.2	4.3	4.4	4.4		
					n_{eto}	-	-	-	-	-		
06F60-	0.9	6000	2.5	0.57	M_0			1.2	1.5	1.5	1.5	1.5
					M_N			0.9	0.9	0.9	0.9	0.9
					$M_{0,max}$			2.1	3.3	4.0	4.4	4.4
					M_{max}			2.1	3.3	4.0	4.4	4.4
					n_{eto}			-	-	-	-	-
06I41-	1.5	4050	1.6	0.64	M_0	1.6	2.0	2.0	2.0	2.0		
					M_N	1.2	1.5	1.5	1.5	1.5		
					$M_{0,max}$	2.9	4.0	5.3	6.2	6.2		
					M_{max}	2.9	4.0	5.3	6.2	6.2		
					n_{eto}	-	-	-	-	-		
06I60-	1.2	6000	2.9	0.75	M_0				2.0	2.0	2.0	2.0
					M_N				1.2	1.2	1.2	1.2
					$M_{0,max}$				3.6	4.4	5.7	5.7
					M_{max}				3.6	4.4	5.7	5.7
					n_{eto}				-	-	-	-
09D41-	2.3	4050	2.3	1.00	M_0		2.2	3.1	3.3	3.3	3.3	3.3
					M_N		1.7	2.3	2.3	2.3	2.3	2.3
					$M_{0,max}$		4.0	5.3	6.7	8.2	9.4	9.4
					M_{max}		4.0	5.3	6.7	8.2	9.4	9.4
					n_{eto}		-	-	-	-	-	-
09D60-	1.8	6000	3.8	1.10	M_0				2.0	2.4	3.3	3.3
					M_N				1.5	1.8	1.8	1.8
					$M_{0,max}$				3.5	4.2	6.3	7.8
					M_{max}				3.5	4.2	6.3	7.8
					n_{eto}				-	-	-	-
09F38-	3.1	3750	2.5	1.20	M_0			3.4	4.2	4.2	4.2	4.2
					M_N			3.0	3.1	3.1	3.1	3.1
					$M_{0,max}$			6.6	8.4	10.2	12.0	12.0
					M_{max}			6.6	8.4	10.2	12.0	12.0
					n_{eto}			-	-	-	-	-

► I... [A], M... [Nm], n... [r/min], P... [kW]

6.6

Selection tables, Inverter Drives 8400 TopLine

Non-ventilated motors

► The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 8 kHz.

□4024	□5524	□7524	□1134	□1534	□1834	□2234	□3034	E84AVTC					
9.5	13.0	16.5	23.5	32.0	39.0	47.0	61.0	I_N					
14.3	19.5	26.4	32.9	43.2	60.0	70.5	91.5	$I_{0,max}$					
19.0	26.0	33.0	47.0	64.0	78.0	94.0	122.0	I_{max}	P_N	I_N	n_N	M_N	MCS
								M_0					
								M_N					
								$M_{0,max}$	0.25	1.3	4050	0.6	06C41-
								M_{max}					
								n_{eto}					
								M_0					
								M_N					
								$M_{0,max}$	0.31	2.4	6000	0.5	06C60-
								M_{max}					
								n_{eto}					
								M_0					
								M_N					
								$M_{0,max}$	0.51	1.5	4050	1.2	06F41-
								M_{max}					
								n_{eto}					
								M_0					
								M_N					
								$M_{0,max}$	0.57	2.5	6000	0.9	06F60-
								M_{max}					
								n_{eto}					
								M_0					
								M_N					
								$M_{0,max}$	0.64	1.6	4050	1.5	06I41-
								M_{max}					
								n_{eto}					
								M_0					
								M_N					
								$M_{0,max}$	0.75	2.9	6000	1.2	06I60-
								M_{max}					
								n_{eto}					
								M_0					
								M_N					
								$M_{0,max}$	1.00	2.3	4050	2.3	09D41-
								M_{max}					
								n_{eto}					
3.3	3.3							M_0					
1.8	1.8							M_N					
9.1	9.3							$M_{0,max}$	1.10	3.8	6000	1.8	09D60-
9.1	9.3							M_{max}					
-	-							n_{eto}					
								M_0					
								M_N					
								$M_{0,max}$	1.20	2.5	3750	3.1	09F38-
								M_{max}					
								n_{eto}					

► I... [A], M... [Nm], n... [r/min], P... [kW]

Selection tables, Inverter Drives 8400 TopLine

Non-ventilated motors

► The data applies to a mains connection voltage of 3 x 400 V and
an inverter switching frequency of 8 kHz.

					E84AVTC	□3714	□5514	□7514	□1124	□1524	□2224	□3024
					I_N	1.3	1.8	2.4	3.2	3.9	5.9	7.3
					$I_{0,max}$	2.0	2.7	3.6	4.8	5.9	8.4	11.0
MCS	M_N	n_N	I_N	P_N	I_{max}	2.6	3.6	4.8	6.4	7.8	11.2	14.6
09F60-	2.4	6000	4.5	1.50	M_0						4.2	4.2
					M_N						2.4	2.4
					$M_{0,max}$						7.8	9.6
					M_{max}						7.8	9.6
					n_{eto}						-	-
09H41-	3.8	4050	3.4	1.60	M_0				4.7	5.0	5.5	5.5
					M_N				3.6	3.8	3.8	3.8
					$M_{0,max}$				8.1	9.9	14.0	17.4
					M_{max}				8.1	9.9	14.0	17.4
					n_{eto}				-	-	-	-
09H60-	3.0	6000	6.0	1.90	M_0						4.4	4.5
					M_N						3.0	3.0
					$M_{0,max}$						7.5	9.3
					M_{max}						7.5	9.3
					n_{eto}						-	-
09L41-	4.5	4050	4.2	1.90	M_0				3.9	4.7	7.5	7.5
					M_N				3.4	4.2	4.5	4.5
					$M_{0,max}$				7.3	8.9	13.1	16.3
					M_{max}				7.3	8.9	13.1	16.3
					n_{eto}				-	-	-	-
09L51-	3.6	5100	6.9	1.90	M_0							4.2
					M_N							3.6
					$M_{0,max}$							8.3
					M_{max}							8.3
					n_{eto}							-
12D20-	5.5	1950	2.6	1.10	M_0			5.7	6.4	6.4	6.4	6.4
					M_N			5.1	5.5	5.5	5.5	5.5
					$M_{0,max}$			9.6	12.6	15.3	17.7	17.7
					M_{max}			9.6	12.6	15.3	17.7	17.7
					n_{eto}			-	-	-	-	-
12D41-	4.3	4050	4.5	1.80	M_0				3.8	4.6	6.4	6.4
					M_N				3.0	3.7	4.3	4.3
					$M_{0,max}$				6.4	7.8	11.4	14.0
					M_{max}				6.4	7.8	11.4	14.0
					n_{eto}				-	-	-	-
12H15-	10.0	1500	3.8	1.60	M_0				9.2	10.9	11.4	11.4
					M_N				8.4	10.0	10.0	10.0
					$M_{0,max}$				16.4	20.0	29.0	29.0
					M_{max}				16.4	20.0	29.0	29.0
					n_{eto}				-	-	-	-
12H35-	7.5	3525	5.7	2.80	M_0						9.8	9.8
					M_N						7.5	7.5
					$M_{0,max}$						15.2	18.8
					M_{max}						15.2	18.8
					n_{eto}						-	-

► I... [A], M... [Nm], n... [r/min], P... [kW]

6.6

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Selection tables, Inverter Drives 8400 TopLine

Non-ventilated motors

► The data applies to a mains connection voltage of 3 x 400 V and
an inverter switching frequency of 8 kHz.

□4024	□5524	□7524	□1134	□1534	□1834	□2234	□3034	E84AVTC		P_N	I_N	n_N	M_N	MCS
9.5	13.0	16.5	23.5	32.0	39.0	47.0	61.0	I_N						
14.3	19.5	26.4	32.9	43.2	60.0	70.5	91.5	$I_{0,max}$						
19.0	26.0	33.0	47.0	64.0	78.0	94.0	122.0	I_{max}						
4.2	4.2							M_0						
2.4	2.4							M_N						
11.1	11.4							$M_{0,max}$		1.50	4.5	6000	2.4	09F60-
11.1	11.4							M_{max}						
-	-							n_{eto}						
5.5	5.5							M_0						
3.8	3.8							M_N						
19.6	20.1							$M_{0,max}$		1.60	3.4	4050	3.8	09H41-
19.6	20.1							M_{max}						
-	-							n_{eto}						
5.5	5.5							M_0						
3.0	3.0							M_N						
11.4	11.7							$M_{0,max}$		1.90	6.0	6000	3.0	09H60-
11.4	11.7							M_{max}						
-	-							n_{eto}						
7.5	7.5							M_0						
4.5	4.5							M_N						
20.3	20.8							$M_{0,max}$		1.90	4.2	4050	4.5	09L41-
20.3	20.8							M_{max}						
-	-							n_{eto}						
7.5	7.5	7.5	7.5					M_0						
3.6	3.6	3.6	3.6					M_N						
10.8	19.1	19.1	19.1					$M_{0,max}$		1.90	6.9	5100	3.6	09L51-
10.8	19.1	19.1	19.1					M_{max}						
-	-	-	-					n_{eto}						
								M_0						
								M_N						
								$M_{0,max}$		1.10	2.6	1950	5.5	12D20-
								M_{max}						
								n_{eto}						
6.4	6.4							M_0						
4.3	4.3							M_N						
16.9	17.3							$M_{0,max}$		1.80	4.5	4050	4.3	12D41-
16.9	17.3							M_{max}						
-	-							n_{eto}						
11.4	11.4							M_0						
10.0	10.0							M_N						
28.3	29.0							$M_{0,max}$		1.60	3.8	1500	10.0	12H15-
28.3	29.0							M_{max}						
-	-							n_{eto}						
11.4	11.4							M_0						
7.5	7.5							M_N						
23.5	24.1							$M_{0,max}$		2.80	5.7	3525	7.5	12H35-
23.5	24.1							M_{max}						
-	-							n_{eto}						

► I... [A], M... [Nm], n... [r/min], P... [kW]

Selection tables, Inverter Drives 8400 TopLine

Non-ventilated motors

► The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 8 kHz.

					E84AVTC	□3714	□5514	□7514	□1124	□1524	□2224	□3024
					I_N	1.3	1.8	2.4	3.2	3.9	5.9	7.3
					$I_{0,max}$	2.0	2.7	3.6	4.8	5.9	8.4	11.0
MCS	M_N	n_N	I_N	P_N	I_{max}	2.6	3.6	4.8	6.4	7.8	11.2	14.6
12L20-	13.5	1950	5.9	2.80	M_0						15.0	15.0
					M_N						13.5	13.5
					$M_{0,max}$						27.4	33.9
					M_{max}						27.4	33.9
					n_{eto}						-	-
12L41-	11.0	4050	10.2	4.70	M_0							
					M_N							
					$M_{0,max}$							
					M_{max}							
					n_{eto}							
14D15-	9.2	1500	4.5	1.45	M_0				7.0	8.5	11.0	11.0
					M_N				6.6	8.0	9.2	9.2
					$M_{0,max}$				13.1	16.0	22.7	28.1
					M_{max}				13.1	16.0	22.7	28.1
					n_{eto}				-	-	-	-
14D36-	7.5	3600	7.5	2.80	M_0							8.0
					M_N							7.3
					$M_{0,max}$							15.2
					M_{max}							15.2
					n_{eto}							-
14H15-	16.0	1500	6.6	2.50	M_0							17.3
					M_N							16.0
					$M_{0,max}$							35.3
					M_{max}							35.3
					n_{eto}							-
14H32-	14.0	3225	11.9	4.70	M_0							
					M_N							
					$M_{0,max}$							
					M_{max}							
					n_{eto}							
14L15-	23.0	1500	9.7	3.60	M_0							
					M_N							
					$M_{0,max}$							
					M_{max}							
					n_{eto}							
14L32-	17.2	3225	15.0	5.80	M_0							
					M_N							
					$M_{0,max}$							
					M_{max}							
					n_{eto}							
14P14-	30.0	1350	10.8	4.20	M_0							
					M_N							
					$M_{0,max}$							
					M_{max}							
					n_{eto}							

► I... [A], M... [Nm], n... [r/min], P... [kW]

6.6

Selection tables, Inverter Drives 8400 TopLine

Non-ventilated motors

► The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 8 kHz.

□4024	□5524	□7524	□1134	□1534	□1834	□2234	□3034	E84AVTC	P_N	I_N	n_N	M_N	MCS
9.5	13.0	16.5	23.5	32.0	39.0	47.0	61.0	I_N					
14.3	19.5	26.4	32.9	43.2	60.0	70.5	91.5	$I_{0,max}$					
19.0	26.0	33.0	47.0	64.0	78.0	94.0	122.0	I_{max}					
15.0	15.0							M_0					
13.5	13.5							M_N					
40.8	41.9							$M_{0,max}$	2.80	5.9	1950	13.5	12L20-
40.8	41.9							M_{max}					
-	-							n_{eto}					
14.0	15.0	15.0	15.0	15.0				M_0					
10.2	11.0	11.0	11.0	11.0				M_N					
22.2	30.4	35.5	35.5	35.5				$M_{0,max}$	4.70	10.2	4050	11.0	12L41-
22.2	30.4	49.6	49.6	49.6				M_{max}					
-	-	-	-	-				n_{eto}					
11.0	11.0							M_0					
9.2	9.2							M_N					
28.3	29.0							$M_{0,max}$	1.45	4.5	1500	9.2	14D15-
28.3	29.0							M_{max}					
-	-							n_{eto}					
11.0	11.0	11.0	11.0					M_0					
7.5	7.5	7.5	7.5					M_N					
18.5	25.3	29.0	29.0					$M_{0,max}$	2.80	7.5	3600	7.5	14D36-
18.5	22.2	22.2	22.2					M_{max}					
-	-	-	-					n_{eto}					
21.0	21.0							M_0					
16.0	16.0							M_N					
42.8	43.9							$M_{0,max}$	2.50	6.6	1500	16.0	14H15-
42.8	43.9							M_{max}					
-	-							n_{eto}					
12.9	16.2	21.0	21.0	21.0				M_0					
11.2	14.0	14.0	14.0	14.0				M_N					
23.2	31.7	37.1	37.1	37.1				$M_{0,max}$	4.70	11.9	3225	14.0	14H32-
23.2	31.7	51.9	51.9	51.9				M_{max}					
-	-	-	-	-				n_{eto}					
27.4	28.0	28.0	28.0					M_0					
22.5	23.0	23.0	23.0					M_N					
43.8	52.9	52.9	52.9					$M_{0,max}$	3.60	9.7	1500	23.0	14L15-
43.8	60.0	73.8	73.8					M_{max}					
-	-	-	-					n_{eto}					
	15.2	27.4	27.4	28.0	28.0	28.0		M_0					
	14.9	17.2	17.2	17.2	17.2	17.2		M_N					
	31.3	39.7	52.9	52.9	52.9	52.9		$M_{0,max}$	5.80	15.0	3225	17.2	14L32-
	31.3	57.6	73.9	73.9	73.9	73.9		M_{max}					
	-	-	-	-	-	-		n_{eto}					
32.5	37.0	37.0	37.0	37.0				M_0					
26.4	30.0	30.0	30.0	30.0				M_N					
51.2	70.0	80.0	80.0	80.0				$M_{0,max}$	4.20	10.8	1350	30.0	14P14-
51.2	70.0	105.1	105.1	105.1				M_{max}					
-	-	-	-	-				n_{eto}					

► I... [A], M... [Nm], n... [r/min], P... [kW]

6.6

Selection tables, Inverter Drives 8400 TopLine

Non-ventilated motors

► The data applies to a mains connection voltage of 3 x 400 V and
an inverter switching frequency of 8 kHz.

				E84AVTC	□3714	□5514	□7514	□1124	□1524	□2224	□3024
				I_N	1.3	1.8	2.4	3.2	3.9	5.9	7.3
				$I_{0,max}$	2.0	2.7	3.6	4.8	5.9	8.4	11.0
MCS	M_N	n_N	I_N	P_N / I_{max}	2.6	3.6	4.8	6.4	7.8	11.2	14.6
14P32-	21.0	3225	15.6	7.10 / M_0							
				M_N							
				$M_{0,max}$							
				M_{max}							
				n_{eto}							
19F14-	27.0	1425	8.6	4.00 / M_0							23.6
				M_N							22.9
				$M_{0,max}$							45.9
				M_{max}							45.9
				n_{eto}							-
19F30-	21.0	3000	14.0	6.60 / M_0							
				M_N							
				$M_{0,max}$							
				M_{max}							
				n_{eto}							
19J14-	40.0	1425	12.3	6.00 / M_0							
				M_N							
				$M_{0,max}$							
				M_{max}							
				n_{eto}							
19J30-	29.0	3000	18.5	9.10 / M_0							
				M_N							
				$M_{0,max}$							
				M_{max}							
				n_{eto}							
19P14-	51.0	1350	14.3	7.20 / M_0							
				M_N							
				$M_{0,max}$							
				M_{max}							
				n_{eto}							
19P30-	32.0	3000	19.0	10.00 / M_0							
				M_N							
				$M_{0,max}$							
				M_{max}							
				n_{eto}							

► I... [A], M... [Nm], n... [r/min], P... [kW]

6.6

Selection tables, Inverter Drives 8400 TopLine

Non-ventilated motors

► The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 8 kHz.

□4024	□5524	□7524	□1134	□1534	□1834	□2234	□3034	E84AVTC	P_N	I_N	n_N	M_N	MCS
9.5	13.0	16.5	23.5	32.0	39.0	47.0	61.0	I_N					
14.3	19.5	26.4	32.9	43.2	60.0	70.5	91.5	$I_{0,max}$					
19.0	26.0	33.0	47.0	64.0	78.0	94.0	122.0	I_{max}					
	19.8	35.8	35.8	37.0	37.0	37.0		M_0					
	17.5	21.0	21.0	21.0	21.0	21.0		M_N					
	36.5	46.3	61.8	61.8	61.8	61.8		$M_{0,max}$	7.10	15.6	3225	21.0	14P32-
	36.5	67.3	86.4	86.4	86.4	86.4		M_{max}					
	-	-	-	-	-	-		n_{eto}					
32.0	32.0	32.0	32.0					M_0					
27.0	27.0	27.0	27.0					M_N					
56.7	68.3	68.3	68.3					$M_{0,max}$	4.00	8.6	1425	27.0	19F14-
56.7	77.6	86.0	86.0					M_{max}					
-	-	-	-					n_{eto}					
	21.0	32.0	32.0	32.0				M_0					
	19.5	21.0	21.0	21.0				M_N					
	47.2	47.2	47.2	47.2				$M_{0,max}$	6.60	14.0	3000	21.0	19F30-
	38.9	68.3	68.3	68.3				M_{max}					
	-	-	-	-				n_{eto}					
	43.6	51.0	51.0	51.0				M_0					
	40.0	40.0	40.0	40.0				M_N					
	81.1	96.0	96.0	96.0				$M_{0,max}$	6.00	12.3	1425	40.0	19J14-
	81.1	129.0	129.0	129.0				M_{max}					
	-	-	-	-				n_{eto}					
			39.3	51.0	51.0	51.0	51.0	M_0					
			29.0	29.0	29.0	29.0	29.0	M_N					
			73.6	79.5	79.5	79.5	79.5	$M_{0,max}$	9.10	18.5	3000	29.0	19J30-
			110.4	127.6	127.6	127.6	127.6	M_{max}					
			-	-	-	-	-	n_{eto}					
	47.5	64.0	64.0	64.0				M_0					
	46.4	51.0	51.0	51.0				M_N					
	92.7	106.7	106.7	106.7				$M_{0,max}$	7.20	14.3	1350	51.0	19P14-
	92.7	155.5	155.5	155.5				M_{max}					
	-	-	-	-				n_{eto}					
			43.1	58.7	64.0	64.0	64.0	M_0					
			32.0	32.0	32.0	32.0	32.0	M_N					
			79.2	87.6	87.6	87.6	87.6	$M_{0,max}$	10.00	19.0	3000	32.0	19P30-
			118.6	144.3	144.3	144.3	144.3	M_{max}					
			-	-	-	-	-	n_{eto}					

► I... [A], M... [Nm], n... [r/min], P... [kW]

Selection tables, Inverter Drives 8400 TopLine

Forced ventilated IP54 motors

► The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 8 kHz.

MCS	M_N	n_N	I_N	P_N	E84AVTC	□1124	□1524	□2224	□3024	□4024	□5524	□7524	□1134	□1534	□1834	□2234	□3034
					I_N	3.2	3.9	5.9	7.3	9.5	13.0	16.5	23.5	32.0	39.0	47.0	61.0
					$I_{0,max}$	4.8	5.9	8.4	11.0	14.3	19.5	26.4	32.9	43.2	60.0	70.5	91.5
					I_{max}	6.4	7.8	11.2	14.6	19.0	26.0	33.0	47.0	64.0	78.0	94.0	122.0
12D17-	7.0	1650	3.0	1.20	M_0	7.5	7.5	7.5	7.5								
					M_N	7.0	7.0	7.0	7.0								
					$M_{0,max}$	12.6	15.3	17.7	17.7								
					M_{max}	12.6	15.3	17.7	17.7								
					n_{eto}	-	-	-	-								
12D35-	6.0	3525	5.6	2.20	M_0		4.6	7.5	7.5	7.5	7.5						
					M_N		3.7	6.0	6.0	6.0	6.0						
					$M_{0,max}$		7.8	11.4	14.0	16.9	17.3						
					M_{max}		7.8	11.4	14.0	16.9	17.3						
					n_{eto}		-	-	-	-	-						
12H14-	12.0	1350	4.1	1.70	M_0	8.9	10.9	12.8	12.8	12.8	12.8						
					M_N	8.5	10.3	12.0	12.0	12.0	12.0						
					$M_{0,max}$	16.4	20.0	29.0	29.0	28.3	29.0						
					M_{max}	16.4	20.0	29.0	29.0	28.3	29.0						
					n_{eto}	-	-	-	-	-							
12H34-	10.5	3375	7.5	3.70	M_0				10.2	12.8	12.8						
					M_N				10.0	10.5	10.5						
					$M_{0,max}$				18.8	23.5	24.1						
					M_{max}				18.8	23.5	24.1						
					n_{eto}				-	-	-						
12L17-	17.0	1650	6.7	2.90	M_0				18.5	19.0	19.0						
					M_N				17.0	17.0	17.0						
					$M_{0,max}$				33.9	40.8	41.9						
					M_{max}				33.9	40.8	41.9						
					n_{eto}				-	-	-						
12L39-	14.0	3900	11.7	5.70	M_0					17.2	17.2	19.0	19.0	19.0			
					M_N					14.0	14.0	14.0	14.0	14.0			
					$M_{0,max}$					22.2	30.4	35.5	35.5	35.5			
					M_{max}					22.2	30.4	49.6	49.6	49.6			
					n_{eto}					-	-	-	-	-			
14D14-	12.0	1350	5.4	1.70	M_0		8.5	12.5	12.5	12.5	12.5						
					M_N		8.0	12.0	12.0	12.0	12.0						
					$M_{0,max}$		16.0	22.7	28.1	28.3	29.0						
					M_{max}		16.0	22.7	28.1	28.3	29.0						
					n_{eto}		-	-	-	-	-						
14D30-	10.5	3000	9.7	3.30	M_0				7.7	12.2	12.5	12.5	12.5				
					M_N				7.0	9.8	10.0	10.0	10.0				
					$M_{0,max}$				15.2	18.5	25.3	29.0	29.0				
					M_{max}				15.2	18.5	22.2	22.2	22.2				
					n_{eto}				-	-	-	-					
14H12-	23.5	1200	8.3	3.00	M_0				18.0	25.5	25.5						
					M_N				17.9	23.5	23.5						
					$M_{0,max}$				35.3	42.8	43.9						
					M_{max}				35.3	42.8	43.9						
					n_{eto}				-	-	-						

► I... [A], M... [Nm], n... [r/min], P... [kW]

6.6

Selection tables, Inverter Drives 8400 TopLine

Forced ventilated IP54 motors

► The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 8 kHz.

MCS	M_N	n_N	I_N	P_N	E84AVTC	□1124	□1524	□2224	□3024	□4024	□5524	□7524	□1134	□1534	□1834	□2234	□3034
					I_N	3.2	3.9	5.9	7.3	9.5	13.0	16.5	23.5	32.0	39.0	47.0	61.0
					$I_{0,max}$	4.8	5.9	8.4	11.0	14.3	19.5	26.4	32.9	43.2	60.0	70.5	91.5
					I_{max}	6.4	7.8	11.2	14.6	19.0	26.0	33.0	47.0	64.0	78.0	94.0	122.0
14H28-	20.5	2775	15.0	6.00	M_0						16.2	25.5	25.5	25.5			
					M_N						16.1	20.5	20.5	20.5			
					$M_{0,max}$						31.7	37.1	37.1	37.1			
					M_{max}						31.7	51.9	51.9	51.9			
					n_{eto}						-	-	-	-			
14L14-	30.5	1350	11.8	4.30	M_0					26.9	33.4	34.5	34.5				
					M_N					24.6	30.5	30.5	30.5				
					$M_{0,max}$					43.8	52.9	52.9	52.9				
					M_{max}					43.8	60.0	73.8	73.8				
					n_{eto}					-	-	-	-				
14L30-	25.5	3000	20.8	8.00	M_0								27.4	34.5	34.5	34.5	
					M_N								25.5	25.5	25.5	25.5	
					$M_{0,max}$								52.9	52.9	52.9	52.9	
					M_{max}								73.9	73.9	73.9	73.9	
					n_{eto}								-	-	-	-	
14P11-	42.0	1050	13.4	4.60	M_0						38.9	43.5	43.5	43.5			
					M_N						38.8	42.0	42.0	42.0			
					$M_{0,max}$						70.0	80.0	80.0	80.0			
					M_{max}						70.0	105.1	105.1	105.1			
					n_{eto}						-	-	-	-			
14P26-	33.0	2625	21.9	9.10	M_0								35.8	43.5	43.5	43.5	
					M_N								33.0	33.0	33.0	33.0	
					$M_{0,max}$								66.0	86.4	86.4	86.4	
					M_{max}								86.4	86.4	86.4	86.4	
					n_{eto}								-	-	-	-	
19F12-	38.0	1200	11.3	4.80	M_0				23.6	34.9	41.5	41.5	41.5				
					M_N				22.9	31.9	38.0	38.0	38.0				
					$M_{0,max}$				45.9	56.7	68.3	68.3	68.3				
					M_{max}				45.9	56.7	77.6	86.0	86.0				
					n_{eto}				-	-	-	-	-				
19F29-	32.5	2850	20.1	9.70	M_0								39.9	41.5			
					M_N								32.5	32.5			
					$M_{0,max}$								47.2	47.2			
					M_{max}								68.3	68.3			
					n_{eto}								-	-			
19J12-	62.5	1200	18.3	7.90	M_0						43.6		70.5	70.5			
					M_N						43.4		62.5	62.5			
					$M_{0,max}$						81.1		96.0	96.0			
					M_{max}						81.1		129.0	129.0			
					n_{eto}						-		-	-			
19J29-	50.5	2850	31.0	15.10	M_0								55.5	70.5	70.5	70.5	
					M_N								50.5	50.5	50.5	50.5	
					$M_{0,max}$								87.6	87.6	87.6	87.6	
					M_{max}								127.6	127.6	127.6	127.6	
					n_{eto}								-	-	-	-	

► I... [A], M... [Nm], n... [r/min], P... [kW]

6.6

Selection tables, Inverter Drives 8400 TopLine

Forced ventilated IP54 motors

► The data applies to a mains connection voltage of 3 x 400 V and
an inverter switching frequency of 8 kHz.

					E84AVTC	□1124	□1524	□2224	□3024	□4024	□5524	□7524	□1134	□1534	□1834	□2234	□3034
					I_N	3.2	3.9	5.9	7.3	9.5	13.0	16.5	23.5	32.0	39.0	47.0	61.0
					$I_{0,max}$	4.8	5.9	8.4	11.0	14.3	19.5	26.4	32.9	43.2	60.0	70.5	91.5
MCS	M_N	n_N	I_N	P_N	I_{max}	6.4	7.8	11.2	14.6	19.0	26.0	33.0	47.0	64.0	78.0	94.0	122.0
19P12-	72.0	1200	21.3	9.00	M_0						47.5		86.0	86.0			
					M_N						46.4		72.0	72.0			
					$M_{0,max}$						92.7		106.7	106.7			
					M_{max}						92.7		155.5	155.5			
					n_{eto}						-		-	-			
19P29-	53.0	2850	29.5	15.80	M_0									58.7	86.0	86.0	86.0
					M_N									53.0	53.0	53.0	53.0
					$M_{0,max}$									87.6	87.6	87.6	87.6
					M_{max}									144.3	144.3	144.3	144.3
					n_{eto}									-	-	-	-

► I... [A], M... [Nm], n... [r/min], P... [kW]

6.6

Selection tables, Servo Drives ECS

Non-ventilated motors

► The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 4 kHz.

MCS	M_N	n_N	I_N	P_N	ECS□□	004C□B	008C□B	016C□B	032C□B	048C□B	064C□B
					I_N	2.0	4.0	8.0	12.7	17.0	20.0
					$I_{0,max}$	2.3	4.6	9.1	18.1	27.2	36.3
					I_{max}	4.0	8.0	16.0	32.0	48.0	64.0
06C41-	0.6	4050	1.3	0.25	M_0	0.8					
					M_N	0.6					
					$M_{0,max}$	1.2					
					M_{max}	1.9					
					n_{eto}	2747					
06C60-	0.5	6000	2.4	0.31	M_0	0.6	0.8				
					M_N	0.4	0.5				
					$M_{0,max}$	0.6	1.2				
					M_{max}	1.0	1.9				
					n_{eto}	7000	6814				
06F41-	1.2	4050	1.5	0.51	M_0	1.5					
					M_N	1.2					
					$M_{0,max}$	2.0					
					M_{max}	3.6					
					n_{eto}	1902					
06F60-	0.9	6000	2.5	0.57	M_0	1.0	1.5				
					M_N	0.7	0.9				
					$M_{0,max}$	1.0	2.0				
					M_{max}	1.8	3.7				
					n_{eto}	7000	4602				
06I41-	1.5	4050	1.6	0.64	M_0	2.0	2.0				
					M_N	1.5	1.5				
					$M_{0,max}$	2.6	5.0				
					M_{max}	4.4	6.2				
					n_{eto}	1898	1384				
06I60-	1.2	6000	2.9	0.75	M_0	1.2	2.0	2.0			
					M_N	0.8	1.2	1.2			
					$M_{0,max}$	1.3	2.6	5.2			
					M_{max}	2.2	4.7	6.2			
					n_{eto}	6407	4200	3157			
09D41-	2.3	4050	2.3	1.00	M_0		3.3	3.3			
					M_N		2.3	2.3			
					$M_{0,max}$		5.0	8.8			
					M_{max}		8.0	9.4			
					n_{eto}		2361	2008			
09D60-	1.8	6000	3.8	1.10	M_0		2.5	3.3			
					M_N		1.8	1.8			
					$M_{0,max}$		2.5	4.9			
					M_{max}		4.4	8.0			
					n_{eto}		7000	5217			
09F38-	3.1	3750	2.5	1.20	M_0		4.2	4.2			
					M_N		3.1	3.1			
					$M_{0,max}$		6.2	10.8			
					M_{max}		9.8	14.9			
					n_{eto}		2589	1737			

► I... [A], M... [Nm], n... [r/min], P... [kW]

6.6

Selection tables, Servo Drives ECS

Non-ventilated motors

► The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 4 kHz.

MCS	M_N	n_N	I_N	P_N	ECS□□	004C□B	008C□B	016C□B	032C□B	048C□B	064C□B
					I_N	2.0	4.0	8.0	12.7	17.0	20.0
					$I_{0,max}$	2.3	4.6	9.1	18.1	27.2	36.3
					I_{max}	4.0	8.0	16.0	32.0	48.0	64.0
09F60-	2.4	6000	4.5	1.50	M_0		2.8	4.2	4.2		
					M_N		2.1	2.4	2.4		
					$M_{0,max}$		3.2	6.1	10.8		
					M_{max}		5.4	9.8	14.9		
					n_{eto}		7000	5906	3715		
09H41-	3.8	4050	3.4	1.60	M_0		5.2	5.5			
					M_N		3.8	3.8			
					$M_{0,max}$		5.9	11.1			
					M_{max}		9.9	17.5			
					n_{eto}		3675	2231			
09H60-	3.0	6000	6.0	1.90	M_0			5.2	5.5	5.5	
					M_N			3.0	3.0	3.0	
					$M_{0,max}$			5.9	11.0	15.5	
					M_{max}			9.9	17.5	20.4	
					n_{eto}			7000	5061	4375	
09L41-	4.5	4050	4.2	1.90	M_0		4.8	7.5	7.5		
					M_N		4.3	4.5	4.5		
					$M_{0,max}$		5.2	10.3	19.5		
					M_{max}		9.1	17.4	31.9		
					n_{eto}		4450	3188	1878		
09L51-	3.6	5100	6.9	1.90	M_0			4.8	7.5	7.5	7.5
					M_N			3.6	3.6	3.6	3.6
					$M_{0,max}$			5.2	10.3	15.1	19.6
					M_{max}			9.1	17.5	25.1	31.9
					n_{eto}			7000	7000	5647	4076
12D20-	5.5	1950	2.6	1.10	M_0	4.7	6.4	6.4			
					M_N	4.2	5.5	5.5			
					$M_{0,max}$	4.6	9.1	17.0			
					M_{max}	8.0	15.3	17.7			
					n_{eto}	1730	1089	919			
12D41-	4.3	4050	4.5	1.80	M_0		4.7	6.4			
					M_N		3.8	4.3			
					$M_{0,max}$		4.6	8.8			
					M_{max}		7.8	14.7			
					n_{eto}		3902	2433			
12H15-	10.0	1500	3.8	1.60	M_0		11.2	11.4			
					M_N		10.0	10.0			
					$M_{0,max}$		11.9	22.6			
					M_{max}		20.1	29.0			
					n_{eto}		1220	918			
12H35-	7.5	3525	5.7	2.80	M_0		5.6	11.2	11.4		
					M_N		5.3	7.5	7.5		
					$M_{0,max}$		6.0	11.8	22.5		
					M_{max}		10.4	20.1	29.0		
					n_{eto}		3850	2838	2092		

► I... [A], M... [Nm], n... [r/min], P... [kW]

MCS synchronous servo motors

Technical data

Selection tables, Servo Drives ECS

Non-ventilated motors

► The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 4 kHz.

MCS	M_N	n_N	I_N	P_N	ECS□□	004C□B	008C□B	016C□B	032C□B	048C□B	064C□B
					I_N	2.0	4.0	8.0	12.7	17.0	20.0
					$I_{0,max}$	2.3	4.6	9.1	18.1	27.2	36.3
					I_{max}	4.0	8.0	16.0	32.0	48.0	64.0
12L20-	13.5	1950	5.9	2.80	M_0			15.0	15.0		
					M_N			13.5	13.5		
					$M_{0,max}$			21.4	39.4		
					M_{max}			35.5	56.4		
					n_{eto}			1324	863		
12L41-	11.0	4050	10.2	4.70	M_0			9.7	15.0	15.0	15.0
					M_N			8.6	11.0	11.0	11.0
					$M_{0,max}$			10.8	21.3	30.8	39.5
					M_{max}			19.0	35.5	49.6	56.4
					n_{eto}			4450	3013	2236	1907
14D15-	9.2	1500	4.5	1.45	M_0		8.8	11.0			
					M_N		8.2	9.2			
					$M_{0,max}$		9.6	17.9			
					M_{max}		15.9	28.3			
					n_{eto}		1141	689			
14D36-	7.5	3600	7.5	2.80	M_0			8.8	11.0		
					M_N			7.5	7.5		
					$M_{0,max}$			9.5	17.8		
					M_{max}			15.9	28.3		
					n_{eto}			2496	1614		
14H15-	16.0	1500	6.6	2.50	M_0			19.8	21.0		
					M_N			16.0	16.0		
					$M_{0,max}$			22.3	41.2		
					M_{max}			37.1	54.8		
					n_{eto}			920	667		
14H32-	14.0	3225	11.9	4.70	M_0				15.8	21.0	21.0
					M_N				14.0	14.0	14.0
					$M_{0,max}$				22.2	32.1	41.3
					M_{max}				37.1	51.9	54.8
					n_{eto}				1953	1471	1409
14L15-	23.0	1500	9.7	3.60	M_0			18.7	28.0	28.0	
					M_N			19.0	23.0	23.0	
					$M_{0,max}$			21.9	42.1	59.9	
					M_{max}			37.6	68.5	77.1	
					n_{eto}			1284	828	767	
14L32-	17.2	3225	15.0	5.80	M_0				14.8	19.8	23.3
					M_N				14.6	17.2	17.2
					$M_{0,max}$				21.8	32.4	42.2
					M_{max}				37.6	53.9	68.5
					n_{eto}				2801	2096	1757
14P14-	30.0	1350	10.8	4.20	M_0				37.0	37.0	37.0
					M_N				30.0	30.0	30.0
					$M_{0,max}$				49.1	70.0	88.4
					M_{max}				80.0	105.1	105.1
					n_{eto}				710	573	573

► I... [A], M... [Nm], n... [r/min], P... [kW]

6.6

MCS synchronous servo motors

Technical data

Selection tables, Servo Drives ECS

Non-ventilated motors

► The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 4 kHz.

				ECS□□	004C□B	008C□B	016C□B	032C□B	048C□B	064C□B
				I_N	2.0	4.0	8.0	12.7	17.0	20.0
				$I_{0,max}$	2.3	4.6	9.1	18.1	27.2	36.3
MCS	M_N	n_N	I_N	P_N	I_{max}					
					4.0	8.0	16.0	32.0	48.0	64.0
14P32-	21.0	3225	15.6	7.10	M_0				19.3	25.9	30.5
					M_N				17.1	21.0	21.0
					$M_{0,max}$				25.4	37.9	49.3
					M_{max}				43.9	63.0	80.0
					n_{eto}				2469	1829	1495
19F14-	27.0	1425	8.6	4.00	M_0			25.9	32.0		
					M_N			25.1	27.0		
					$M_{0,max}$			28.6	54.6		
					M_{max}			48.9	86.0		
					n_{eto}			1204	746		
19F30-	21.0	3000	14.0	6.60	M_0				20.5	27.5	32.0
					M_N				19.0	21.0	21.0
					$M_{0,max}$				27.2	40.5	53.0
					M_{max}				47.2	68.3	86.0
					n_{eto}				2774	2033	1653
19J14-	40.0	1425	12.3	6.00	M_0				42.6	51.0	
					M_N				40.0	40.0	
					$M_{0,max}$				58.9	82.8	
					M_{max}				96.0	129.0	
					n_{eto}				1063	839	
19J30-	29.0	3000	18.5	9.10	M_0					28.4	33.4
					M_N					26.6	29.0
					$M_{0,max}$					42.6	56.9
					M_{max}					73.8	96.0
					n_{eto}					2850	2323
19P14-	51.0	1350	14.3	7.20	M_0				46.4	62.2	64.0
					M_N				45.3	51.0	51.0
					$M_{0,max}$				64.6	91.5	120.1
					M_{max}				106.7	155.5	190.0
					n_{eto}				1227	996	870
19P30-	32.0	3000	19.0	10.00	M_0					31.2	36.7
					M_N					28.6	32.0
					$M_{0,max}$					45.8	61.1
					M_{max}					81.2	106.7
					n_{eto}					2938	2715

► I... [A], M... [Nm], n... [r/min], P... [kW]

6.6

Selection tables, Servo Drives ECS

Non-ventilated motors

► The data applies to a mains connection voltage of 3x230V   and
an inverter switching frequency of 4 kHz.

					ECS□□	004C□B	008C□B	016C□B	032C□B	048C□B	064C□B
					I_N	2.0	4.0	8.0	12.7	17.0	20.0
					$I_{0,max}$	2.3	4.6	9.1	18.1	27.2	36.3
MCS	M_N	n_N	I_N	P_N	I_{max}	4.0	8.0	16.0	32.0	48.0	64.0
06C41L	0.6	4050	2.6	0.25	M_0	0.6	0.8				
					M_N	0.5	0.6				
					$M_{0,max}$	0.6	1.1				
					M_{max}	1.0	1.9				
					n_{eto}	6298	2835				
06C60L	0.5	6000	4.0	0.31	M_0		0.7	0.8			
					M_N		0.5	0.5			
					$M_{0,max}$		0.7	1.3			
					M_{max}		1.2	2.2			
					n_{eto}		7000	1149			
06F41L	1.2	4050	2.9	0.51	M_0	1.0	1.5	1.5			
					M_N	0.8	1.2	1.2			
					$M_{0,max}$	1.2	2.1	3.9			
					M_{max}	1.9	3.5	4.4			
					n_{eto}	3838	2118	2831			
06F60L	0.9	6000	3.8	0.57	M_0		1.5	1.5			
					M_N		0.9	0.9			
					$M_{0,max}$		1.5	2.9			
					M_{max}		2.6	4.3			
					n_{eto}		6138	3182			
06I41L	1.5	4050	3.2	0.64	M_0	1.3	2.0	2.0			
					M_N	1.0	1.5	1.5			
					$M_{0,max}$	1.4	2.8	5.0			
					M_{max}	2.4	4.4	6.2			
					n_{eto}	3549	1947	2831			
06I60L	1.2	6000	3.8	0.75	M_0		1.9	2.0			
					M_N		1.2	1.2			
					$M_{0,max}$		2.1	4.1			
					M_{max}		3.6	6.2			
					n_{eto}		3417	1149			
09D41L	2.3	4050	4.6	1.00	M_0		2.5	3.3	3.3		
					M_N		2.0	2.3	2.3		
					$M_{0,max}$		2.5	4.9	8.8		
					M_{max}		4.4	8.0	9.5		
					n_{eto}		4091	2547	2170		
09D60L	1.8	6000	7.0	1.10	M_0			2.6	3.3	3.3	
					M_N			1.8	1.8	1.8	
					$M_{0,max}$			2.6	5.0	7.1	
					M_{max}			4.5	8.1	9.5	
					n_{eto}			7000	5373	4626	
09F38L	3.1	3750	5.0	1.20	M_0			4.2	4.2		
					M_N			3.1	3.1		
					$M_{0,max}$			6.1	10.8		
					M_{max}			9.8	15.0		
					n_{eto}			1149	1951		

► I... [A], M... [Nm], n... [r/min], P... [kW]

6.6

MCS synchronous servo motors

Technical data

Selection tables, Servo Drives ECS

Non-ventilated motors

► The data applies to a mains connection voltage of 3x230V   and
an inverter switching frequency of 4 kHz.

					ECS□□	004C□B	008C□B	016C□B	032C□B	048C□B	064C□B
					I_N	2.0	4.0	8.0	12.7	17.0	20.0
					$I_{0,max}$	2.3	4.6	9.1	18.1	27.2	36.3
MCS	M_N	n_N	I_N	P_N	I_{max}	4.0	8.0	16.0	32.0	48.0	64.0
09F60L	2.4	6000	7.9	1.50	M_0			3.2	4.2	4.2	4.2
					M_N			2.4	2.4	2.4	2.4
					$M_{0,max}$			3.6	6.8	9.6	11.9
					M_{max}			6.1	10.9	14.3	15.0
					n_{eto}			6985	3448	2612	2397
09H41L	3.8	4050	6.8	1.60	M_0			5.2	5.5	5.5	
					M_N			3.8	3.8	3.8	
					$M_{0,max}$			5.9	11.0	15.3	
					M_{max}			9.9	17.2	20.0	
					n_{eto}			1149	2138	1852	
09H60L	3.0	6000	8.0	1.90	M_0			3.7	5.5	5.5	5.5
					M_N			3.0	3.0	3.0	3.0
					$M_{0,max}$			4.1	8.0	11.5	14.5
					M_{max}			7.2	13.2	17.9	20.0
					n_{eto}			1149	4081	2984	2695
09L41L	4.5	4050	8.4	1.90	M_0			4.8	7.5	7.5	7.5
					M_N			4.3	4.5	4.5	4.5
					$M_{0,max}$			5.2	10.3	15.1	19.6
					M_{max}			9.1	17.5	25.1	31.9
					n_{eto}			4562	3243	2497	1909
12D20L	5.5	1950	5.2	1.10	M_0		4.7	6.4			
					M_N		4.2	5.5			
					$M_{0,max}$		4.6	9.0			
					M_{max}		8.0	14.9			
					n_{eto}		1878	1181			
12D41L	4.3	4050	8.8	1.80	M_0			4.8	6.4	6.4	
					M_N			3.9	4.3	4.3	
					$M_{0,max}$			4.6	9.2	13.3	
					M_{max}			8.1	15.2	17.9	
					n_{eto}			4102	2535	2187	
12H15L	10.0	1500	7.6	1.60	M_0			11.2	11.4		
					M_N			10.0	10.0		
					$M_{0,max}$			11.8	22.5		
					M_{max}			20.1	29.0		
					n_{eto}			1098	827		
12H30L	8.0	3000	10.5	2.50	M_0			6.8	10.7	11.4	
					M_N			6.1	8.0	8.0	
					$M_{0,max}$			7.2	14.3	20.9	
					M_{max}			12.7	24.3	29.0	
					n_{eto}			2831	1849	1591	
12L20L	13.5	1950	11.8	2.80	M_0				15.0	15.0	15.0
					M_N				13.5	13.5	13.5
					$M_{0,max}$				21.3	30.7	39.4
					M_{max}				35.4	49.3	56.0
					n_{eto}				1307	1004	866

► I... [A], M... [Nm], n... [r/min], P... [kW]

6.6

MCS synchronous servo motors

Technical data

Selection tables, Servo Drives ECS

Forced ventilated IP54 motors

► The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 4 kHz.

MCS	M_N	n_N	I_N	P_N	ECS□□	004C□B	008C□B	016C□B	032C□B	048C□B	064C□B
					I_N	2.0	4.0	8.0	12.7	17.0	20.0
					$I_{0,max}$	2.3	4.6	9.1	18.1	27.2	36.3
					I_{max}	4.0	8.0	16.0	32.0	48.0	64.0
12D17-	7.0	1650	3.0	1.20	M_0	4.7	7.5	7.5			
					M_N	4.2	7.0	7.0			
					$M_{0,max}$	4.6	9.1	17.0			
					M_{max}	8.0	15.3	17.7			
					n_{eto}	1730	1089	919			
12D35-	6.0	3525	5.6	2.20	M_0		4.7	7.5			
					M_N		3.8	6.0			
					$M_{0,max}$		4.6	8.8			
					M_{max}		7.8	14.7			
					n_{eto}		3902	2433			
12H14-	12.0	1350	4.1	1.70	M_0		11.2	12.8			
					M_N		10.6	12.0			
					$M_{0,max}$		11.9	22.6			
					M_{max}		20.1	29.0			
					n_{eto}		1220	918			
12H34-	10.5	3375	7.5	3.70	M_0		5.6	11.2	12.8		
					M_N		5.3	10.0	7.5		
					$M_{0,max}$		6.0	11.8	22.5		
					M_{max}		10.4	20.1	29.0		
					n_{eto}		3850	2838	2092		
12L17-	17.0	1650	6.7	2.90	M_0			19.0	19.0		
					M_N			17.0	17.0		
					$M_{0,max}$			21.4	39.4		
					M_{max}			35.5	56.4		
					n_{eto}			1324	863		
12L39-	14.0	3900	11.7	5.70	M_0			9.7	16.7	19.0	19.0
					M_N			8.6	14.0	14.0	14.0
					$M_{0,max}$			10.8	21.3	30.8	39.5
					M_{max}			19.0	35.5	49.6	56.4
					n_{eto}			4450	3013	2236	1907
14D14-	12.0	1350	5.4	1.70	M_0		8.8	12.5			
					M_N		8.2	12.0			
					$M_{0,max}$		9.6	17.9			
					M_{max}		15.9	28.3			
					n_{eto}		1141	689			
14D30-	10.5	3000	9.7	3.30	M_0			8.8	11.4		
					M_N			8.6	9.7		
					$M_{0,max}$			9.5	17.8		
					M_{max}			15.9	28.3		
					n_{eto}			2496	1614		
14H12-	23.5	1200	8.3	3.00	M_0			19.8	25.5		
					M_N			19.6	23.5		
					$M_{0,max}$			22.3	41.2		
					M_{max}			37.1	54.8		
					n_{eto}			920	667		

► I... [A], M... [Nm], n... [r/min], P... [kW]

6.6

Selection tables, Servo Drives ECS

Forced ventilated IP54 motors

► The data applies to a mains connection voltage of 3 x 400 V and
an inverter switching frequency of 4 kHz.

				ECS□□	004C□B	008C□B	016C□B	032C□B	048C□B	064C□B
				I_N	2.0	4.0	8.0	12.7	17.0	20.0
				$I_{0,max}$	2.3	4.6	9.1	18.1	27.2	36.3
MCS	M_N	n_N	I_N	P_N	I_{max}	4.0	8.0	16.0	32.0	48.0	64.0
14H28-	20.5	2775	15.0	6.00	M_0				15.8	23.5	25.5
					M_N				15.6	20.5	20.5
					$M_{0,max}$				22.2	32.1	41.3
					M_{max}				37.1	51.9	54.8
					n_{eto}				1953	1471	1409
14L14-	30.5	1350	11.8	4.30	M_0			18.7	32.7	34.5	
					M_N			19.0	30.5	30.5	
					$M_{0,max}$			21.9	42.1	59.9	
					M_{max}			37.6	68.5	77.1	
					n_{eto}			1284	828	767	
14L30-	25.5	3000	20.8	8.00	M_0					19.8	23.3
					M_N					19.7	23.3
					$M_{0,max}$					32.4	42.2
					M_{max}					53.9	68.5
					n_{eto}					2096	1757
14P11-	42.0	1050	13.4	4.60	M_0				39.1	43.5	43.5
					M_N				38.9	42.0	42.0
					$M_{0,max}$				49.1	70.0	88.4
					M_{max}				80.0	105.1	105.1
					n_{eto}				710	573	573
14P26-	33.0	2625	21.9	9.10	M_0					25.9	30.5
					M_N					25.6	30.1
					$M_{0,max}$					37.9	49.3
					M_{max}					63.0	80.0
					n_{eto}					1829	1495
19F12-	38.0	1200	11.3	4.80	M_0			25.9	41.5		
					M_N			25.1	38.0		
					$M_{0,max}$			28.6	54.6		
					M_{max}			48.9	86.0		
					n_{eto}			1204	746		
19F29-	32.5	2850	20.1	9.70	M_0					27.5	33.9
					M_N					27.4	32.5
					$M_{0,max}$					40.5	53.0
					M_{max}					68.3	86.0
					n_{eto}					2033	1653
19J12-	62.5	1200	18.3	7.90	M_0					59.0	69.4
					M_N					58.1	62.5
					$M_{0,max}$					82.8	82.8
					M_{max}					129.0	129.0
					n_{eto}					839	839
19J29-	50.5	2850	31.0	15.10	M_0						34.3
					M_N						32.6
					$M_{0,max}$						56.9
					M_{max}						96.0
					n_{eto}						2323

► I... [A], M... [Nm], n... [r/min], P... [kW]

6.6

Selection tables, Servo Drives ECS

Forced ventilated IP54 motors

► The data applies to a mains connection voltage of 3 x 400 V and
an inverter switching frequency of 4 kHz.

					ECS□□	004C□B	008C□B	016C□B	032C□B	048C□B	064C□B
					I_N	2.0	4.0	8.0	12.7	17.0	20.0
					$I_{0,max}$	2.3	4.6	9.1	18.1	27.2	36.3
MCS	M_N	n_N	I_N	P_N	I_{max}	4.0	8.0	16.0	32.0	48.0	64.0
19P12-	72.0	1200	21.3	9.00	M_0					62.2	76.8
					M_N					57.5	67.6
					$M_{0,max}$					91.5	120.1
					M_{max}					155.5	190.0
					n_{eto}					996	870
19P29-	53.0	2850	29.5	15.80	M_0						36.7
					M_N						35.9
					$M_{0,max}$						61.1
					M_{max}						106.7
					n_{eto}						2715

► I... [A], M... [Nm], n... [r/min], P... [kW]

Selection tables, Servo Inverter 9300

Non-ventilated motors

► The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 8 kHz.

					EVS	9321-E□	9322-E□	9323-E□	9324-E□	9325-E□	9326-E□	9327-E□	9328-E□	9329-E□
					I_N	1.5	2.5	3.9	7.0	13.0	23.5	32.0	47.0	59.0
					$I_{0,max}$	2.3	3.8	5.9	10.5	19.5	23.5	32.0	47.0	52.0
MCS	M_N	n_N	I_N	P_N	I_{max}	2.3	3.8	5.9	10.5	19.5	35.3	48.0	70.5	88.5
06C41-	0.6	4050	1.3	0.25	M_0	0.8	0.8	0.8						
					M_N	0.6	0.6	0.6						
					$M_{0,max}$	1.2	1.8	2.4						
					M_{max}	1.2	1.8	2.4						
					n_{eto}	4635	2871	2019						
06C60-	0.5	6000	2.4	0.31	M_0		0.8	0.8	0.8					
					M_N		0.5	0.5	0.5					
					$M_{0,max}$		1.0	1.5	2.4					
					M_{max}		1.0	1.5	2.4					
					n_{eto}		7000	7000	5368					
06F41-	1.2	4050	1.5	0.51	M_0	1.5	1.5	1.5						
					M_N	1.2	1.2	1.2						
					$M_{0,max}$	2.0	3.4	4.4						
					M_{max}	2.0	3.4	4.4						
					n_{eto}	2819	1973	1562						
06F60-	0.9	6000	2.5	0.57	M_0		1.3	1.5	1.5					
					M_N		0.9	0.9	0.9					
					$M_{0,max}$		1.7	3.0	4.4					
					M_{max}		1.7	3.0	4.4					
					n_{eto}		7000	5714	3773					
06I41-	1.5	4050	1.6	0.64	M_0	1.8	2.0	2.0						
					M_N	1.4	1.5	1.5						
					$M_{0,max}$	2.6	4.2	6.2						
					M_{max}	2.6	4.2	6.2						
					n_{eto}	2994	1980	1384						
06I60-	1.2	6000	2.9	0.75	M_0		1.5	2.0	2.0					
					M_N		1.0	1.2	1.2					
					$M_{0,max}$		2.1	3.3	5.7					
					M_{max}		2.1	3.3	5.7					
					n_{eto}		7000	5486	3414					
09D41-	2.3	4050	2.3	1.00	M_0	3.1	3.3	3.3						
					M_N	2.3	2.3	2.3						
					$M_{0,max}$	4.2	6.2	9.4						
					M_{max}	4.2	6.2	9.4						
					n_{eto}	4895	2937	2008						
09D60-	1.8	6000	3.8	1.10	M_0			2.4	3.3	3.3				
					M_N			1.8	1.8	1.8				
					$M_{0,max}$			3.2	5.6	9.3				
					M_{max}			3.2	5.6	9.3				
					n_{eto}			7000	7000	4492				
09F38-	3.1	3750	2.5	1.20	M_0		3.5	4.2	4.2					
					M_N		3.1	3.1	3.1					
					$M_{0,max}$		5.2	7.7	12.0					
					M_{max}		5.2	7.7	12.0					
					n_{eto}		4000	3250	2173					

► I... [A], M... [Nm], n... [r/min], P... [kW]

_____

Selection tables, Servo Inverter 9300

Non-ventilated motors

► The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 8 kHz.

					EVS	9321-E□	9322-E□	9323-E□	9324-E□	9325-E□	9326-E□	9327-E□	9328-E□	9329-E□
					I_N	1.5	2.5	3.9	7.0	13.0	23.5	32.0	47.0	59.0
					$I_{0,max}$	2.3	3.8	5.9	10.5	19.5	23.5	32.0	47.0	52.0
MCS	M_N	n_N	I_N	P_N	I_{max}	2.3	3.8	5.9	10.5	19.5	35.3	48.0	70.5	88.5
09F60-	2.4	6000	4.5	1.50	M_0				4.2	4.2				
					M_N				2.4	2.4				
					$M_{0,max}$				6.9	11.4				
					M_{max}				6.9	11.4				
					n_{eto}				7000	5035				
09H41-	3.8	4050	3.4	1.60	M_0			5.0	5.5	5.5				
					M_N			3.8	3.8	3.8				
					$M_{0,max}$			7.5	12.5	20.1				
					M_{max}			7.5	12.5	20.1				
					n_{eto}			4250	2977	1988				
09H60-	3.0	6000	6.0	1.90	M_0				4.5	5.5				
					M_N				3.0	3.0				
					$M_{0,max}$				6.7	11.7				
					M_{max}				6.7	11.7				
					n_{eto}				7000	7000				
09L41-	4.5	4050	4.2	1.90	M_0			4.7	7.5	7.5				
					M_N			4.2	4.5	4.5				
					$M_{0,max}$			6.7	11.7	20.8				
					M_{max}			6.7	11.7	20.8				
					n_{eto}			4450	4154	2796				
09L51-	3.6	5100	6.9	1.90	M_0				4.2	7.5	7.5			
					M_N				3.6	3.6	3.6			
					$M_{0,max}$				6.0	11.1	13.2			
					M_{max}				6.0	11.1	19.1			
					n_{eto}				7000	7000	7000			
12D20-	5.5	1950	2.6	1.10	M_0		5.9	6.4	6.4					
					M_N		5.3	5.5	5.5					
					$M_{0,max}$		7.6	11.6	17.7					
					M_{max}		7.6	11.6	17.7					
					n_{eto}		1790	1358	919					
12D41-	4.3	4050	4.5	1.80	M_0			4.6	6.4	6.4				
					M_N			3.7	4.3	4.3				
					$M_{0,max}$			5.9	10.1	17.3				
					M_{max}			5.9	10.1	17.3				
					n_{eto}			4344	3275	2116				
12H15-	10.0	1500	3.8	1.60	M_0			10.9	11.4	11.4				
					M_N			10.0	10.0	10.0				
					$M_{0,max}$			15.1	25.8	29.0				
					M_{max}			15.1	25.8	29.0				
					n_{eto}			1676	1013	918				
12H35-	7.5	3525	5.7	2.80	M_0				9.8	11.4				
					M_N				7.5	7.5				
					$M_{0,max}$				13.5	24.1				
					M_{max}				13.5	24.1				
					n_{eto}				3618	2447				

► I... [A], M... [Nm], n... [r/min], P... [kW]

6.6

Selection tables, Servo Inverter 9300

Non-ventilated motors

► The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 8 kHz.

				EVS	9321-E□	9322-E□	9323-E□	9324-E□	9325-E□	9326-E□	9327-E□	9328-E□	9329-E□
				I_N	1.5	2.5	3.9	7.0	13.0	23.5	32.0	47.0	59.0
				$I_{0,max}$	2.3	3.8	5.9	10.5	19.5	23.5	32.0	47.0	52.0
MCS	M_N	n_N	I_N	P_N — I_{max}	2.3	3.8	5.9	10.5	19.5	35.3	48.0	70.5	88.5
12L20-	13.5	1950	5.9	2.80 — M_0				15.0	15.0				
				M_N				13.5	13.5				
				$M_{0,max}$				24.4	41.9				
				M_{max}				24.4	41.9				
				n_{eto}				1718	1158				
12L41-	11.0	4050	10.2	4.70 — M_0					15.0	15.0	15.0		
				M_N					11.0	11.0	11.0		
				$M_{0,max}$					22.8	27.0	35.5		
				M_{max}					22.8	38.5	49.6		
				n_{eto}					4287	2799	2236		
14D15-	9.2	1500	4.5	1.45 — M_0			8.5	11.0	11.0				
				M_N			8.0	9.2	9.2				
				$M_{0,max}$			12.1	20.2	29.0				
				M_{max}			12.1	20.2	29.0				
				n_{eto}			1437	928	676				
14D36-	7.5	3600	7.5	2.80 — M_0				7.7	11.0	11.0			
				M_N				7.0	7.5	7.5			
				$M_{0,max}$				10.9	19.0	22.2			
				M_{max}				10.9	19.0	29.0			
				n_{eto}				3479	2159	1593			
14H15-	16.0	1500	6.6	2.50 — M_0				17.3	21.0				
				M_N				16.0	16.0				
				$M_{0,max}$				25.4	43.9				
				M_{max}				25.4	43.9				
				n_{eto}				1247	800				
14H32-	14.0	3225	11.9	4.70 — M_0					16.2	21.0	21.0		
				M_N					14.0	14.0	14.0		
				$M_{0,max}$					23.8	28.2	37.1		
				M_{max}					23.8	40.2	51.9		
				n_{eto}					2875	1817	1471		
14L15-	23.0	1500	9.7	3.60 — M_0					28.0	28.0			
				M_N					23.0	23.0			
				$M_{0,max}$					45.0	52.9			
				M_{max}					45.0	73.8			
				n_{eto}					1126	788			
14L32-	17.2	3225	15.0	5.80 — M_0					15.2	27.4	28.0	28.0	
				M_N					14.9	17.2	17.2	17.2	
				$M_{0,max}$					23.5	28.3	37.6	52.9	
				M_{max}					23.5	41.0	53.9	73.9	
				n_{eto}					3953	2608	2096	1672	
14P14-	30.0	1350	10.8	4.20 — M_0					37.0	37.0	37.0		
				M_N					30.0	30.0	30.0		
				$M_{0,max}$					52.5	61.8	80.0		
				M_{max}					52.5	86.3	105.1		
				n_{eto}					998	668	573		

► I... [A], M... [Nm], n... [r/min], P... [kW]

6.6

Selection tables, Servo Inverter 9300

Non-ventilated motors

► The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 8 kHz.

					EVS	9321-E□	9322-E□	9323-E□	9324-E□	9325-E□	9326-E□	9327-E□	9328-E□	9329-E□
					I_N	1.5	2.5	3.9	7.0	13.0	23.5	32.0	47.0	59.0
					$I_{0,max}$	2.3	3.8	5.9	10.5	19.5	23.5	32.0	47.0	52.0
MCS	M_N	n_N	I_N	P_N	I_{max}	2.3	3.8	5.9	10.5	19.5	35.3	48.0	70.5	88.5
14P32-	21.0	3225	15.6	7.10	M_0					19.8	35.8	37.0	37.0	
					M_N					17.5	21.0	21.0	21.0	
					$M_{0,max}$					27.4	33.0	43.9	61.8	
					M_{max}					27.4	47.9	63.0	86.4	
					n_{eto}					3300	2299	1829	1404	
19F14-	27.0	1425	8.6	4.00	M_0				22.6	32.0	32.0			
					M_N				22.0	27.0	27.0			
					$M_{0,max}$				33.0	58.2	68.3			
					M_{max}				33.0	58.2	86.0			
					n_{eto}				1459	1056	746			
19F30-	21.0	3000	14.0	6.60	M_0					21.0	32.0	32.0		
					M_N					19.5	21.0	21.0		
					$M_{0,max}$					29.2	35.2	47.2		
					M_{max}					29.2	51.5	68.3		
					n_{eto}					3352	2573	2033		
19J14-	40.0	1425	12.3	6.00	M_0					43.6	51.0	51.0		
					M_N					40.0	40.0	40.0		
					$M_{0,max}$					60.8	72.4	96.0		
					M_{max}					60.8	104.5	129.0		
					n_{eto}					1376	996	839		
19J30-	29.0	3000	18.5	9.10	M_0						39.3	51.0	51.0	51.0
					M_N						29.0	29.0	29.0	29.0
					$M_{0,max}$						36.8	50.2	72.4	79.5
					M_{max}						55.2	73.8	104.7	127.6
					n_{eto}						3150	2850	2162	1817
19P14-	51.0	1350	14.3	7.20	M_0					47.5	64.0	64.0		
					M_N					46.4	51.0	51.0		
					$M_{0,max}$					69.5	79.6	106.7		
					M_{max}					69.5	116.7	155.5		
					n_{eto}					1400	1187	996		
19P30-	32.0	3000	19.0	10.00	M_0						43.1	58.7	64.0	64.0
					M_N						32.0	32.0	32.0	32.0
					$M_{0,max}$						39.6	53.9	79.6	87.6
					M_{max}						59.3	81.2	116.9	144.3
					n_{eto}						3000	2938	2638	2298

► I... [A], M... [Nm], n... [r/min], P... [kW]

6.6

Selection tables, Servo Inverter 9300

Forced ventilated IP54 motors

► The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 8 kHz.

					EVS	9322-E□	9323-E□	9324-E□	9325-E□	9326-E□	9327-E□	9328-E□	9329-E□
					I_N	2.5	3.9	7.0	13.0	23.5	32.0	47.0	59.0
					$I_{0,max}$	3.8	5.9	10.5	19.5	23.5	32.0	47.0	52.0
MCS	M_N	n_N	I_N	P_N	I_{max}	3.8	5.9	10.5	19.5	35.3	48.0	70.5	88.5
12D17-	7.0	1650	3.0	1.20	M_0	5.9	7.5	7.5					
					M_N	5.3	7.0	7.0					
					$M_{0,max}$	7.6	11.6	17.7					
					M_{max}	7.6	11.6	17.7					
					n_{eto}	1790	1358	919					
12D35-	6.0	3525	5.6	2.20	M_0		4.6	7.5	7.5				
					M_N		3.7	6.0	6.0				
					$M_{0,max}$		5.9	10.1	17.3				
					M_{max}		5.9	10.1	17.3				
					n_{eto}		4344	3275	2116				
12H14-	12.0	1350	4.1	1.70	M_0		10.9	12.8	12.8				
					M_N		10.3	12.0	12.0				
					$M_{0,max}$		15.1	25.8	29.0				
					M_{max}		15.1	25.8	29.0				
					n_{eto}		1676	1013	918				
12H34-	10.5	3375	7.5	3.70	M_0			9.8	12.8				
					M_N			9.6	10.5				
					$M_{0,max}$			13.5	24.1				
					M_{max}			13.5	24.1				
					n_{eto}			3618	2447				
12L17-	17.0	1650	6.7	2.90	M_0			18.5	19.0				
					M_N			17.0	17.0				
					$M_{0,max}$			24.4	41.9				
					M_{max}			24.4	41.9				
					n_{eto}			1718	1158				
12L39-	14.0	3900	11.7	5.70	M_0				17.2	19.0	19.0		
					M_N				14.0	14.0	14.0		
					$M_{0,max}$				22.8	27.0	35.5		
					M_{max}				22.8	38.5	49.6		
					n_{eto}				4287	2799	2236		
14D14-	12.0	1350	5.4	1.70	M_0		8.5	12.5	12.5				
					M_N		8.0	12.0	12.0				
					$M_{0,max}$		12.1	20.2	29.0				
					M_{max}		12.1	20.2	29.0				
					n_{eto}		1437	928	676				
14D30-	10.5	3000	9.7	3.30	M_0			7.7	12.5	12.5			
					M_N			7.0	10.0	10.0			
					$M_{0,max}$			10.9	19.0	22.2			
					M_{max}			10.9	19.0	29.0			
					n_{eto}			3479	2159	1593			
14H12-	23.5	1200	8.3	3.00	M_0			17.3	25.5				
					M_N			17.2	23.5				
					$M_{0,max}$			25.4	43.9				
					M_{max}			25.4	43.9				
					n_{eto}			1247	800				

► I... [A], M... [Nm], n... [r/min], P... [kW]

6.6

MCS synchronous servo motors

Technical data

Selection tables, Servo Inverter 9300

Forced ventilated IP54 motors

► The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 8 kHz.

					EVS	9322-E□	9323-E□	9324-E□	9325-E□	9326-E□	9327-E□	9328-E□	9329-E□
					I_N	2.5	3.9	7.0	13.0	23.5	32.0	47.0	59.0
					$I_{0,max}$	3.8	5.9	10.5	19.5	23.5	32.0	47.0	52.0
MCS	M_N	n_N	I_N	P_N	I_{max}	3.8	5.9	10.5	19.5	35.3	48.0	70.5	88.5
14H28-	20.5	2775	15.0	6.00	M_0				16.2	25.5	25.5		
					M_N				16.1	20.5	20.5		
					$M_{0,max}$				23.8	28.2	37.1		
					M_{max}				23.8	40.2	51.9		
					n_{eto}				2875	1817	1471		
14L14-	30.5	1350	11.8	4.30	M_0				33.4	34.5			
					M_N				30.5	30.5			
					$M_{0,max}$				45.0	52.9			
					M_{max}				45.0	73.8			
					n_{eto}				1126	788			
14L30-	25.5	3000	20.8	8.00	M_0					27.4	34.5	34.5	
					M_N					25.5	25.5	25.5	
					$M_{0,max}$					28.3	37.6	52.9	
					M_{max}					41.0	53.9	73.9	
					n_{eto}					2608	2096	1672	
14P11-	42.0	1050	13.4	4.60	M_0				40.1	43.5	43.5		
					M_N				40.0	42.0	42.0		
					$M_{0,max}$				52.5	61.8	80.0		
					M_{max}				52.5	86.3	105.1		
					n_{eto}				998	668	573		
14P26-	33.0	2625	21.9	9.10	M_0					35.8	43.5	43.5	
					M_N					33.0	33.0	33.0	
					$M_{0,max}$					33.0	43.9	61.8	
					M_{max}					47.9	63.0	86.4	
					n_{eto}					2299	1829	1404	
19F12-	38.0	1200	11.3	4.80	M_0			22.6	41.5	41.5			
					M_N			22.0	38.0	38.0			
					$M_{0,max}$			33.0	58.2	68.3			
					M_{max}			33.0	58.2	86.0			
					n_{eto}			1459	1056	746			
19F29-	32.5	2850	20.1	9.70	M_0					39.9	41.5		
					M_N					32.5	32.5		
					$M_{0,max}$					35.2	47.2		
					M_{max}					51.5	68.3		
					n_{eto}					2573	2033		
19J12-	62.5	1200	18.3	7.90	M_0				43.6	70.5	70.5		
					M_N				43.4	62.5	62.5		
					$M_{0,max}$				60.8	72.4	96.0		
					M_{max}				60.8	104.5	129.0		
					n_{eto}				1376	996	839		
19J29-	50.5	2850	31.0	15.10	M_0						55.5	70.5	70.5
					M_N						50.5	50.5	50.5
					$M_{0,max}$						50.2	72.4	79.5
					M_{max}						73.8	104.7	127.6
					n_{eto}						2850	2162	1817

► I... [A], M... [Nm], n... [r/min], P... [kW]

6.6

Selection tables, Servo Inverter 9300

Forced ventilated IP54 motors

► The data applies to a mains connection voltage of 3 x 400 V and
an inverter switching frequency of 8 kHz.

					EVS	9322-E☐	9323-E☐	9324-E☐	9325-E☐	9326-E☐	9327-E☐	9328-E☐	9329-E☐
					I_N	2.5	3.9	7.0	13.0	23.5	32.0	47.0	59.0
					$I_{0,max}$	3.8	5.9	10.5	19.5	23.5	32.0	47.0	52.0
MCS	M_N	n_N	I_N	P_N	I_{max}	3.8	5.9	10.5	19.5	35.3	48.0	70.5	88.5
19P12-	72.0	1200	21.3	9.00	M_0				47.5	86.0	86.0		
					M_N				46.4	72.0	72.0		
					$M_{0,max}$				69.5	79.6	106.7		
					M_{max}				69.5	116.7	155.5		
					n_{eto}				1400	1187	996		
19P29-	53.0	2850	29.5	15.80	M_0						58.7	86.0	86.0
					M_N						53.0	53.0	53.0
					$M_{0,max}$						53.9	79.6	87.6
					M_{max}						81.2	116.9	144.3
					n_{eto}						2938	2638	2298

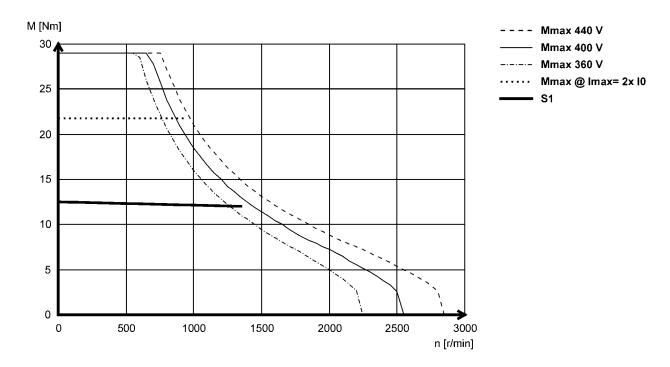► I... [A], M... [Nm], n... [r/min], P... [kW]
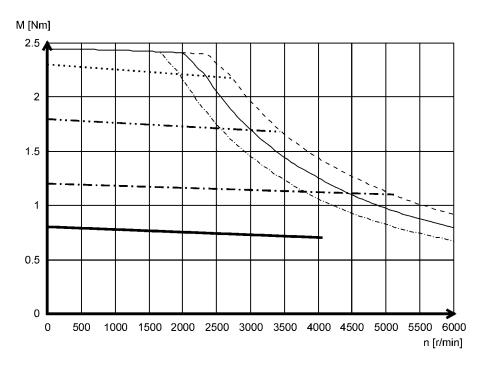
MCS synchronous servo motors

Technical data

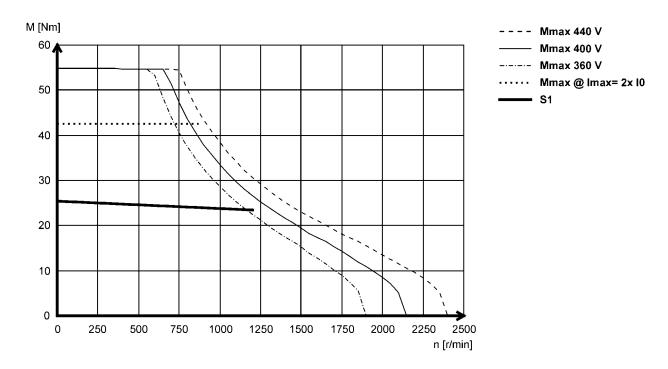## Torque characteristics
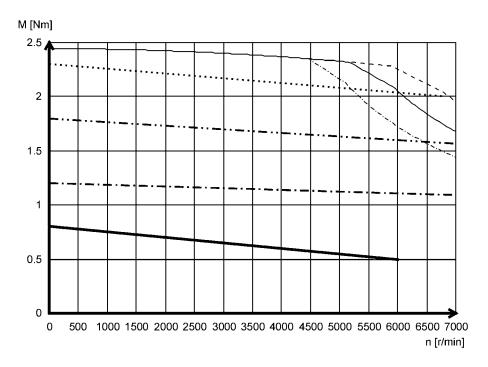
► The data applies to a mains connection voltage of 3 x 400 V.

MCS06C41- (non-ventilated)

M [Nm]

Legend:
- - - - Mmax 440 V
- ——— Mmax 400 V
- -·-·- Mmax 360 V
- ······ Mmax @ Imax= 4x I0
- -··-·· Mmax @ Imax= 3x I0
- -·-·- Mmax @ Imax= 2x I0
- ——— S1

n [r/min]

MCS06C60- (non-ventilated)

M [Nm]

Legend:
- - - - Mmax 440 V
- ——— Mmax 400 V
- -·-·- Mmax 360 V
- ······ Mmax @ Imax= 4x I0
- -··-·· Mmax @ Imax= 3x I0
- -·-·- Mmax @ Imax= 2x I0
- ——— S1

n [r/min]

6.6

Torque characteristics
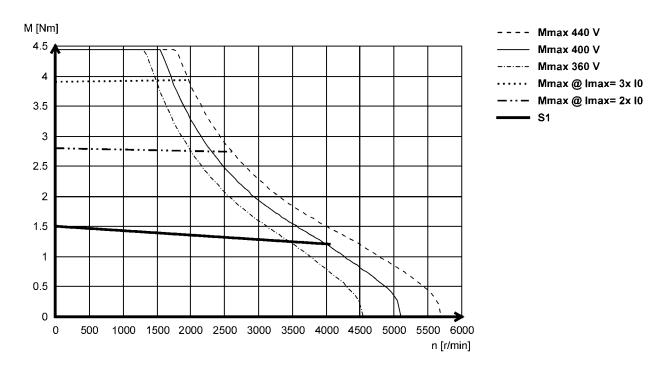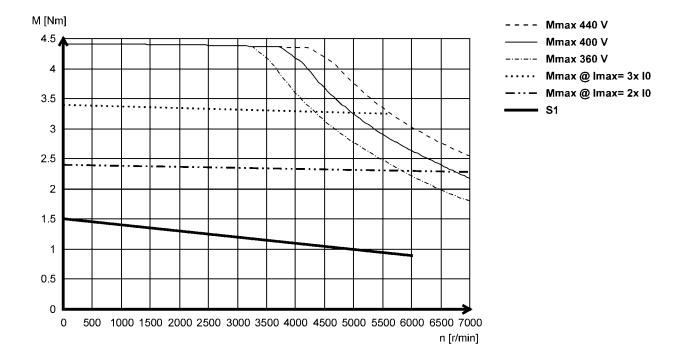
► The data applies to a mains connection voltage of 3 x 400 V.

MCS06F41- (non-ventilated)
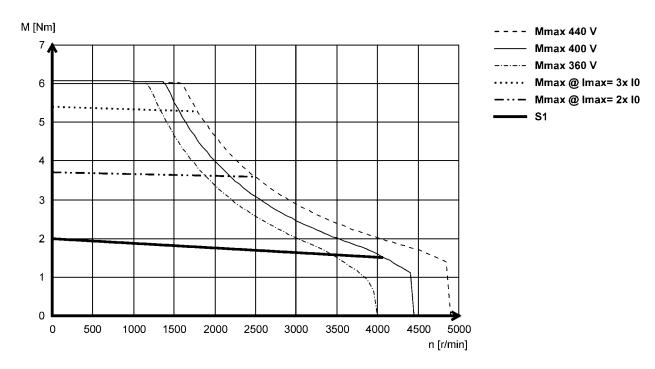
Legend	
- - - -	Mmax 440 V
——	Mmax 400 V
—·—·—	Mmax 360 V
·······	Mmax @ Imax= 3x I0
—··—··—	Mmax @ Imax= 2x I0
——	S1

MCS06F60- (non-ventilated)

Legend	
- - - -	Mmax 440 V
——	Mmax 400 V
—·—·—	Mmax 360 V
·······	Mmax @ Imax= 3x I0
—··—··—	Mmax @ Imax= 2x I0
——	S1

Torque characteristics
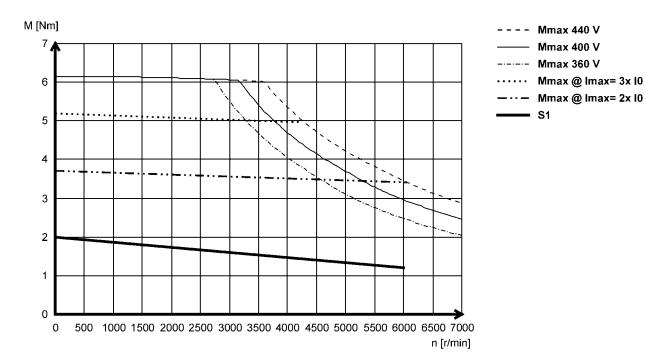
► The data applies to a mains connection voltage of 3 x 400 V.

MCS06I41- (non-ventilated)

- - - -	Mmax 440 V
———	Mmax 400 V
—·—·—	Mmax 360 V
··········	Mmax @ Imax= 3x I0
—··—··—	Mmax @ Imax= 2x I0
———	S1

MCS06I60- (non-ventilated)
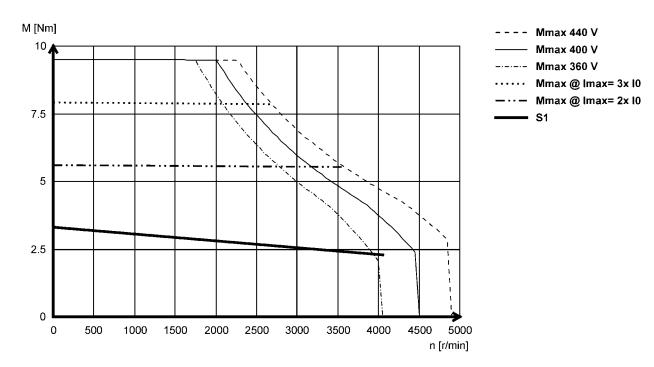
- - - -	Mmax 440 V
———	Mmax 400 V
—·—·—	Mmax 360 V
··········	Mmax @ Imax= 3x I0
—··—··—	Mmax @ Imax= 2x I0
———	S1

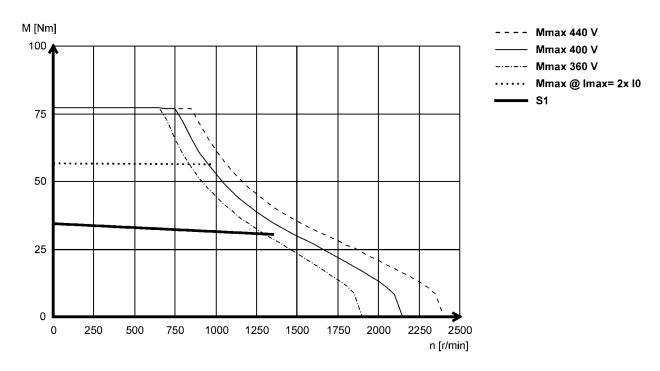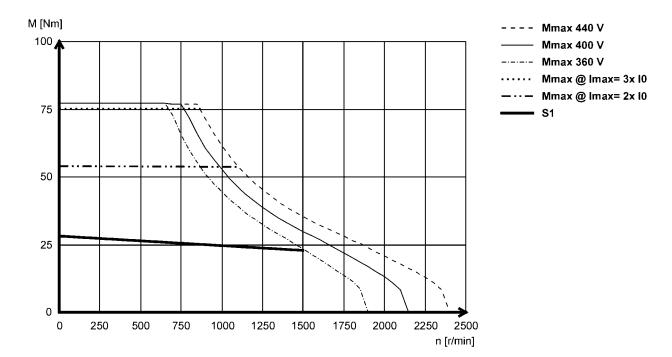6.6

MCS synchronous servo motors

Technical data

Torque characteristics
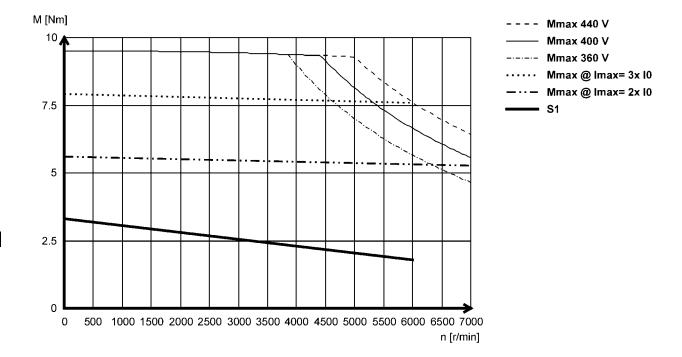
► The data applies to a mains connection voltage of 3 x 400 V.

MCS09D41- (non-ventilated)

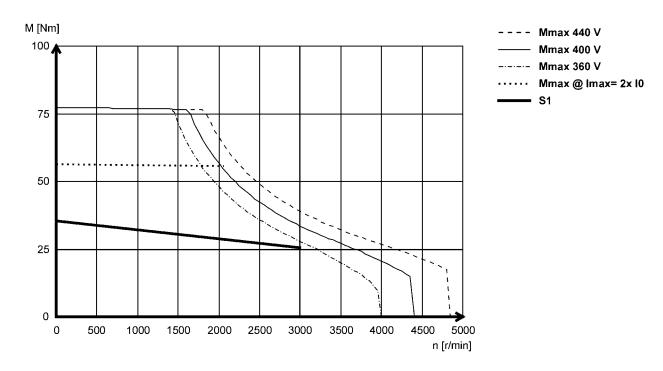

MCS09D60- (non-ventilated)
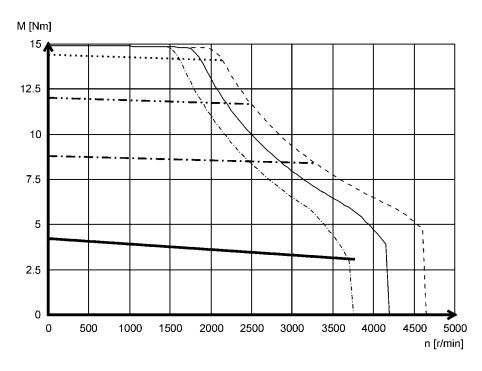
6.6

MCS synchronous servo motors

Technical data

Torque characteristics
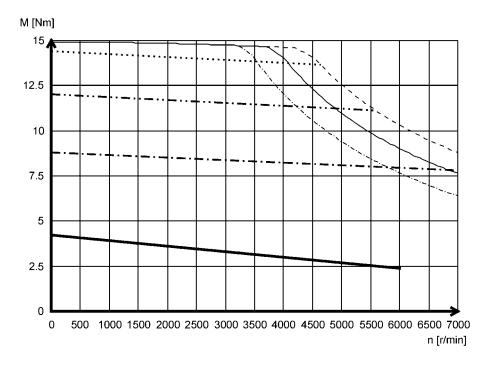
► The data applies to a mains connection voltage of 3 x 400 V.

MCS09F38- (non-ventilated)

Legend:
- --- Mmax 440 V
- —— Mmax 400 V
- —·—· Mmax 360 V
- ······ Mmax @ Imax= 4x I0
- —··—·· Mmax @ Imax= 3x I0
- —·—· Mmax @ Imax= 2x I0
- —— S1

MCS09F60- (non-ventilated)

Legend:
- --- Mmax 440 V
- —— Mmax 400 V
- —·—· Mmax 360 V
- ······ Mmax @ Imax= 4x I0
- —··—·· Mmax @ Imax= 3x I0
- —·—· Mmax @ Imax= 2x I0
- —— S1

MCS synchronous servo motors

Technical data

Torque characteristics
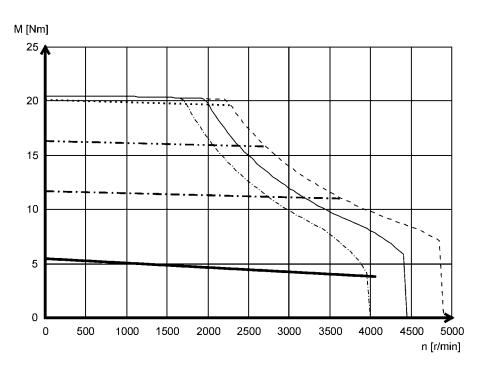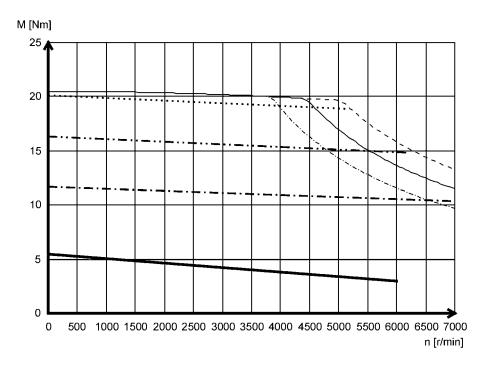
▶ The data applies to a mains connection voltage of 3 x 400 V.

MCS09H41- (non-ventilated)

Legend:
- - - - Mmax 440 V
- —— Mmax 400 V
- —·—· Mmax 360 V
- ······ Mmax @ Imax= 4x I0
- —··— Mmax @ Imax= 3x I0
- —·— Mmax @ Imax= 2x I0
- —— S1

MCS09H60- (non-ventilated)
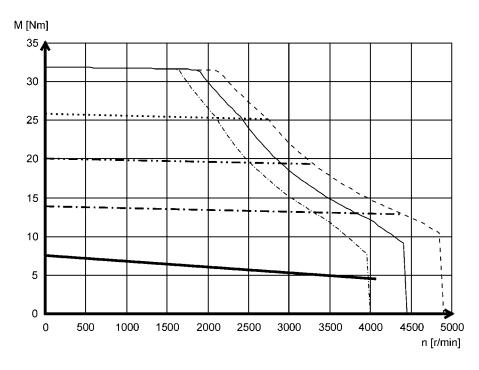
Legend:
- - - - Mmax 440 V
- —— Mmax 400 V
- —·—· Mmax 360 V
- ······ Mmax @ Imax= 4x I0
- —··— Mmax @ Imax= 3x I0
- —·— Mmax @ Imax= 2x I0
- —— S1

Torque characteristics
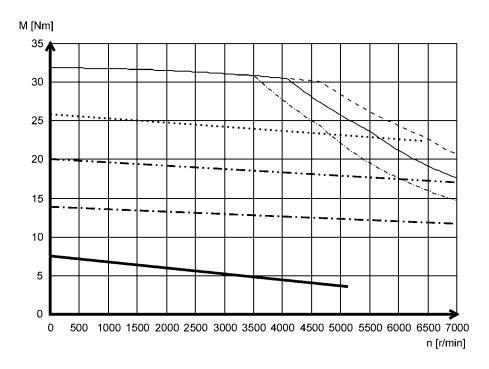
► The data applies to a mains connection voltage of 3 x 400 V.

MCS09L41- (non-ventilated)

Legend:
- - - - Mmax 440 V
- —— Mmax 400 V
- —·—· Mmax 360 V
- ······ Mmax @ Imax= 4x I0
- —··—·· Mmax @ Imax= 3x I0
- —·—· Mmax @ Imax= 2x I0
- —— S1

MCS09L51- (non-ventilated)

Legend:
- - - - Mmax 440 V
- —— Mmax 400 V
- —·—· Mmax 360 V
- ······ Mmax @ Imax= 4x I0
- —··—·· Mmax @ Imax= 3x I0
- —·—· Mmax @ Imax= 2x I0
- —— S1

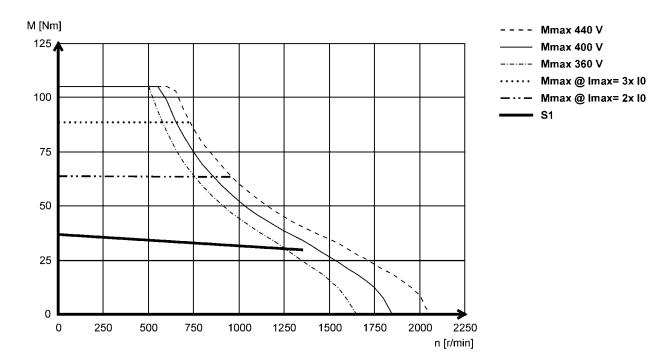## Torque characteristics
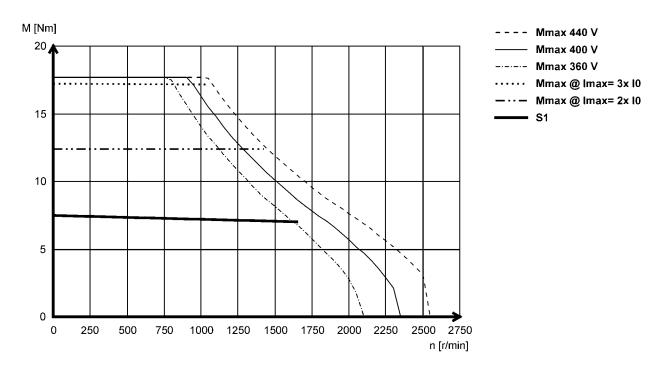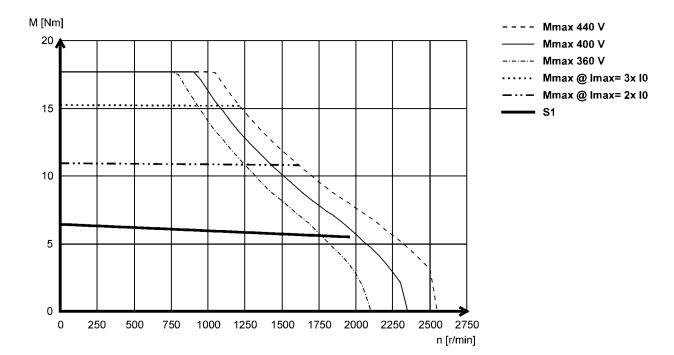
► The data applies to a mains connection voltage of 3 x 400 V.

MCS12D17 (forced ventilated)

MCS12D20- (non-ventilated)
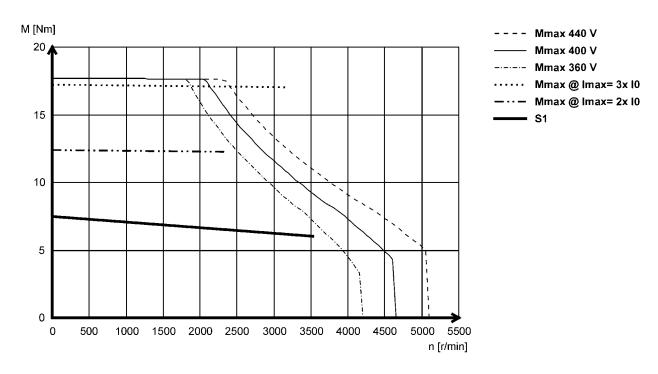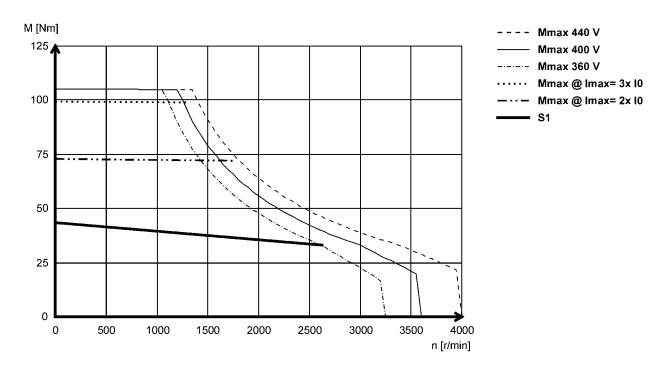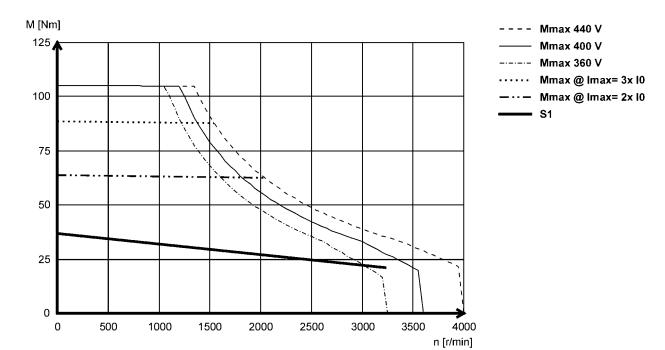
MCS synchronous servo motors

Technical data

Torque characteristics
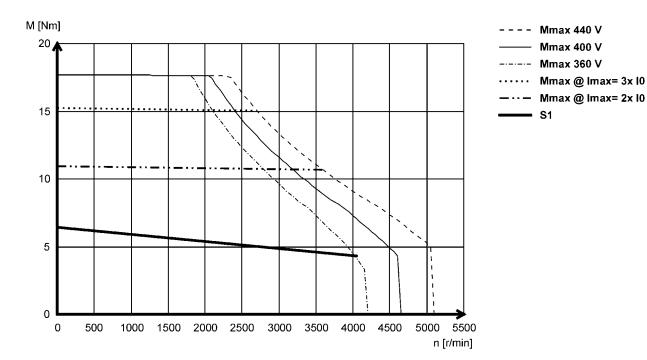
► The data applies to a mains connection voltage of 3 x 400 V.

MCS12D35- (forced ventilated)
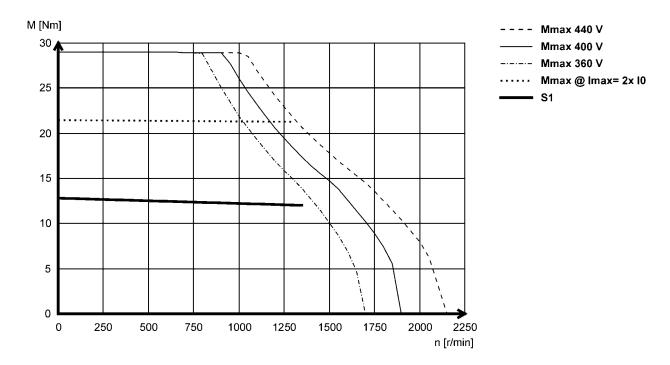
Legend:
- - - - Mmax 440 V
——— Mmax 400 V
—·—·— Mmax 360 V
········ Mmax @ Imax= 3x I0
—··—··— Mmax @ Imax= 2x I0
——— S1

MCS12D41- (non-ventilated)

Legend:
- - - - Mmax 440 V
——— Mmax 400 V
—·—·— Mmax 360 V
········ Mmax @ Imax= 3x I0
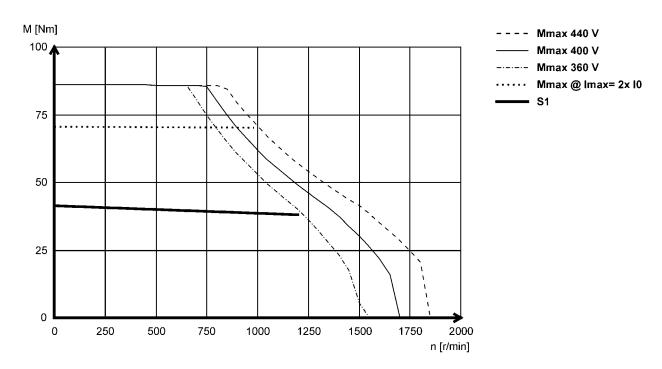—··—··— Mmax @ Imax= 2x I0
——— S1

6.6

MCS synchronous servo motors

Technical data

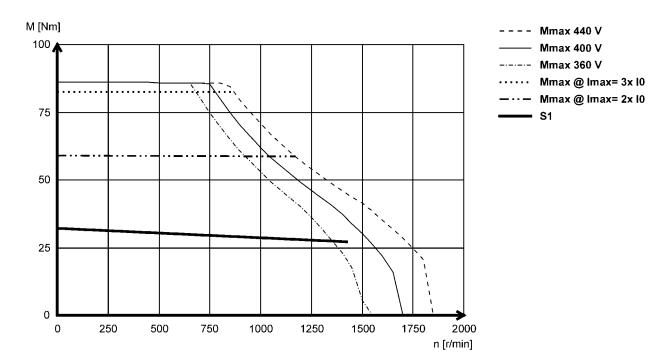### Torque characteristics
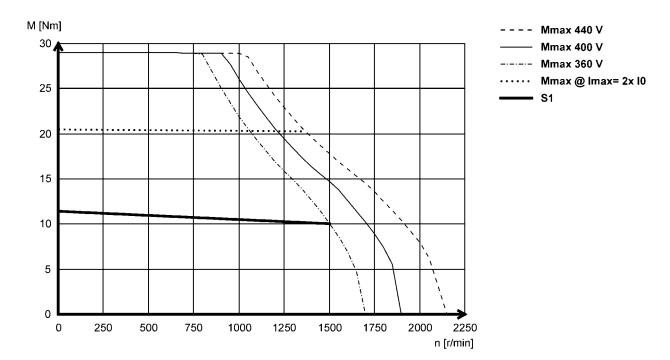
► The data applies to a mains connection voltage of 3 x 400 V.

MCS12H14- (forced ventilated)
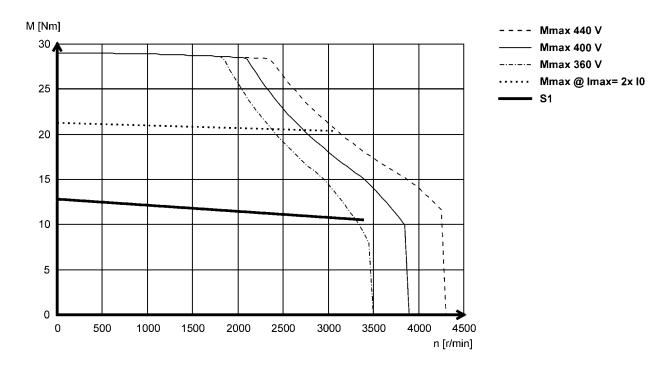
Legend:
- – – – Mmax 440 V
- ——— Mmax 400 V
- –·–·– Mmax 360 V
- ······· Mmax @ Imax= 2x I0
- ——— S1

MCS12H15- (non-ventilated)

Legend:
- – – – Mmax 440 V
- ——— Mmax 400 V
- –·–·– Mmax 360 V
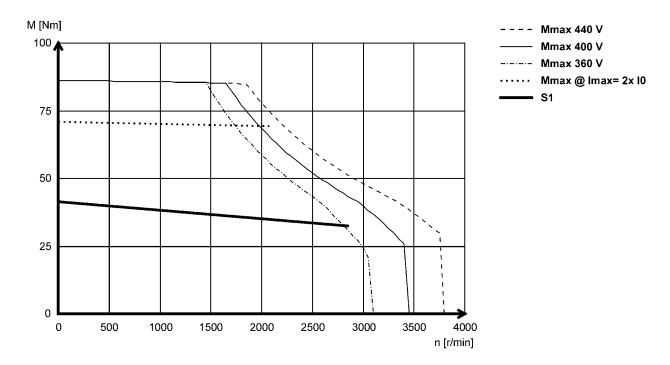- ······· Mmax @ Imax= 2x I0
- ——— S1

MCS synchronous servo motors

Technical data

Torque characteristics
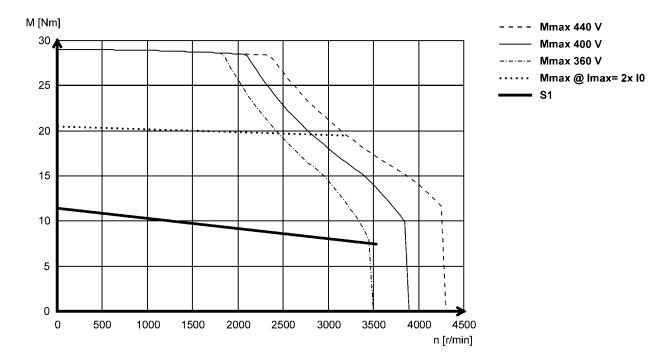
► The data applies to a mains connection voltage of 3 x 400 V.

MCS12H34- (forced ventilated)

Legend:
- - - - Mmax 440 V
- —— Mmax 400 V
- -·-·- Mmax 360 V
- ······ Mmax @ Imax= 2x I0
- —— S1

MCS12H35- (non-ventilated)

Legend:
- - - - Mmax 440 V
- —— Mmax 400 V
- -·-·- Mmax 360 V
- ······ Mmax @ Imax= 2x I0
- —— S1
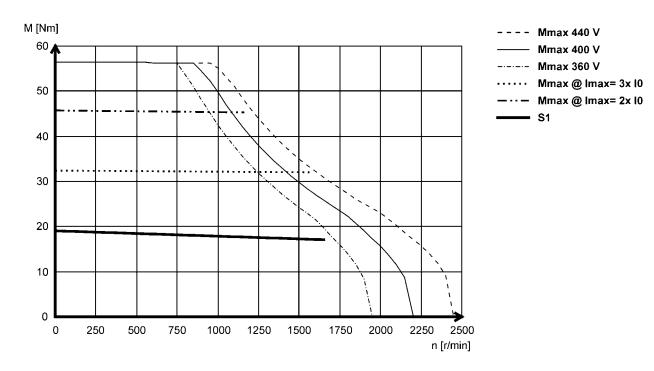
MCS synchronous servo motors

Technical data

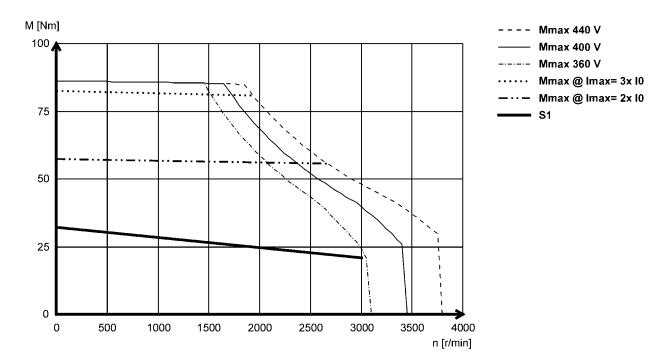## Torque characteristics
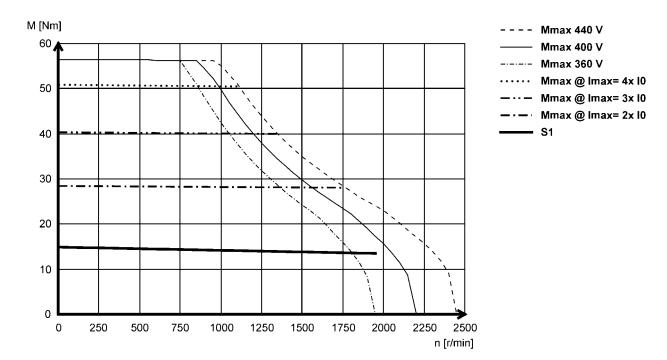
► The data applies to a mains connection voltage of 3 x 400 V.

MCS12L17- (forced ventilated)
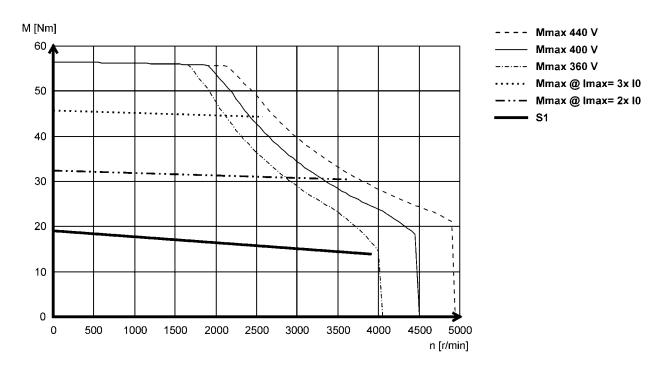
Legend:
- - - - Mmax 440 V
- —— Mmax 400 V
- —·—· Mmax 360 V
- ······ Mmax @ Imax= 3x I0
- —··— Mmax @ Imax= 2x I0
- —— S1

MCS12L20- (non-ventilated)

Legend:
- - - - Mmax 440 V
- —— Mmax 400 V
- —·—· Mmax 360 V
- ······ Mmax @ Imax= 4x I0
- —··— Mmax @ Imax= 3x I0
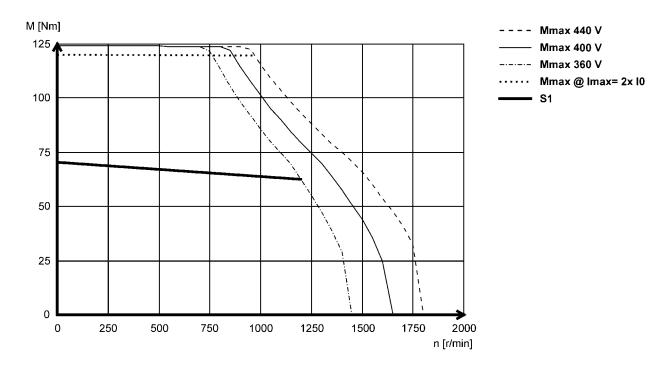- —·—· Mmax @ Imax= 2x I0
- —— S1

MCS synchronous servo motors

Technical data

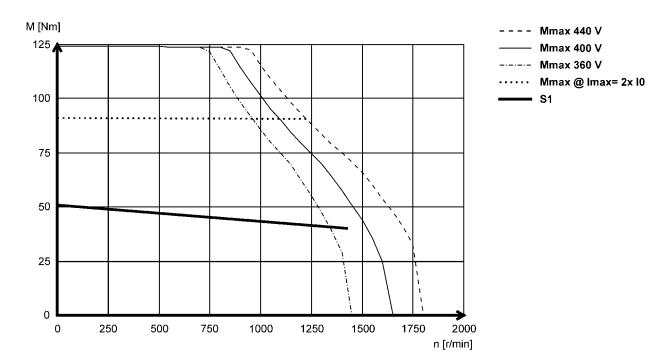## Torque characteristics
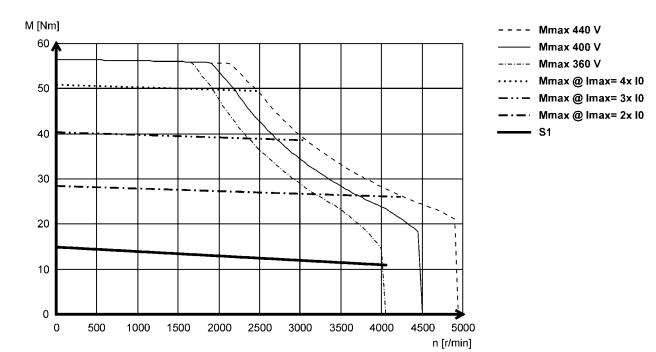
► The data applies to a mains connection voltage of 3 x 400 V.

MCS12L39- (forced ventilated)

Legend:
- Mmax 440 V (- - - -)
- Mmax 400 V (——)
- Mmax 360 V (-·-·-)
- Mmax @ Imax= 3x I0 (······)
- Mmax @ Imax= 2x I0 (-··-··)
- S1 (——)

MCS12L41- (non-ventilated)

Legend:
- Mmax 440 V (- - - -)
- Mmax 400 V (——)
- Mmax 360 V (-·-·-)
- Mmax @ Imax= 4x I0 (······)
- Mmax @ Imax= 3x I0 (-··-··)
- Mmax @ Imax= 2x I0 (-·-·-)
- S1 (——)

MCS synchronous servo motors

Technical data

Torque characteristics
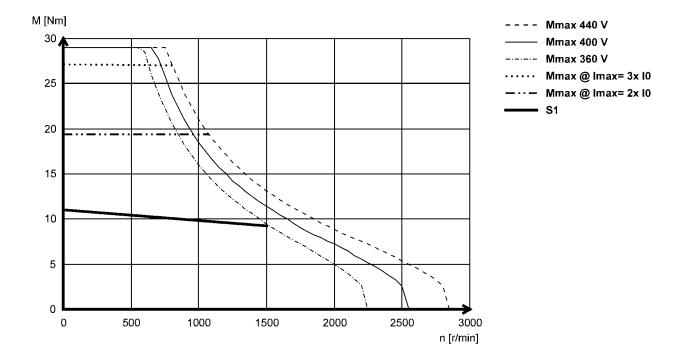
► The data applies to a mains connection voltage of 3 x 400 V.

MCS14D14- (forced ventilated)

– – – –	Mmax 440 V
———	Mmax 400 V
– · – · –	Mmax 360 V
· · · · ·	Mmax @ Imax= 2x I0
———	S1

MCS14D15- (non-ventilated)
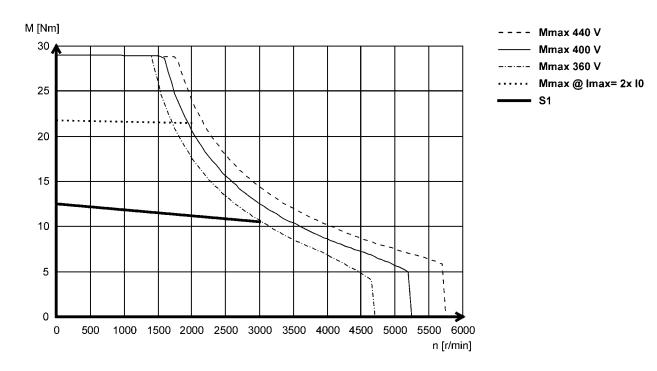
– – – –	Mmax 440 V
———	Mmax 400 V
– · – · –	Mmax 360 V
· · · · ·	Mmax @ Imax= 3x I0
– · · – · ·	Mmax @ Imax= 2x I0
———	S1

Torque characteristics
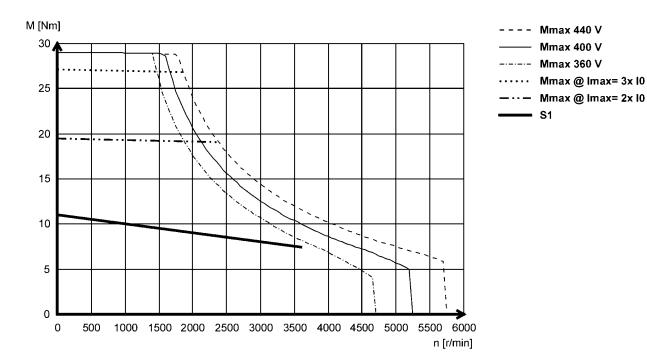
► The data applies to a mains connection voltage of 3 x 400 V.

MCS14D30 (forced ventilated)

M [Nm]

- - - - Mmax 440 V
—— Mmax 400 V
—·—· Mmax 360 V
········· Mmax @ Imax= 2x I0
—— S1

n [r/min]

MCS14D36- (non-ventilated)

M [Nm]

- - - - Mmax 440 V
—— Mmax 400 V
—·—· Mmax 360 V
········· Mmax @ Imax= 3x I0
—··—·· Mmax @ Imax= 2x I0
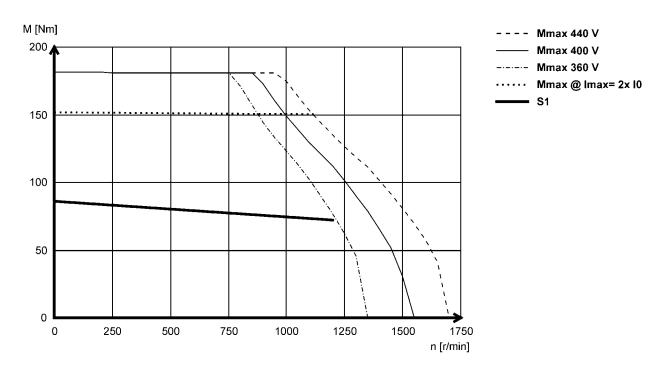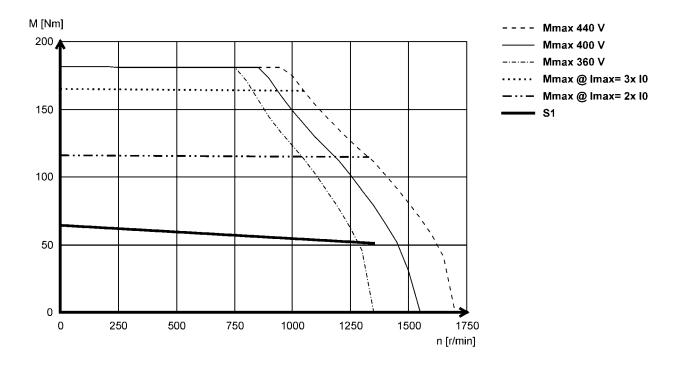—— S1

n [r/min]

6.6

MCS synchronous servo motors

Technical data

Torque characteristics
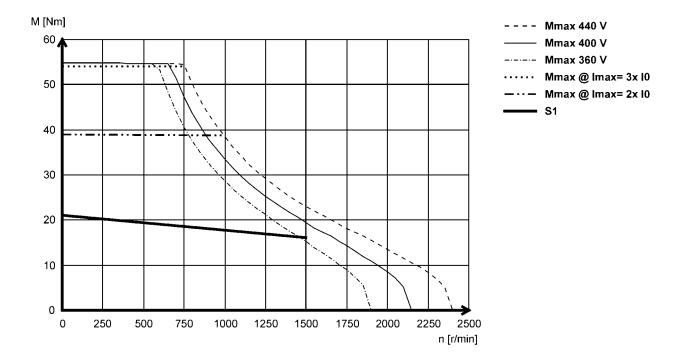
► The data applies to a mains connection voltage of 3 x 400 V.

MCS14H12- (forced ventilated)

Legend:
- Mmax 440 V (dashed)
- Mmax 400 V (solid)
- Mmax 360 V (dash-dot)
- Mmax @ Imax= 2x I0 (dotted)
- S1 (bold solid)

MCS14H15- (non-ventilated)
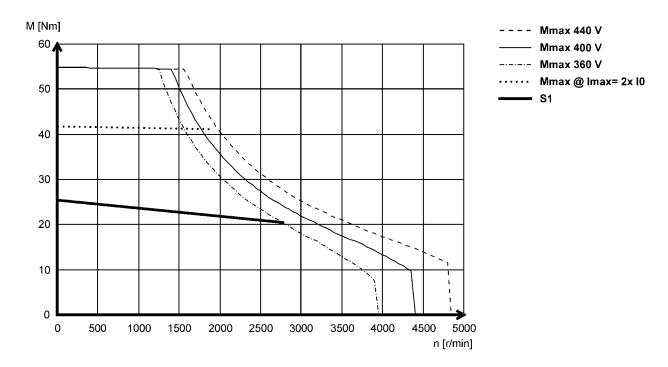
Legend:
- Mmax 440 V (dashed)
- Mmax 400 V (solid)
- Mmax 360 V (dash-dot)
- Mmax @ Imax= 3x I0 (dotted)
- Mmax @ Imax= 2x I0 (dash-dot-dot)
- S1 (bold solid)

## Torque characteristics
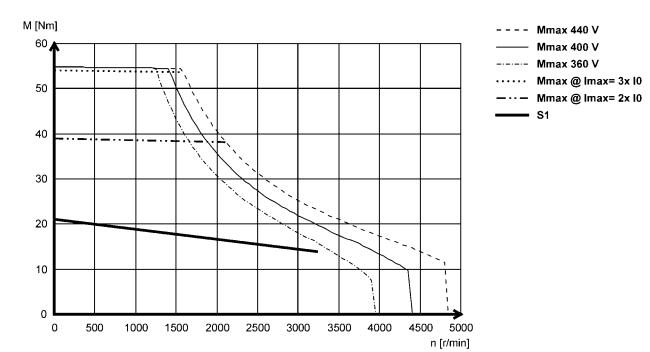
► The data applies to a mains connection voltage of 3 x 400 V.

MCS14H28- (forced ventilated)

Legend
- - - - Mmax 440 V
——— Mmax 400 V
—·—·— Mmax 360 V
·········· Mmax @ Imax= 2x I0
——— S1

MCS14H32- (non-ventilated)

Legend
- - - - Mmax 440 V
——— Mmax 400 V
—·—·— Mmax 360 V
·········· Mmax @ Imax= 3x I0
—··—··— Mmax @ Imax= 2x I0
——— S1

6.6

Torque characteristics

► The data applies to a mains connection voltage of 3 x 400 V.

MCS14L14- (forced ventilated)

M [Nm]

		Mmax 440 V
		Mmax 400 V
		Mmax 360 V
		Mmax @ Imax= 2x I0
		S1

n [r/min]

MCS14L15- (non-ventilated)

M [Nm]

		Mmax 440 V
		Mmax 400 V
		Mmax 360 V
		Mmax @ Imax= 3x I0
		Mmax @ Imax= 2x I0
		S1

n [r/min]

6.6

MCS synchronous servo motors

Technical data

Torque characteristics
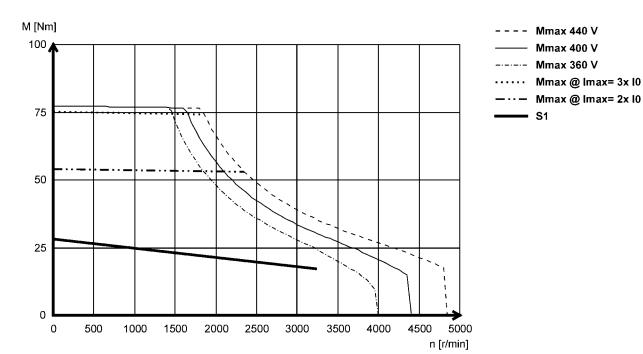
► The data applies to a mains connection voltage of 3 x 400 V.

MCS14L30- (forced ventilated)

Legend:
- – – – Mmax 440 V
- —— Mmax 400 V
- –·–·– Mmax 360 V
- ······ Mmax @ Imax= 2x I0
- —— S1

MCS14L32- (non-ventilated)
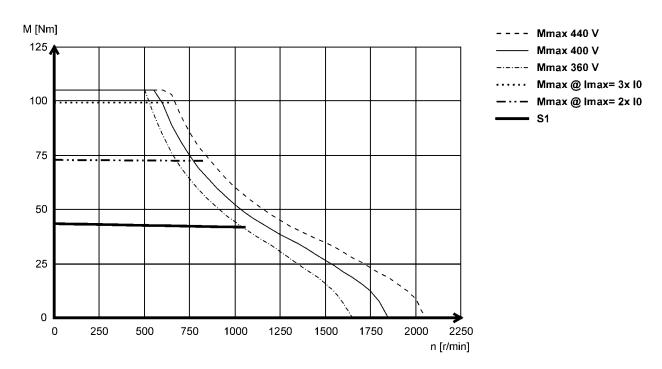
Legend:
- – – – Mmax 440 V
- —— Mmax 400 V
- –·–·– Mmax 360 V
- ······ Mmax @ Imax= 3x I0
- –··–··– Mmax @ Imax= 2x I0
- —— S1

6.6

Torque characteristics

► The data applies to a mains connection voltage of 3 x 400 V.

MCS14P11- (forced ventilated)

MCS14P14- (non-ventilated)

MCS synchronous servo motors

Technical data

Torque characteristics

► The data applies to a mains connection voltage of 3 x 400 V.

MCS14P26- (forced ventilated)

Legend:
- - - - Mmax 440 V
- —— Mmax 400 V
- —·—· Mmax 360 V
- ······ Mmax @ Imax= 3x I0
- —··—·· Mmax @ Imax= 2x I0
- —— S1

MCS14P32- (non-ventilated)

Legend:
- - - - Mmax 440 V
- —— Mmax 400 V
- —·—· Mmax 360 V
- ······ Mmax @ Imax= 3x I0
- —··—·· Mmax @ Imax= 2x I0
- —— S1

6.6

Torque characteristics

► The data applies to a mains connection voltage of 3 x 400 V.

MCS19F12- (forced ventilated)

M [Nm]

Legend:
- – – – Mmax 440 V
- —— Mmax 400 V
- —·—· Mmax 360 V
- ·········· Mmax @ Imax= 2x I0
- —— S1

n [r/min]

MCS19F14- (non-ventilated)

M [Nm]

Legend:
- – – – Mmax 440 V
- —— Mmax 400 V
- —·—· Mmax 360 V
- ·········· Mmax @ Imax= 3x I0
- —··—·· Mmax @ Imax= 2x I0
- —— S1

n [r/min]

MCS synchronous servo motors

Technical data

Torque characteristics

► The data applies to a mains connection voltage of 3 x 400 V.

MCS19F29- (forced ventilated)

Legend:
- – – – Mmax 440 V
- —— Mmax 400 V
- –·–·– Mmax 360 V
- ······ Mmax @ Imax= 2x I0
- —— S1

MCS19F30- (non-ventilated)

Legend:
- – – – Mmax 440 V
- —— Mmax 400 V
- –·–·– Mmax 360 V
- ······ Mmax @ Imax= 3x I0
- –··–··– Mmax @ Imax= 2x I0
- —— S1

6.6

Torque characteristics

► The data applies to a mains connection voltage of 3 x 400 V.

MCS19J12- (forced ventilated)

MCS19J14- (non-ventilated)
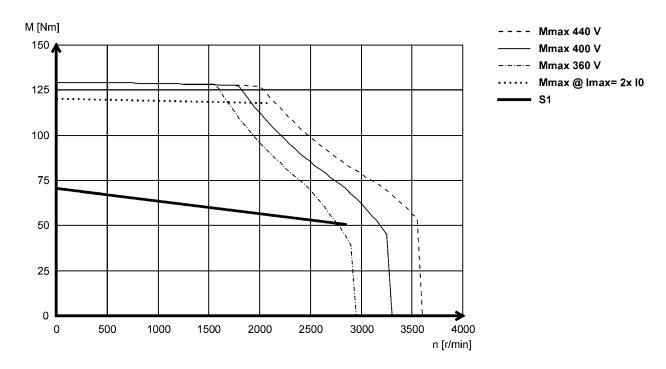
MCS synchronous servo motors

Technical data

Torque characteristics
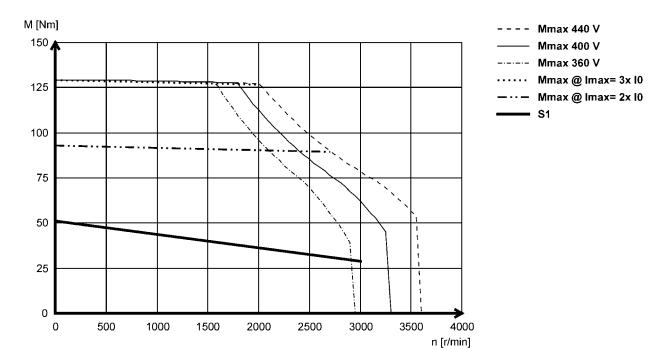
► The data applies to a mains connection voltage of 3 x 400 V.

MCS19J29- (forced ventilated)

Legend:
- - - - Mmax 440 V
- ——— Mmax 400 V
- -·-·- Mmax 360 V
- ······ Mmax @ Imax= 2x I0
- ——— S1

MCS19J30- (non-ventilated)

Legend:
- - - - Mmax 440 V
- ——— Mmax 400 V
- -·-·- Mmax 360 V
- ······ Mmax @ Imax= 3x I0
- -··-··- Mmax @ Imax= 2x I0
- ——— S1

6.6

MCS synchronous servo motors

Technical data

Torque characteristics

► The data applies to a mains connection voltage of 3 x 400 V.

MCS19P12 (forced ventilated)

MCS19P14- (non-ventilated)
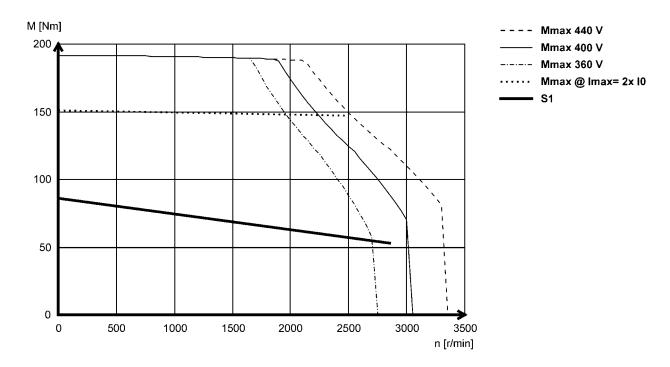
MCS synchronous servo motors

Technical data

Torque characteristics
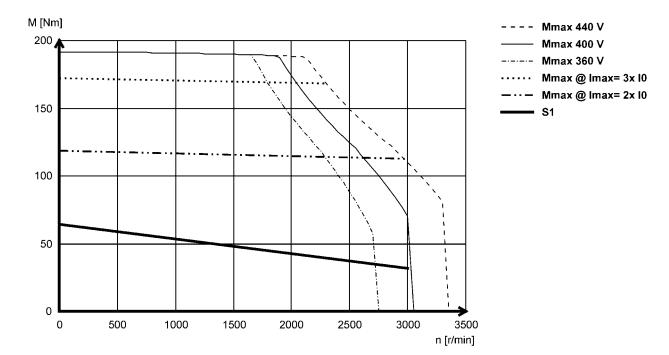
▶ The data applies to a mains connection voltage of 3 x 400 V.

MCS19P29- (forced ventilated)

- - - -	Mmax 440 V
——	Mmax 400 V
-·-·-	Mmax 360 V
······	Mmax @ Imax= 2x I0
——	S1

MCS19P30- (non-ventilated)
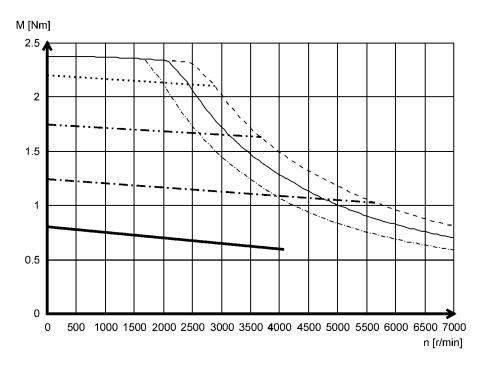
- - - -	Mmax 440 V
——	Mmax 400 V
-·-·-	Mmax 360 V
······	Mmax @ Imax= 3x I0
—··—··—	Mmax @ Imax= 2x I0
——	S1

6.6

MCS synchronous servo motors

Technical data

Torque characteristics
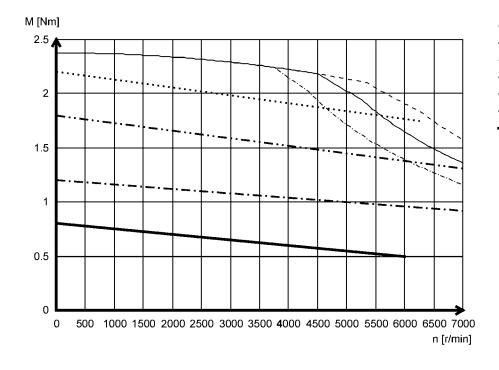
► The data applies to a mains connection voltage of 3 x 230 V.

MCS06C41L (non-ventilated)

Legend:
- ---- Mmax 253 V
- —— Mmax 230 V
- —·—· Mmax 207 V
- ······ Mmax @ Imax= 4x I0
- —··—·· Mmax @ Imax= 3x I0
- —·—·— Mmax @ Imax= 2x I0
- —— S1

MCS06C60L (non-ventilated)

Legend:
- ---- Mmax 253 V
- —— Mmax 230 V
- —·—· Mmax 207 V
- ······ Mmax @ Imax= 4x I0
- —··—·· Mmax @ Imax= 3x I0
- —·—·— Mmax @ Imax= 2x I0
- —— S1

Torque characteristics
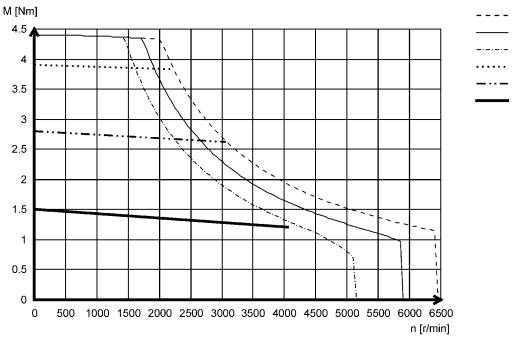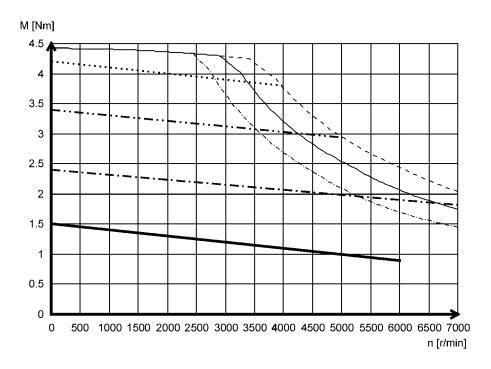
► The data applies to a mains connection voltage of 3 x 230 V.

MCS06F41L (non-ventilated)

Legend:
- – – – Mmax 253 V
- ——— Mmax 230 V
- –·–·– Mmax 207 V
- ········· Mmax @ Imax= 3x I0
- –··–··– Mmax @ Imax= 2x I0
- ——— S1

MCS06F60L (non-ventilated)

Legend:
- – – – Mmax 253 V
- ——— Mmax 230 V
- –·–·– Mmax 207 V
- ········· Mmax @ Imax= 4x I0
- –··–··– Mmax @ Imax= 3x I0
- –·–·– Mmax @ Imax= 2x I0
- ——— S1

6.6

Torque characteristics
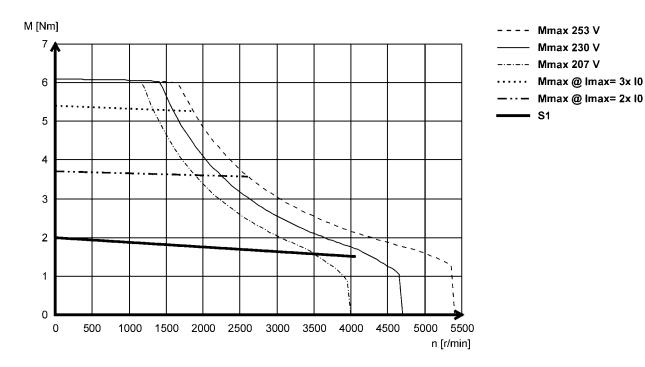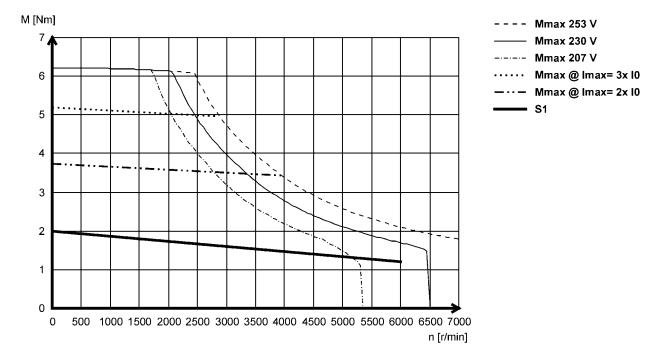
► The data applies to a mains connection voltage of 3 x 230 V.

MCS06I41L (non-ventilated)

- - - -	Mmax 253 V
―――	Mmax 230 V
–·–·–	Mmax 207 V
······	Mmax @ Imax= 3x I0
–··–··	Mmax @ Imax= 2x I0
▬▬▬	S1

MCS06I60L (non-ventilated)
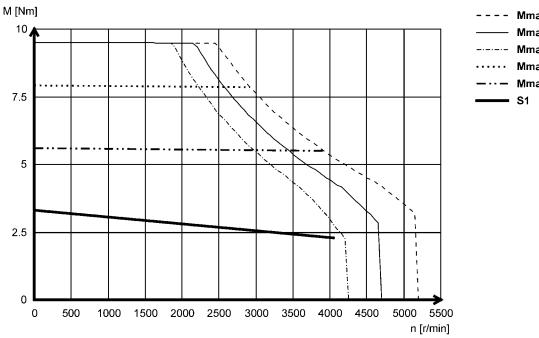
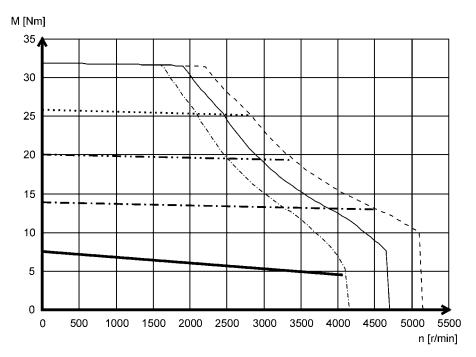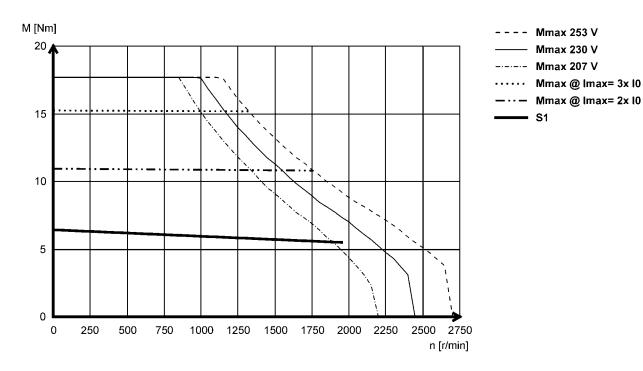|	
- - - -	Mmax 253 V
―――	Mmax 230 V
–·–·–	Mmax 207 V
······	Mmax @ Imax= 3x I0
–··–··	Mmax @ Imax= 2x I0
▬▬▬	S1

MCS synchronous servo motors

Technical data

Torque characteristics
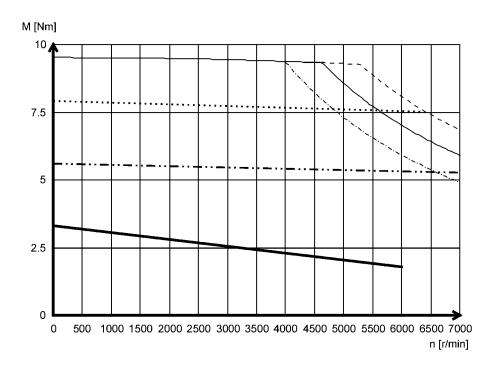
► The data applies to a mains connection voltage of 3 x 230 V.

MCS09D41L (non-ventilated)

- - - -	Mmax 253 V
——	Mmax 230 V
—·—·—	Mmax 207 V
········	Mmax @ Imax= 3x I0
—··—··—	Mmax @ Imax= 2x I0
——	S1

MCS09D60L (non-ventilated)

- - - -	Mmax 253 V
——	Mmax 230 V
—·—·—	Mmax 207 V
········	Mmax @ Imax= 3x I0
—··—··—	Mmax @ Imax= 2x I0
——	S1

6.6

Torque characteristics
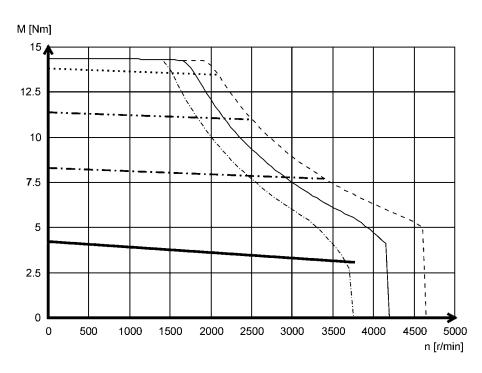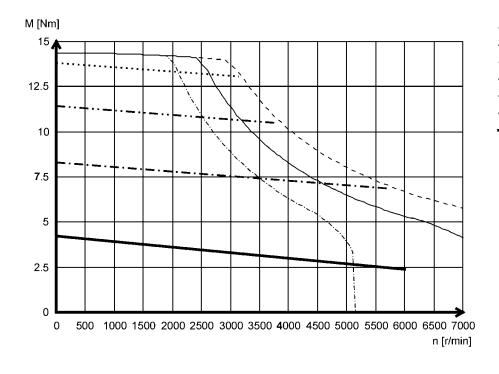
► The data applies to a mains connection voltage of 3 x 230 V.

MCS09F38L (non-ventilated)

– – –	Mmax 253 V
——	Mmax 230 V
–·–·–	Mmax 207 V
······	Mmax @ Imax= 4x I0
–··–··–	Mmax @ Imax= 3x I0
–·–·–	Mmax @ Imax= 2x I0
——	S1

MCS09F60L (non-ventilated)

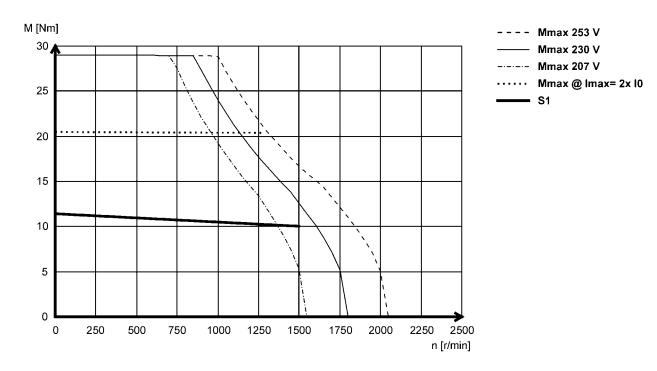|	
– – –	Mmax 253 V
——	Mmax 230 V
–·–·–	Mmax 207 V
······	Mmax @ Imax= 4x I0
–··–··–	Mmax @ Imax= 3x I0
–·–·–	Mmax @ Imax= 2x I0
——	S1

MCS synchronous servo motors

Technical data

Torque characteristics
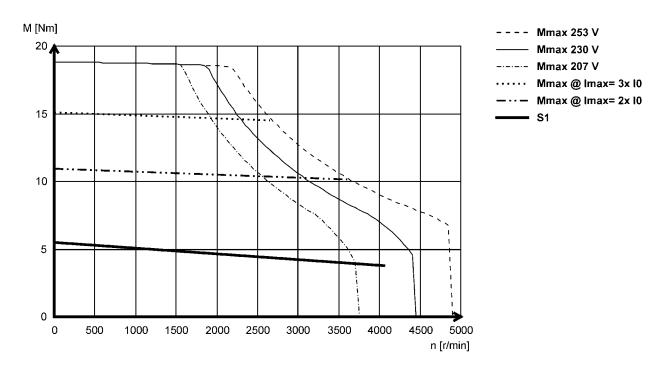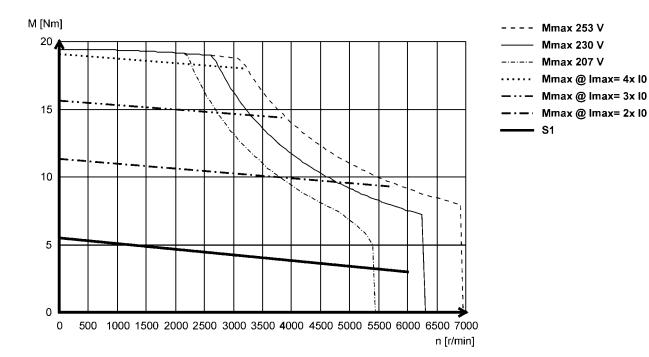
► The data applies to a mains connection voltage of 3 x 230 V.

MCS09H41L (non-ventilated)

Legend:
- - - - Mmax 253 V
- —— Mmax 230 V
- —·—· Mmax 207 V
- ······ Mmax @ Imax= 3x I0
- —··— Mmax @ Imax= 2x I0
- —— S1

MCS09H60L (non-ventilated)

Legend:
- - - - Mmax 253 V
- —— Mmax 230 V
- —·—· Mmax 207 V
- ······ Mmax @ Imax= 4x I0
- —··— Mmax @ Imax= 3x I0
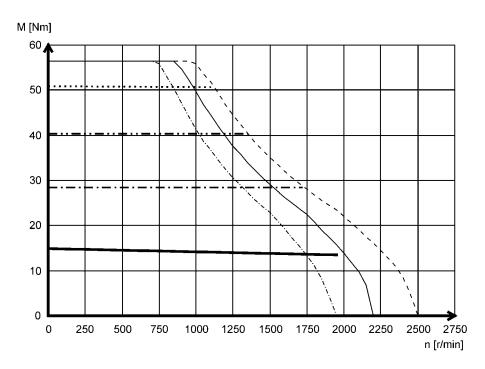- —·— Mmax @ Imax= 2x I0
- —— S1

6.6

MCS synchronous servo motors

Technical data

Torque characteristics

► The data applies to a mains connection voltage of 3 x 230 V.

MCS09L41L (non-ventilated)

Legend:
- – – – Mmax 253 V
- ——— Mmax 230 V
- – · – · Mmax 207 V
- · · · · · Mmax @ Imax= 4x I0
- – · · – Mmax @ Imax= 3x I0
- – · – · Mmax @ Imax= 2x I0
- ——— S1

MCS synchronous servo motors

Technical data

Torque characteristics
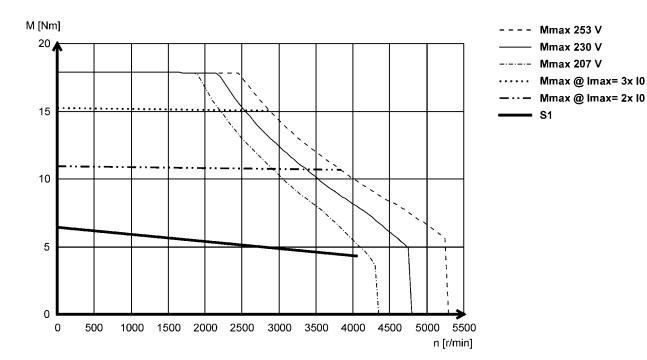
► The data applies to a mains connection voltage of 3 x 230 V.

MCS12D20L (non-ventilated)

- - - -	Mmax 253 V
———	Mmax 230 V
—·—·—	Mmax 207 V
·······	Mmax @ Imax= 3x I0
—··—··	Mmax @ Imax= 2x I0
———	S1

MCS12D41L (non-ventilated)

- - - -	Mmax 253 V
———	Mmax 230 V
—·—·—	Mmax 207 V
·······	Mmax @ Imax= 3x I0
—··—··	Mmax @ Imax= 2x I0
———	S1

6.6

MCS synchronous servo motors

Technical data

Torque characteristics
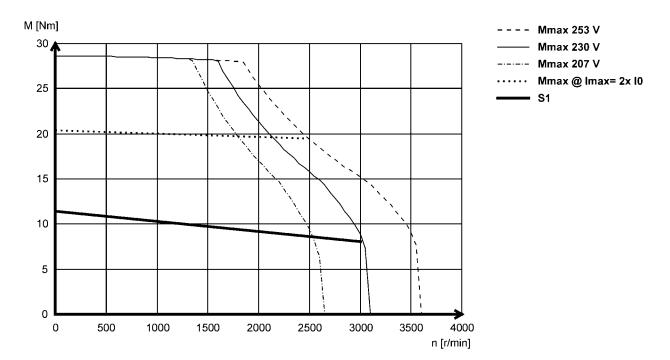
► The data applies to a mains connection voltage of 3 x 230 V.

MCS12H15L (non-ventilated)

Legend:
- - - - Mmax 253 V
——— Mmax 230 V
—·—·— Mmax 207 V
······ Mmax @ Imax= 2x I0
——— S1

MCS12H30L- (non-ventilated)

Legend:
- - - - Mmax 253 V
——— Mmax 230 V
—·—·— Mmax 207 V
······ Mmax @ Imax= 2x I0
——— S1

6.6

MCS synchronous servo motors

Technical data

Torque characteristics

► The data applies to a mains connection voltage of 3 x 230 V.

MCS12L20L (non-ventilated)

- - - -	Mmax 253 V
——	Mmax 230 V
—·—·—	Mmax 207 V
· · · · · ·	Mmax @ Imax= 4x I0
—··—··—	Mmax @ Imax= 3x I0
—·—·—	Mmax @ Imax= 2x I0
——	S1

6.6

Dimensions, self-ventilated
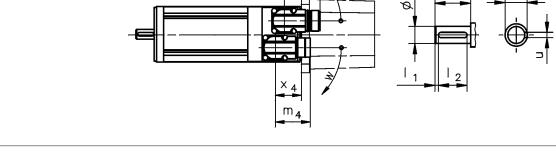
			MCS06C	MCS06F	MCS06I
R□0 / C40 B0	k	[mm]	155	185	215
R□0 / C40 P□	k	[mm]	174	204	233
SR□ / SV□ / E□□ B0	k	[mm]	237	266	297
SR□ / SV□ / E□□ P□	k	[mm]	255	285	315
SR□ / SV□ / E□□	k_5	[mm]		82.0	
	g_2	[mm]		86.0	
SKM B0	k	[mm]	190	220	250
SKM P□	k	[mm]	209	239	268
SKM	k_5	[mm]		35.0	
	g_2	[mm]		62.0	

► Speed / angle sensor: R□□ / C□□ / S□□ / E□□
► Brake: B0 / P□

MCS synchronous servo motors

Technical data

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Dimensions, self-ventilated

	g_1	g_3	x_3	x_4	m_3	m_4	n_3	n_4	y	v	w
	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[°]	[°]
MCS06	77	77	19	29	40	40	28	28	30	190	230

	d	d_2	l	l_1	l_2	u	t
	k6		-0.7 ... 0.3				
	[mm]	[mm]		[mm]	[mm]	[mm]	[mm]
MCS06	11	M4	23	2.0	18	4.0	12.5
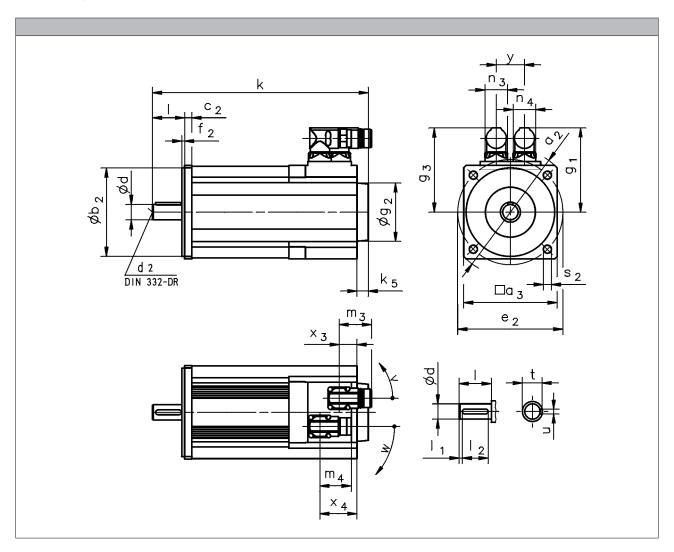
	a_3	b_2	c_2	e_2	f_2	s_2
		j6				
	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]
MCS06	62	60	8	75	2.5	5.5

MCS synchronous servo motors

Technical data

Dimensions, self-ventilated

			MCS09D	MCS09F	MCS09H	MCS09L	MCS12D	MCS12H	MCS12L
R□0 / C40 B0	k	[mm]	213	233	253	293	228	268	308
R□0 / C40 P□	k	[mm]	233	253	273	313	248	288	328
R□0 / C40	k_5	[mm]	13				14		
	g_2	[mm]	67				72		
S□□ / E□□ B0	k	[mm]	264	284	304	344	277	317	357
S□□ / E□□ P□	k	[mm]	284	304	324	364	297	337	377
S□□ / E□□	k_5	[mm]	64				63		
	g_2	[mm]	81				89		

			MCS14D	MCS14H	MCS14L	MCS14P	MCS19F	MCS19J	MCS19P
R□0 / C40 B0	k	[mm]	251	291	331	371	280	320	380
R□0 / C40 P□	k	[mm]	279	319	359	399	314	364	424
R□0 / C40	k_5	[mm]	24				15		
	g_2	[mm]	78						
S□□ / E□□ B0	k	[mm]	301	341	381	421	329	369	429
S□□ / E□□ P□	k	[mm]	329	369	409	449	363	413	473
S□□ / E□□	k_5	[mm]	74				64		
	g_2	[mm]	101						

► Speed / angle sensor: R□□ / C□□ / S□□ / E□□
► Brake: B0 / P□

MCS synchronous servo motors

Technical data

Dimensions, self-ventilated

	g₁ [mm]	g₃ [mm]	x₃ [mm]	x₄ [mm]	m₃ [mm]	m₄ [mm]	n₃ [mm]	n₄ [mm]	y [mm]	v [°]	w [°]
MCS09	90	90	20	44	40	40	28	28	35	195	260
MCS12	105	105	22	46							

	g₁ [mm]	g₃ [mm]	x₃ [mm]	x₄ [mm]	m₃ [mm]	m₄ [mm]	n₃ [mm]	n₄ [mm]	y [mm]	v [°]	w [°]
MCS14D15-	117	117	24	48	40	40	28	28	35	195	260
MCS14D36-											
MCS14H15-											
MCS14H32-											
MCS14L15-											
MCS14L32-	146	126	29	36		75		45		180	205
MCS14P14-	117	117	24	48		40		28		195	260
MCS14P32-	146	126	29	36		75		45		180	205
MCS19F14-	142	142	24 51[1]	48 75[1]		40		28		195	260
MCS19F30-	171	151	29 56[1]	36 63[1]		75		45		180	205
MCS19J14-	142	142	24 51[1]	48 75[1]		40		28		195	260
MCS19J30-	171	151	29 56[1]	36 63[1]		75		45		180	205
MCS19P14-	142	142	24 51[1]	48 75[1]		40		28		195	260
MCS19P30-	171	151	29 56[1]	36 63[1]		75		45		180	205

	d k6 [mm]	d₂ [mm]	l -0.7 ... 0.3	l₁ [mm]	l₂ [mm]	u [mm]	t [mm]
MCS09	14	M5	30	2.5	25	5.0	16.0
MCS12	19	M6	40	4.0	32	6.0	21.5
MCS14	24	M8	50	5.0	40	8.0	27.0
MCS19	28	M10	60		50		31.0

	a₂ [mm]	a₃ [mm]	b₂ j6 [mm]	c₂ [mm]	e₂ [mm]	f₂ [mm]	s₂ [mm]
MCS09	120	89	80	8	100	3.0	7.0
MCS12	160	116	110	9	130	3.5	10.0
MCS14	188	143	130	13	165		12.0
MCS19	250	192	180	11	215	4.0	14.0

[1] On version with brake (P□)
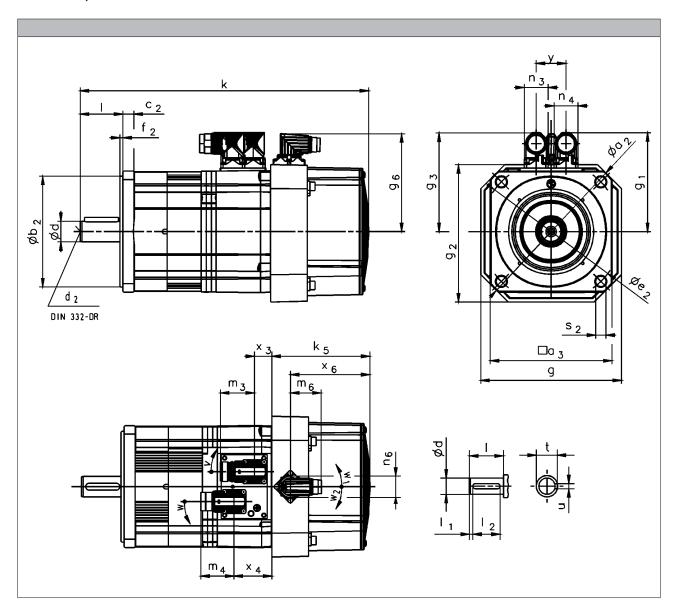
Dimensions, forced ventilated

			MCS12D	MCS12H	MCS12L	MCS14D	MCS14H	MCS14L	MCS14P	MCS19F	MCS19J	MCS19P
R□0 / C40 B0	k	[mm]	301	341	381	339	379	419	459	387	427	487
R□0 / C40 P□	k	[mm]	321	361	401	368	408	448	488	421	471	531
R□0 / C40	k_5	[mm]		92			115				126	
S□□ / E□□ B0	k	[mm]	344	384	424	392	432	472	512	425	465	525
S□□ / E□□ P□	k	[mm]	364	404	444	421	461	501	541	459	509	569
S□□ / E□□	k_5	[mm]		135			169				165	
	g	[mm]		140			167				212	
	g_2	[mm]		140			163				210	

► Speed / angle sensor: R□□ / C□□ / S□□ / E□□
► Brake: B0 / P□

MCS synchronous servo motors

Technical data

Dimensions, forced ventilated

	g_1 [mm]	g_3 [mm]	g_6 [mm]	x_3 [mm]	x_4 [mm]	x_6 [mm]	m_3 [mm]	m_4 [mm]	m_6 [mm]	n_3 [mm]	n_4 [mm]	n_6 [mm]	y [°]	v [°]	w [°]	w_1 [°]	w_2 [°]
MCS12D17	105	105	107	16	40	67		40			28						
MCS12D35																	
MCS12H14																	
MCS12H34																	
MCS12L17																	
MCS12L39																	
MCS14D14	117	117	115	20	44	93	40	40	37	28	28	28	35	160	160	120	130
MCS14D30																	
MCS14H12																	
MCS14H28	146	126		24	31			75			45						
MCS14L14	117	117		20	44			40			28						
MCS14L30	146	126		24	31			75			45						
MCS14P11	117	117		20	44			40			28						
MCS14P26	146	126		24	31			75			45						
MCS19F12	142	142	142	19 / 46 [1]	43 / 70 [1]	96		40			28						
MCS19F29	171	151		24 / 51 [1]	31 / 58 [1]			75			45						
MCS19J12																	
MCS19J29																	
MCS19P12																	
MCS19P29																	

	d k6 [mm]	d_2 [mm]	l -0.7 ... 0.3 [mm]	l_1 [mm]	l_2 [mm]	u [mm]	t [mm]
MCS12	19	M6	40	4.0	32	6.0	21.5
MCS14	24	M8	50	5.0	40	8.0	27.0
MCS19	28	M10	60		50		31.0

	a_2 [mm]	a_3 [mm]	b_2 j6 [mm]	c_2 [mm]	e_2 [mm]	f_2 [mm]	s_2 [mm]
MCS12	160	116	110	9	130	3.5	10.0
MCS14	188	143	130	13	165	3.5	12.0
MCS19	250	192	180	11	215	4.0	14.0

[1] On version with brake (P□)

MCS synchronous servo motors

Accessories

Permanent magnet holding brake

The synchronous servo motor can be fitted with integral permanent magnet holding brakes.

In the case of permanent magnet brakes, the rated torque applies solely as holding torque at standstill. This is due to the nature of their design. During braking from full motor speed, e.g. in the event of emergency stops, the braking torque is significantly reduced.

As such, they may not be used as safety elements (particularly with lifting axes) without additional measures being implemented.

The brakes are activated when the supply voltage is disconnected (closed-circuit principle). When using the brakes purely as holding brakes, virtually no wear occurs on the friction surfaces.

For traversing axes, adherence to the permissible load/brake motor (J_L / J_{MB}) moment of inertia ensures that the permissible maximum switching rate of the brake will not be exceeded and at least 2,000 emergency stop functions can be performed from a speed of 3,000 rpm.

For lifting axes, the load torque resulting from the weight acts additionally. In this case the specifications for J_L / J_{MB} do not apply.

Caution:
The brakes used are not safety brakes in the sense that a reduction in torque may arise as a result of disruptive factors that cannot be influenced, e.g. oil ingress.

The ohmic voltage drop along the cable must be taken into consideration in long motor supply cables and must be compensated for by a higher voltage at the line input.

The following applies for Lenze system cables:

$$U[V] = U_B[V] + 0.08 \frac{[V]}{[A] \cdot [m]} \cdot I_{Lg}[m] \cdot I_B[A]$$

If no suitable voltage (incorrect value, incorrect polarity) is applied to the brake, the brake will be applied and can be overheated and destroyed by the motor continuing to rotate.

The shortest switching times of the brakes are achieved by DC switching of the voltage. A spark suppressor is required to suppress interference and to increase the service life of the relay contacts here.

Permanent magnet holding brake

MCS synchronous servo motors

Accessories

Permanent magnet holding brake

Rated data with standard braking torque

	$U_{N, DC}$ [3, 5)	M_N	M_N	M_{av}	I_N [2)	J	t_1 [1)	t_2 [1)	Q_E [4)	m	J_{MB}	J_L/J_{MB}
		20 °C	120 °C	120 °C								
	[V]	[Nm]	[Nm]	[Nm]	[A]	[kgcm²]	[ms]	[ms]	[J]	[kg]	[kgcm²]	
MCS06C											0.26	22.1
MCS06F		2.20	2.00	0.60	0.34	0.12	15.0	30.0	30.0	0.30	0.34	16.6
MCS06I											0.42	13.3
MCS09D											2.17	36.4
MCS09F		8.00	6.00	4.50			20.0	40.0		0.80	2.57	30.5
MCS09H											2.97	26.3
MCS09L					0.65	1.07			400		3.87	19.9
MCS12D	24										5.07	15.0
MCS12H		12.0	10.0	7.00			13.0	43.0		0.90	8.40	8.70
MCS12L											11.7	5.90
MCS14D											11.3	10.5
MCS14H											17.4	6.50
MCS14L		22.0	18.0	8.00	0.88	3.20	15.0	150	640	1.90	26.6	3.90
MCS14P											37.9	2.40
MCS19F		37.0	32.0	15.0	0.93	12.4	96.0	113	2350	3.10	77.4	5.20

Rated data with increased braking torque

	$U_{N, DC}$ [3, 5)	M_N	M_N	M_{av}	I_N [2)	J	t_1 [1)	t_2 [1)	Q_E [4)	m	J_{MB}	J_L/J_{MB}
		20 °C	120 °C	120 °C								
	[V]	[Nm]	[Nm]	[Nm]	[A]	[kgcm²]	[ms]	[ms]	[J]	[kg]	[kgcm²]	
MCS09D											2.17	36.4
MCS09F		12.0	10.0	7.00	0.65	1.07	20.0	40.0	400	0.80	2.57	30.5
MCS09H											2.97	26.3
MCS09L											3.87	19.9
MCS12D											7.10	24.3
MCS12H		24.0	19.0	12.0	0.71	3.13	16.0	90.0	890	1.20	10.4	16.3
MCS12L	24										13.7	12.1
MCS14D											20.5	22.2
MCS14H											26.6	16.9
MCS14L		37.0	32.0	15.0	0.93	12.4	96.0	113	2350	3.10	35.8	12.3
MCS14P											47.1	9.10
MCS19J		100	80.0	43.0	1.29	30.0	30.0	90.0	2100	4.30	135	2.20
MCS19P											190	1.20

[1) Engagement and disengagement times are valid for rated voltage (± 0 %) and protective circuit for brakes with varistor for DC switching. The times may increase without a protective circuit.
[2) The currents are the maximum values when the brake is cold (value used for dimensioning the current supply). The values for a motor at operating temperature are considerably lower.
[3) With 24V DC brake: smoothed DC voltage, ripple ≤1 %.
[4) Maximum switching energy per emergency stop at n = 3000 r/min for at least 2000 emergency stops.
[5) Voltage tolerance: -10% to +5%

6.6

Resolver

Stator-fed resolver with two stator windings offset by 90° and one rotor winding with transformer winding.

Speed/angle sensor				RS0	RV0
Product key	1)				
				RS0	RV03
Resolution					
Angle			[']	0.80	
Accuracy					
			[']	-10 ... 10	
Absolute positioning					
				1 revolution	
Max. speed					
	n_{max}		[r/min]	8000	
Max. input voltage					
DC	$U_{in,max}$		[V]	10.0	
Max. input frequency					
	$f_{in,max}$		[kHz]	4.00	
Ratio					
Stator / rotor		± 5 %		0.30	
Rotor impedance					
	Z_{ro}		[Ω]	51 + j90	
Stator impedance					
	Z_{so}		[Ω]	102 + j150	
Impedance					
	Z_{rs}		[Ω]	44 + j76	
Min. insulation resistance					
At DC 500 V	R		[MΩ]	10.0	
Number of pole pairs					
				1	
Max. angle error					
			[']	-10 ... 10	
Inverter assignment					
				i700 E84AVTC E94A ECS EVS93	E84AVTC E94A ECS EVS93

1) ▶ 🗉 6 - Product key > speed/angle sensor

Speed-dependent safety functions

Suitable for safety function				No	Yes
Max. permissible angular acceleration					
MCS06	α		[rad/s²]		56000
MCS09 ... MCS19 2)	α		[rad/s²]		19000
Functional safety					
IEC 61508					SIL3
EN 13849-1					Up to Performance Level e

2) ▶ 🗉 10 - Single encoder concepts with resolvers

Incremental encoder and SinCos absolute value encoder

Encoder type			TTL incremental	SinCos absolute value		
Speed/angle sensor						
	[1]		C40	EQI	SRS	SVS
Product key						
			IK4096-5V-T	AM32-5V-E	AS1024-8V-H	AS1024-8V-K2
Encoder type						
			Single-turn	Multi-turn	Single-turn	
Pulses						
			4096	32	1024	
Output signals						
			TTL	1 Vss		
Interfaces						
				EnDat	Hiperface	
Absolute revolutions						
			0	4096	1	
Resolution						
Angle [2]		[']	1.30	0.40		
Accuracy						
		[']	-1 ... 1	-5 ... 5	-0.8 ... 0.8	
Min. input voltage						
DC	$U_{in,min}$	[V]	4.50	4.75	7.00	
Max. input voltage						
DC	$U_{in,max}$	[V]	5.50	5.25	12.0	
Max. speed						
	n_{max}	[r/min]	7324	12000	6000	
Max. current consumption						
	I_{max}	[A]	0.075	0.17	0.080	
Limit frequency						
	f_{max}	[kHz]	500	6.00	200	
Inverter assignment						
			E94P	E94A	E84AVTC E94A ECS EVS93	

[1] ▶ 目   6 - Product key > speed/angle sensor

[2] Inverter-dependent.

Speed-dependent safety functions

Suitable for safety function						
			No	No	No	Yes
Max. permissible angular acceleration						
MCS06	α	[rad/s²]				970000
MCS09 ... MCS19	α	[rad/s²]				240000
Functional safety						
IEC 61508						SIL2
EN 13849-1						Up to Performance Level d

MCS synchronous servo motors

Accessories

- -

Incremental encoder and SinCos absolute value encoder

Encoder type							
			SinCos absolute value				
Speed/angle sensor							
			SKM	SRM	SVM	ECN	EQN
Product key							
			AM128-8V-H	AM1024-8V-H	AM1024-8V-K2	AS2048-5V-E	AM2048-5V-E
Encoder type							
			Multi-turn			Single-turn	Multi-turn
Pulses							
			128	1024		2048	
Output signals							
			1 Vss				
Interfaces							
			Hiperface			EnDat	
Absolute revolutions							
			4096			1	4096
Resolution							
Angle		[']	0.40				
Accuracy							
		[']	-1.3 … 1.3	-0.8 … 0.8		-0.6 … 0.6	
Min. input voltage							
DC	$U_{in,min}$	[V]	7.00			4.75	
Max. input voltage							
DC	$U_{in,max}$	[V]	12.0			5.25	
Max. speed							
	n_{max}	[r/min]	9000	6000		12000	
Max. current consumption							
	I_{max}	[A]	0.060	0.080		0.15	0.25
Limit frequency							
	f_{max}	[kHz]	200				
Inverter assignment							
			i700 E84AVTC E94A ECS EVS93	E84AVTC E94A ECS EVS93		E94A	

[1] Inverter-dependent.

Speed-dependent safety functions

Suitable for safety function							
			No	No	Yes	No	No
Max. permissible angular acceleration							
MCS06	α	[rad/s^2]			970000		
MCS09 … MCS19	α	[rad/s^2]			240000		
Functional safety							
IEC 61508					SIL2		
EN 13849-1					Up to Performance Level d		

6.6

MCS synchronous servo motors

Accessories

Blower

Rated data for 50 Hz

		Enclosure	Number of phases	U_{min}	U_{max}	$U_{N, AC}$	P_N	I_N
				[V]	[V]	[V]	[kW]	[A]
MCS12	F10			210	240	230	0.019	0.12
	F50			104	122	115	0.018	0.22
MCS14	F10	IP54	1	210	240	230	0.040	0.25
	F50			104	122	115		0.53
MCS19	F10			210	240	230	0.060	0.26
	F50			104	122	115	0.047	0.45

Rated data for 60 Hz

		Enclosure	Number of phases	U_{min}	U_{max}	$U_{N, AC}$	P_N	I_N
				[V]	[V]	[V]	[kW]	[A]
MCS12	F10			210	240	230	0.019	0.12
	F50			104	122	115	0.018	0.22
MCS14	F10	IP54	1	210	240	230	0.040	0.25
	F50			104	122	115		0.53
MCS19	F10			210	240	230	0.060	0.26
	F50			104	122	115	0.047	0.45

MCS synchronous servo motors

Accessories

_____

Temperature monitoring
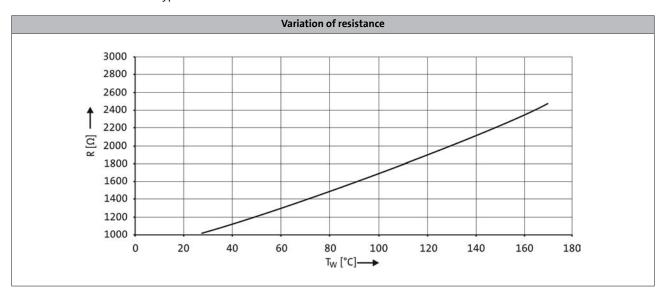
The thermal sensors used in the MCS motors continuously monitor the motor temperature. The temperature signal is transmitted over the system cable of the feedback system to the servo controller. Because of the different physical conditions, there are two temperature monitoring mechanisms on the MCS motors (there is no complete motor protection in either case).
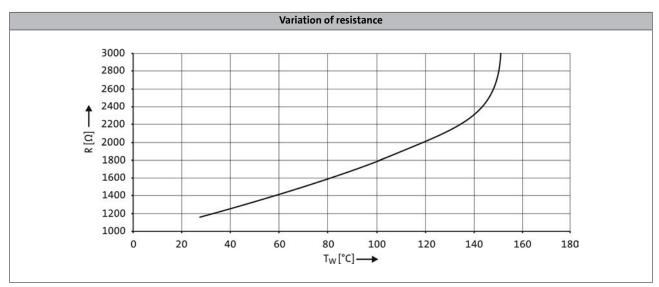
MCS06
In case of this motor, the winding temperature of one winding phase is monitored with a KTY 83-110 type thermal sensor.

Variation of resistance

MCS09 ... 19
These motors are monitored by three thermal sensors (1x KTY 83-110 + 2x PTC 150 °C) connected in series. This means that the temperature of the motor is determined with great accuracy in the permitted operating range and at the same time the overtemperature response configured in the controller is executed in one of the winding phases.

Variation of resistance

▶ If the thermal sensor is supplied with a measurement current of 1 mA, the above relationship between the temperature and the resistance applies.

- -

Terminal box

If a servo motor is to be connected to an existing cable or plug connectors are not to be used for other reasons, the connection can also be made via a terminal box.

The terminals are designed as tension spring terminals to ensure here the long-term vibration resistance of the cable contacts with adequate contact pressure required.

The terminal boxes have generously dimensioned space for the customer's own wiring and large surface shield connection areas to ensure a secure EMC-compliant connection. The cable outlet may be to the left or to the right, depending on requirements.
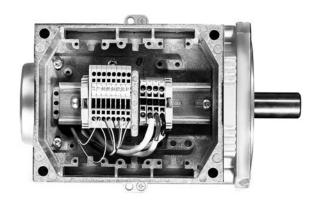
It is not possible to attach a terminal box to the MCS06 or to models with the blower.

Connections

1: Power connection (terminals loadable up to 65 A) + brake connection.

2: Angle/speed sensor connection + thermal sensor connection.

3: PE connection.

4: Large area shield contact.

5: Openings for 2x M32, 2x M25, 2x M20 fittings. The openings are plugged and can be opened up as required by the customer.

MCS synchronous servo motors
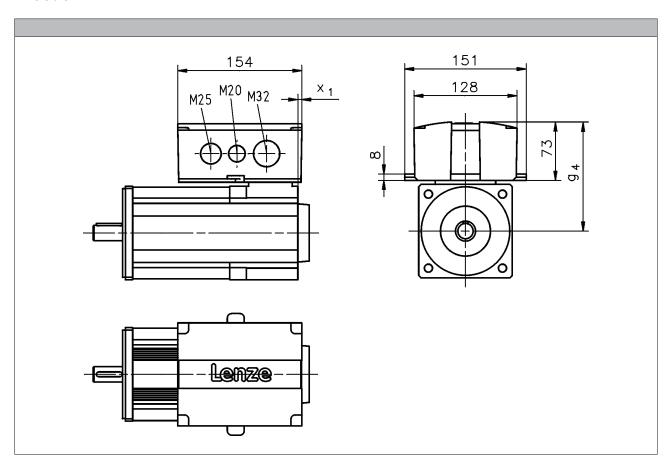
Accessories

Terminal box

Dimensions

	g_4 [mm]	x_1 [mm]
MCS09	121	8
MCS12	136	5
MCS14	147	3
MCS19	172	

MCS synchronous servo motors

Accessories

ICN connector

An ICN connector is used as standard for the electrical connection to the servo motors.

A connector is used for the connection of motor and brake. The connections to the feedback system/temperature monitoring and the blower each employ a separate connector.

The connectors can be rotated through 270° and are fitted with a bayonet catch for SpeedTec connectors. As the connector fixing is also compatible with conventional union nuts. Existing mating connectors can therefore still be used without difficulty.

Connection for power and brake

► MCS06 to 12

Pin assignment			
Contact	**Designation**	**Meaning**	
1	BD1	Holding brake +	
2	BD2	Holding brake -	
PE	PE	PE conductor	
4	U	Phase U power	
5	V	Phase V power	
6	W	Phase W power	

► MCS14 to 19

Pin assignment			
Contact	**Designation**	**Meaning**	
1		Not assigned	
2			
+	BD1	Holding brake +	
-	BD2	Holding brake -	
PE	PE	PE conductor	
U	U	Phase U power	
V	V	Phase V power	
W	W	Phase W power	

MCS synchronous servo motors

Accessories

ICN connector

Feedback connection

► Resolver

Pin assignment			
Contact	Designation	Meaning	
1	+Ref	Transformer windings	
2	-Ref		
3	+VCC ETS	Supply: Electronic nameplate	
4	+COS	Cosine stator windings	
5	-COS		
6	+SIN	Sine stator windings	
7	-SIN		
8		Not assigned	
9			
10			
11	+KTY	KTY temperature sensor	
12	-KTY		

Code 0°

► Hiperface incremental encoder and SinCos absolute value encoder

Pin assignment			
Contact	Designation	Meaning	
1	B	Track B/+SIN	
2	A⁻	Track A inverse/-COS	
3	A	Track A/+COS	
4	+U$_B$	Supply +	
5	GND	Mass	
6	Z⁻	Zero track inverse/-RS485	
7	Z	Zero track/+RS485	
8		Not assigned	
9	B⁻	Track B inverse/-SIN	
10		Not assigned	
11	+KTY	KTY temperature sensor	
12	-KTY		

Code 20°

6.6

ICN connector

Feedback connection

► SinCos absolute value encoder with EnDat interface

Pin assignment			
Contact	Designation	Meaning	
1	U_P sensor	Supply: UP sensor	
2		Not assigned	
3			
4	0 V sensor	Supply: 0 V sensor	
5	+KTY	KTY temperature sensor	
6	-KTY		
7	$+U_B$	Supply +	
8	Cycle	EnDat interface cycle	
9	$Cycle^-$	EnDat interface inverse cycle	
10	GND	Mass	
11	Shield	Encoder housing screen	
12	B	Track B	
13	B^-	Track B inverse/-SIN	
14	Data	EnDat interface data	
15	A	Track A	
16	A^-	Track A inverse	
17	$Data^-$	EnDat interface inverse data	

Code 0°

Blower connection

Pin assignment			
Contact	Designation	Meaning	
PE	PE	PE conductor	
1	U1	Fan	
2	U2		
3		Not assigned	
4			
5			
6			

MCA asynchronous servo motors

2 to 1,100 Nm

MCA asynchronous servo motors

Contents

6.6

List of abbreviations

$\eta_{100\%}$	[%]	Efficiency
$\cos\varphi$		Power factor
du/dt	[kV/µs]	Insulation resistance
$F_{ax,-}$	[N]	Min. axial force
$F_{ax,+}$	[N]	Max. axial force
$f_{in,max}$	[Hz]	Max. input frequency
f_{max}	[kHz]	Limit frequency
f_{max}	[kHz]	Max. switching frequency
f_N	[Hz]	Rated frequency
F_{rad}	[N]	Max. radial force
H_{max}	[m]	Site altitude
I_0	[A]	Standstill current
I_{max}	[A]	Max. short-time DC-bus current
I_{max}	[A]	Max. current
I_{max}	[A]	Max. current consumption
I_{max}	[A]	Max. current
I_{max}	[A]	Max. DC-bus current
I_N	[A]	Rated current
J	[kgcm²]	Moment of inertia
J_{MB}	[kgcm²]	Moment of inertia
$KE_{LL\ 150\ °C}$	[V /(1000 r/min)]	Voltage constant
$Kt_{0\ 150\ °C}$	[Nm/A]	Torque constant
L	[mH]	Mutual inductance
$L_{1\sigma}$	[mH]	Stator leakage inductance
$L_{2\sigma}$	[mH]	Rotor leakage inductance
L_N	[mH]	Rated inductance
m	[kg]	Mass
M_0	[Nm]	Stall torque
$M_{0,\ max}$	[Nm]	Max. standstill torque
M_{av}	[Nm]	Average dynamic torque
M_{max}	[Nm]	Max. torque
M_N	[Nm]	Rated torque
n_{eto}	[r/min]	Transition speed
n_k	[r/min]	Speed
n_{max}	[r/min]	Max. speed

n_N	[r/min]	Rated speed
P_N	[kW]	Rated power
Q_E	[J]	Maximum switching energy
R	[Ω]	Insulation resistance
R	[Ω]	Min. insulation resistance
R_1	[Ω]	Stator impedance
R_2	[Ω]	Charging resistor
R_2	[Ω]	Rotor impedance
$R_{UV\ 150\ °C}$	[Ω]	Stator impedance
$R_{UV\ 20\ °C}$	[Ω]	Stator impedance
$S_{hü}$	[1/h]	Transition operating frequency
T	[°C]	Operating temperature
T	[°C]	Rated temperature
T	[°C]	Max. ambient temperature of bearing
T	[°C]	Max. surface temperature
T	[°C]	Max. ambient temperature for transport
T	[°C]	Min. ambient storage temperature
T	[°C]	Min. ambient temperature for transport
T	[°C]	Ambient temperature
t_1	[ms]	Engagement time
t_2	[ms]	Disengagement time
$T_{opr,max}$	[°C]	Max. ambient operating temperature
$T_{opr,min}$	[°C]	Min. ambient operating temperature
$U_{in,max}$	[V]	Max. input voltage
$U_{in,min}$	[V]	Min. input voltage
U_{max}	[V]	Max. mains voltage
U_{max}	[V]	Min. input voltage
U_{min}	[V]	Min. mains voltage
$U_{N,\ AC}$	[V]	Rated voltage
$U_{N,\ DC}$	[V]	Rated voltage
Z_{ro}	[Ω]	Rotor impedance
Z_{rs}	[Ω]	Impedance
Z_{so}	[Ω]	Stator impedance

6.6

List of abbreviations
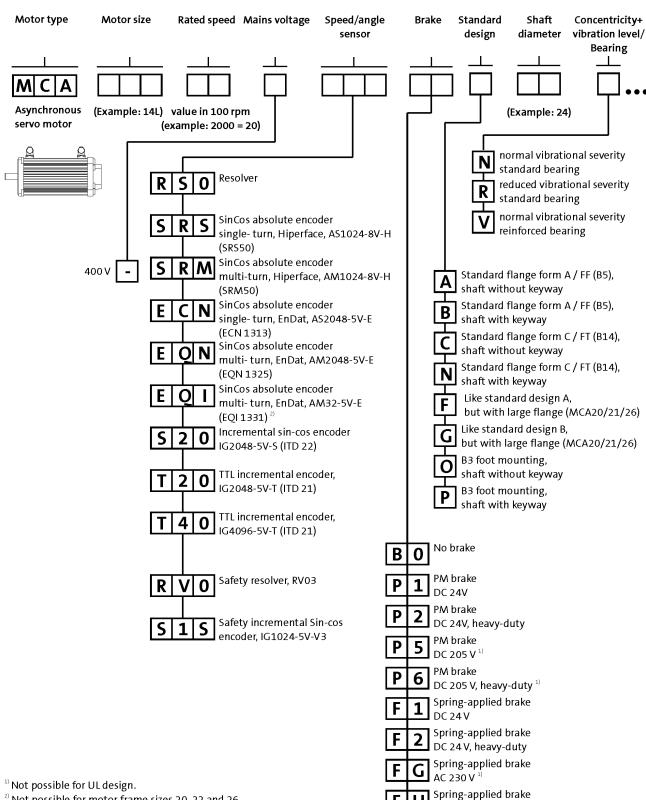
CE	Communauté Européenne
CSA	Canadian Standards Association
DIN	Deutsches Institut für Normung e.V.
EMC	Electromagnetic compatibility
EN	European standard
EAC	Customs union Russia / Belarus / Kazakhstan certificate
IEC	International Electrotechnical Commission
IM	International Mounting Code
IP	International Protection Code
NEMA	National Electrical Manufacturers Association
UkrSEPRO	Certificate for Ukraine
UL	Underwriters Laboratory Listed Product
UR	Underwriters Laboratory Recognized Product
VDE	Verband deutscher Elektrotechniker (Association of German Electrical Engineers)

6.6

MCA asynchronous servo motors

General information

Product key

| Motor type | Motor size | Rated speed | Mains voltage | Speed/angle sensor | Brake | Standard design | Shaft diameter | Concentricity+ vibration level/ Bearing |

M C A — Asynchronous servo motor

(Example: 14L)

value in 100 rpm (example: 2000 = 20)

(Example: 24)

400 V —

R S 0 Resolver

S R S SinCos absolute encoder single- turn, Hiperface, AS1024-8V-H (SRS50)

S R M SinCos absolute encoder multi-turn, Hiperface, AM1024-8V-H (SRM50)

E C N SinCos absolute encoder single- turn, EnDat, AS2048-5V-E (ECN 1313)

E Q N SinCos absolute encoder multi- turn, EnDat, AM2048-5V-E (EQN 1325)

E Q I SinCos absolute encoder multi- turn, EnDat, AM32-5V-E (EQI 1331) [2]

S 2 0 Incremental sin-cos encoder IG2048-5V-S (ITD 22)

T 2 0 TTL incremental encoder, IG2048-5V-T (ITD 21)

T 4 0 TTL incremental encoder, IG4096-5V-T (ITD 21)

R V 0 Safety resolver, RV03

S 1 S Safety incremental Sin-cos encoder, IG1024-5V-V3

N normal vibrational severity standard bearing

R reduced vibrational severity standard bearing

V normal vibrational severity reinforced bearing

A Standard flange form A / FF (B5), shaft without keyway

B Standard flange form A / FF (B5), shaft with keyway

C Standard flange form C / FT (B14), shaft without keyway

N Standard flange form C / FT (B14), shaft with keyway

F Like standard design A, but with large flange (MCA20/21/26)

G Like standard design B, but with large flange (MCA20/21/26)

O B3 foot mounting, shaft without keyway

P B3 foot mounting, shaft with keyway

B 0 No brake

P 1 PM brake DC 24V

P 2 PM brake DC 24V, heavy-duty

P 5 PM brake DC 205 V [1]

P 6 PM brake DC 205 V, heavy-duty [1]

F 1 Spring-applied brake DC 24 V

F 2 Spring-applied brake DC 24 V, heavy-duty

F G Spring-applied brake AC 230 V [1]

F H Spring-applied brake AC 230 V, heavy-duty [1]

[1] Not possible for UL design.
[2] Not possible for motor frame sizes 20, 22 and 26.

MCA asynchronous servo motors

General information

Product key

Electrical connection	Degree of protection	Cooling	Load flywheel	Temperature protection	Nameplate	Colour	Specification

• • •

S	T	Separate round plugs for power+brake, encoder +thermal sensor, blower

K	K	Separate terminal boxes for power+brake, encoder +thermal sensor+blower

K	S	Terminal box for power+brake separate round plugs for encoder+thermal sensor, blower

ST

KK

KS

Degree of protection:
- IP23s — | 2 |
- IP54 — | 5 |
- IP65 — | 6 |

Cooling:
- Natural ventilation, no fan — | S | 0 | 0 |
- Blower 230 V without filter — | F | 1 | 0 |
- Blower 230 V with filter — | F | 1 | F |

Load flywheel:
- | N | Without

Temperature protection:
- | R | KTY temperature sensor

Nameplate:
- | 0 | International
- | 1 | International + electronic
- | 2 | International + second supplied loose
- | 3 | International + electronic + second supplied loose

Colour:
- | S | Black
- | X | Other colours

Specification:
- | U | UL / CSA cURus approval
- | 0 | Without

6.6

MCA asynchronous servo motors

General information

- -

Product information

An application-oriented structure, low moments of inertia, compact dimensions and a high degree of intrinsic operational reliability characterise these robust and dynamic motors.

The compact design and the low moment of inertia allow these motors to be used in dynamic applications. If your application calls for a broad speed setting range and a robust construction, then the choice is easy: MCA asynchronous servo motors from Lenze.
Whether as a self-ventilated version or with a blower – with a power range from 0.8 to 53.8 kW, the MCA asynchronous servo motors offer rated torque values of up to 280 Nm and peak torque values of up to 1100 Nm. In comparison to standard three-phase AC motors, these servo motors have the edge in terms of lower moments of inertia, lower weight and higher maximum speeds.

Advantages

- High dynamic performance thanks to low moments of inertia
- Compact size with high power density
- Robust regenerative resolver system – alternatively SinCos and incremental encoder for the highest precision
- Easy to install and service friendly thanks to use of SpeedTec connectors
- Terminal box optional up to MCA21 MCA22 and 26 with three-part terminal box
- Protection: IP23, IP54, IP65 optional for naturally ventilated servo motors
- cURus-approved, GOST-certified, CE, RoHS-compliant
- High maximum speeds
- Wide speed setting range
- Field weakening operation usable
- Electronic nameplate

MCA21 asynchronous servo motor

Functions and features

Design	MCA10	MCA13	MCA14	MCA17	MCA19
	B14-FT85 B5-FF100	B14-FT130 B5-FF130	B14-FT130 B5-FF165		B14-FT130 B5-FF215
Shaft end (with and without keyway)					
	14 x 30	19 x 40	24 x 50		28 x 60
A end shield					
	Oil-tight Not oil-tight				
Brake					
Spring-applied brake					
Permanent magnetic brake	DC 24 V AC 230 V [1] DC 205 V [1]				
Speed and angle encoder					
	Resolver SinCos single-turn/multi-turn Incremental encoder				
Cooling					
Without blower	Naturally ventilated				
Axial blower, 1 phase	230 V; 50 Hz				
Thermal sensor					
Thermal detector	KTY				
Motor connection: plug connector					
	Power + brake Encoder + thermal sensor Blower				
Motor connection: terminal box					
	Power + brake Encoder + thermal sensor	Power + brake Encoder + thermal sensor + blower			
Motor connection: Terminal box + plug connector					
Terminal box	Power + brake Encoder + thermal sensor				
Plug connector		Blower			
Shaft bearings					
Bearing type	Deep-groove ball bearing with high-temperature resistant grease, sealing disc or cover plate				
Position of the locating bearing	Drive end Standard motors (B3, B5, B14): side B Motors for gearbox direct mounting: side A				
Installation of the locating bearing					
Colour					
	RAL9005M				

[1] Not possible for UR version.

MCA asynchronous servo motors

General information

_____

Functions and features

	MCA20	MCA21	MCA22	MCA26
Design				
	B3 B35-FF215 B35-FF265	B14-FT130 B5-FF215 B5-FF265	B3 B35-FF265	B3 B35-FF265 B35-FF350
Shaft end (with and without keyway)				
	38 x 80			55 x 110
A end shield				
	Oil-tight Not oil-tight			
Brake				
Spring-applied brake	DC 24 V AC 230 V [1]		DC 24 V AC 230 V [1]	
Permanent magnetic brake		DC 24 V AC 230 V [1] DC 205 V [1]		
Speed and angle encoder				
	Resolver SinCos single-turn/multi-turn Incremental encoder			
Cooling				
Without blower	Naturally ventilated			
Axial blower, 1 phase	230 V; 50 Hz 230 V; 60 Hz	230 V; 50 Hz	230 V; 50 Hz 230 V; 60 Hz	
Thermal sensor				
Thermal detector	KTY			
Motor connection: plug connector				
	Power + brake Encoder + thermal sensor Blower			
Motor connection: terminal box				
	Power + brake Encoder + thermal sensor + blower			
Motor connection: Terminal box + plug connector				
Terminal box	Power + brake	Power + brake Encoder + thermal sensor	Power + brake	
Plug connector	Encoder + thermal sensor Blower	Blower	Encoder + thermal sensor Blower	
Shaft bearings				
Bearing type	Deep-groove ball bearing with high-temperature resistant grease, sealing disc or cover plate			
Position of the locating bearing	Non-drive end	Drive end Standard motors (B3, B5, B14): side B Motors for gearbox direct mounting: side A	Non-drive end	
Installation of the locating bearing	insulation		insulation	
Colour				
	RAL9005M			

[1] Not possible for UR version.

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Dimensioning

Speed-dependent safety functions

Single encoder concepts with resolvers

Servo motors can perform speed-dependent safety functions for safe speed and / or safe relative position monitoring in a drive system with the Servo Drives 9400. The SM301 safety module, which can be integrated in the Servo Drives 9400, is used to implement these functions. When planning systems/installations of this kind, the following must always be observed:

When using just one single feedback system in the environment of these safety applications, the applicable safety engineering standard IEC 61800-5-2 [Adjustable speed electrical power drive systems - Part: 5-2: Safety requirements - Functional] stipulates special requirements for the connection between feedback system and motor shaft. This is due to the fact that two-channel safety systems at this point in the mechanical system are actually designed as single-channel systems. If this mechanical connection is designed with considerable overdimensioning, the standard permits exclusion of the fault "encoder-shaft breakage" or "encoder-shaft slip".
As such, acceleration limit values must not be exceeded for the individual drive solutions. You can find the limit values in the corresponding feedback data of the individual motor ranges.

Speed-dependent safety functions in connection with the SM301 safety module

For the following speed-dependent safety functions, the motor-feedback system combinations listed in the following table are available:
- Safe stop 1 (SS1)
- Safe operational stop (SOS)
- Safely Limited Speed (SLS)
- Safe Maximum Speed (SMS)

- Safe direction (SDI)
- Operation mode selector (OMS) with confirmation (ES)
- Safe speed monitor (SSM)
- Safely limited increment (SLI).

Encoder type	Encoder type	Product key	Feedback	Safe speed monitoring
			Design	
SinCos incremental	Single-turn	IG1024-5V-V3		PL e/SIL 3
Resolver		RV03		
			2-encoder concept	up to PL e / SIL 3

6.6

Dimensioning

Cooling effect of mounting flange

Mounting on a thermally conducting / insulating plate or machine chassis has an influence on heating up the motor, particularly when using naturally ventilated motors.

The motor rating data specified in the catalogue applies when mounting on a steel plate with free convection with the following dimensions:
- MCA10 / 13: 270 x 270 mm
- MCA14 / 17: 330 x 330 mm
- MCA19 to 26: 450 x 450 mm

Vibrational severity

		MCA10	MCA13	MCA14	MCA17	MCA19	MCA20	MCA21	MCA22	MCA26
Vibrational severity										
IEC/EN 60034-14		A		B			A	B	A	
Maximum r.m.s. value of the vibration velocity [1]	[mm/s]	1.60		0.70			1.60	0.70	1.60	
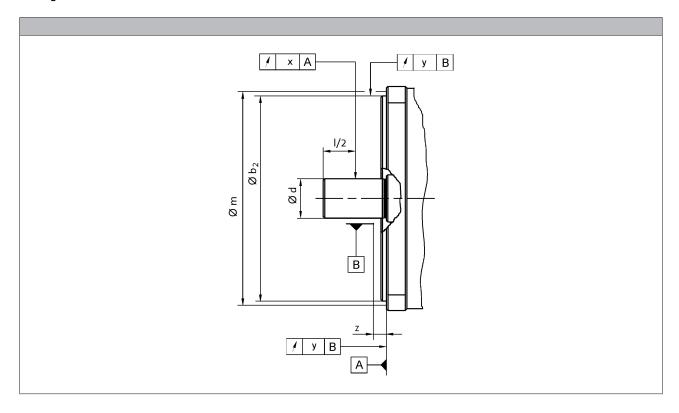
[1] Free suspension

► at n = 600 to 3,600 rpm

Dimensioning

Concentricity and axial run-out of the mounting flanges and smooth running of the shaft ends

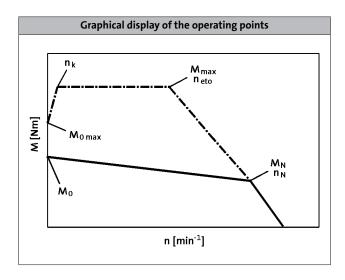|				MCA10		MCA13		MCA14		MCA17		MCA19	
Flange size													
				FF100	FT85	FF130	FT130	FF165	FT130	FF165	FT130	FF215	FT130
Dimensions													
	b_2	j6	[mm]	80	70	110		130	110	130	110	180	110
	b_2	h6	[mm]										
	d	k6	[mm]	14		19		24				28	
	d	m6	[mm]										
Distance													
Measuring diameter	m		[mm]	113	98.0	149		188	149	188	149	239	149
Dial gauge holder for flange check	z	+/- 1	[mm]	10.0									
Concentricity													
IEC 60072				Normal class				Precision class					
Value	y		[mm]	0.080		0.10		0.050					
Linear movement													
IEC 60072				Normal class				Precision class					
Value	y		[mm]	0.080		0.10		0.050					
Smooth running													
IEC 60072				Normal class				Precision class					
Value	x		[mm]	0.035		0.040		0.021					

► Limit values for checking the smooth running of the shaft ends as well as the concentricity and axial run-out of the mounting flange to IEC 60072

Dimensioning

Concentricity and axial run-out of the mounting flanges and smooth running of the shaft ends

				MCA20		MCA21			MCA22		MCA26
Flange size											
				FF215	FF265	FF215	FF265	FT130	FF265		FF350
Dimensions											
	b_2	j6	[mm]	180	230	180	230	110	230		
	b_2	h6	[mm]								300
	d	k6	[mm]				38				
	d	m6	[mm]							55	
Distance											
Measuring diameter	m		[mm]	239	289	239	289	149	289		384
Dial gauge holder for flange check	z	+/- 1	[mm]				10.0				
Concentricity											
IEC 60072				Normal class		Precision class			Normal class		
Value	y		[mm]	0.10		0.050			0.10		
Linear movement											
IEC 60072				Normal class		Precision class			Normal class		
Value	y		[mm]	0.10		0.050			0.10		
Smooth running											
IEC 60072				Normal class		Precision class			Normal class		
Value	x		[mm]	0.050		0.060			0.050	0.060	

▶ Limit values for checking the smooth running of the shaft ends as well as the concentricity and axial run-out of the mounting flange to IEC 60072

6.6

MCA asynchronous servo motors

General information

Dimensioning

Notes on the selection tables

Graphical display of the operating points

Please note:
- With an active load (e.g. vertical drive axes, hoists, test benches, unwinders), $M_{0\,max}$ must be taken into account
- With a passive load (e.g. horizontal drive axes), M_{max} can generally be used
- At speeds $< n_k$, the inverter-specific torque $M_{0\,max}$ that can be achieved is lower than M_{max}
- On the servo inverters, the switching frequency-dependent overload capacity has been taken into account in the factory settings. For further information, please refer to the Servo-Inverters catalogue.
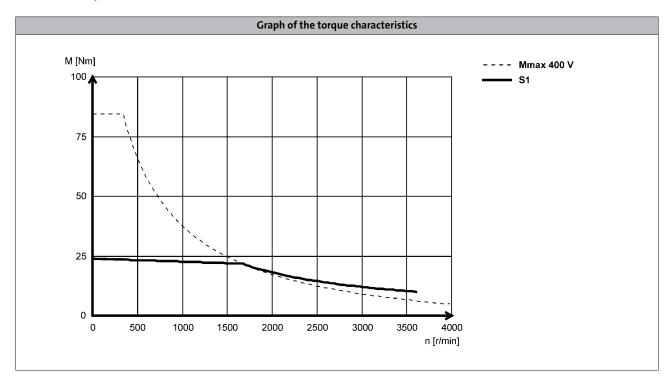
	n_k
	[r/min]
MCA	
MQA	150

Further selection tables with different switching frequencies are available with the following codes:
- DS_ZT_MCS_0001
- DS_ZT_MCA_0001
- DS_ZT_MDSKS_0001
- DS_ZT_MDFKS_0001

Simply enter this code (e.g. DS_ZT_MCS_0001) as a search string at **www.lenze.de/dsc** and you will be given the information immediately in the form of a PDF format.

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Dimensioning

Notes on the torque characteristics

Graph of the torque characteristics

M [Nm]

- - - - Mmax 400 V
—— S1

n [r/min]

With asynchronous servo motors, two characteristics are shown in each case. The characteristics for continuous operation (S1) show the speed-dependent constant torque of the motor when operating with a servo inverter that itself is operated at a constant switching frequency. The limit torque characteristics correspond to those that come about during operation of the motor with the largest possible 9400 Servo Drive in each case (see selection tables). The servo inverter is set to a variable switching frequency here.

Characteristics in the Internet

You can find the torque characteristic for inverter-motor combinations on the Internet at **www.lenze.de/dsc**. This lists all useful combinations with the servo inverters 9400, 9300, ECS and Inverter Drives 8400 TopLine. These characteristics are each determined using the factory default settings of the inverters:
- 9400 with variables switching frequency.
  This means that up to 6-fold overcurrent can be applied in borderline cases.
- 9300 and ECS with fixed switching frequency.
- 8400 TopLine with variables switching frequency.

The continuous operation characteristics (S1) show the inverter-independent motor rating values

Further information on the terms switching frequency and factory default settings can be found in the operating manual of the respective servo inverter.

MCA asynchronous servo motors

General information

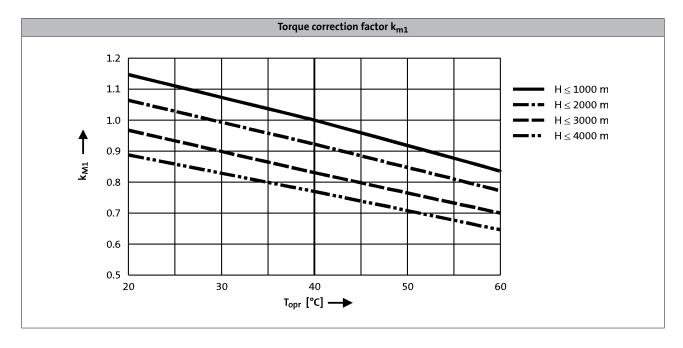--

Dimensioning

Influence of ambient temperature and site altitude

The information relating to the servo motors in the tables and graphs is valid for a maximum ambient temperature (T_{opr}) of 40 °C and a site altitude (H) up to 1000 m above sea level. The torque correction factor (k_{M1}) shall be applied to the S1 torque characteristic ($M_0...M_N$) in the event of differing installation conditions.

► The maximum permissible ambient temperature (T_{opr}) for servo motors with blowers is 40 °C

Torque correction factor k_{m1}

Legend:
- H ≤ 1000 m
- H ≤ 2000 m
- H ≤ 3000 m
- H ≤ 4000 m

Y-axis: k_{M1}
X-axis: T_{opr} [°C]

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MCA asynchronous servo motors

Technical data

Standards and operating conditions

			MCA	
Cooling type			Naturally ventilated	Blower
Enclosure				
EN 60529			IP54 IP65	IP54 IP23s [2]
Temperature class				
IEC/EN 60034-1; utilisation			F	
IEC/EN 60034-1; insulation system (enamel-insulated wire)			H	
Conformity				
CE			Low-Voltage Directive	
			2006/95/EC	
EAC			TP TC 004/2011 (TR CU 004/2011)	
Approval				
			UkrSEPRO	
CSA			CSA 22.2 No. 100	
cURus [3]			UL 1004-1 UL 1004-6 Power Conversion Equipment (File-No. E210321)	
Max. voltage load				
IEC/TS 60034-25			Pulse voltage limiting curve A	
Smooth running				
IEC 60072			Precision class [1] Normal class	
Linear movement				
IEC 60072			Precision class [1] Normal class	
Concentricity				
IEC 60072			Precision class [1] Normal class	
Mechanical ambient conditions (vibration)				
IEC/EN 60721-3-3			3M6 3M6	
Min. ambient operating temperature				
Without brake	$T_{opr,min}$	[°C]	-20	-15
With brake	$T_{opr,min}$	[°C]	-10	
Max. ambient temperature for operation				
	$T_{opr,max}$	[°C]	40	
Max. surface temperature				
	T	[°C]	140	110
Mechanical tolerance				
Flange centring diameter			$b_2 \leq 230$ mm = j6 $b_2 > 230$ mm = h6	
Shaft diameter			$d \leq 50$ mm = k6 $d > 50$ mm = m6	
Site altitude				
Amsl	H_{max}	[m]	4000	
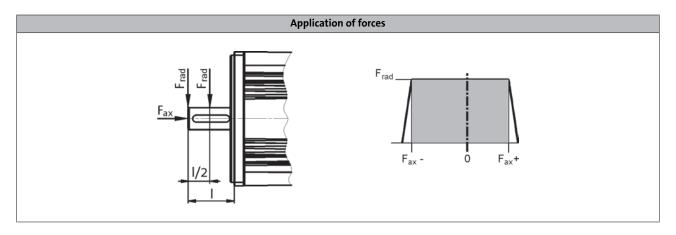
[1] MCA14, 17, 19 and 21.
[2] MCA20, 22 and 26.
[3] MCA20X29, MCA21X35 with circular connector for motor connection only
UR

6.6

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Permissible radial and axial forces

Application of forces

Application of force at l/2

	Bearing service life L_{10}														
	5000 h			10000 h			20000 h			30000 h			50000 h		
	F_{rad}	$F_{ax,-}$	$F_{ax,+}$	F_{rad}	$F_{ax,-}$	$F_{ax,+}$	F_{rad}	$F_{ax,-}$	$F_{ax,+}$	F_{rad}	$F_{ax,-}$	$F_{ax,+}$	F_{rad}	$F_{ax,-}$	$F_{ax,+}$
	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]
MCA10	630	-130	320	500	-60	250	400	-30	210	330	-10	190	230	0	200
MCA13	850	-110	570	700	-10	450	470	0	450		0	450			
MCA14	1000	-140	500	780	-60	420	550	-30	380	400	-10	360	250	0	350
MCA17	1380	-180	790	1040	-70	680	660	-40	650	440	-20	630	280	0	610
MCA19	1880	-50	1530	1080	-30	1510	500	-100	1490	160	0	1470			
MCA20	3400	-1330	690	2500	-1020	380	1950	-780	140	1700	-690	40			
MCA21	3200	-260	1740	2360	-70	1550	1470	-20	1504	1030	0	1480			
MCA22	3600	-2370	1700	2800	-1740	1090	2200	-1280	640	1900	-1080	440	1600	-880	240
MCA26	6950	-2500	1580	5400	-1800	880	4300	-1300	380	3700	-1090	160			

Application of force at l

|	Bearing service life L_{10}														
	5000 h			10000 h			20000 h			30000 h			50000 h		
	F_{rad}	$F_{ax,-}$	$F_{ax,+}$	F_{rad}	$F_{ax,-}$	$F_{ax,+}$	F_{rad}	$F_{ax,-}$	$F_{ax,+}$	F_{rad}	$F_{ax,-}$	$F_{ax,+}$	F_{rad}	$F_{ax,-}$	$F_{ax,+}$
	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]
MCA10	590	-130	320	470	-60	250	370	-30	210	310	-10	190	220	0	200
MCA13	780	-110	570	640	-10	450	430	0	450	300	0	450			
MCA14	930	-140	500	710	-60	420	490	-30	380	370	-10	360	230	0	350
MCA17	1270	-180	790	960	-70	680	610	-40	650	400	-20	630	260	0	610
MCA19	1740	-50	1530	1000	-30	1510	420	-100	1490	140	0	1470			
MCA20	3150	-1170	530	2300	-920	280	1800	-710	70	1400	-650	0			
MCA21	2940	-260	1740	2160	-70	1550	1350	-20	1504	950	0	1480			
MCA22	3500	-2240	1600	2600	-1640	1100	2050	-1200	560	1800	-1020	380	1450	-850	200
MCA26	6400	-2080	1150	5000	-1600	680	4000	-1160	230	3400	-1090	50			
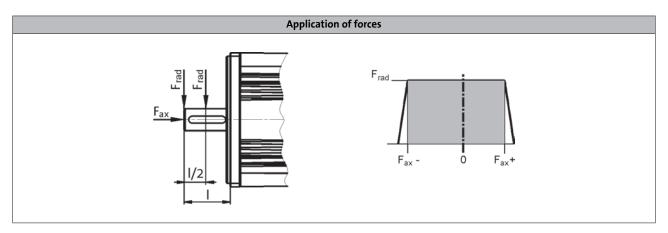
► The values for the bearing service life L_{10} relate to an average speed of 4000 r/min. For MCA20/22/26 the speed is 3000 r/min. Depending on the ambient temperatures, the service life of the bearings is also reduced by the grease lifetime.

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Permissible radial and axial forces

► Reinforced bearings

Application of forces

Application of force at l/2

Bearing service life L_{10}														
5000 h			10000 h			20000 h			30000 h			50000 h		
F_{rad}	$F_{ax,-}$	$F_{ax,+}$	F_{rad}	$F_{ax,-}$	$F_{ax,+}$	F_{rad}	$F_{ax,-}$	$F_{ax,+}$	F_{rad}	$F_{ax,-}$	$F_{ax,+}$	F_{rad}	$F_{ax,-}$	$F_{ax,+}$
[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]
MCA20	7100	-970	330	5100	-800	160	3900	-640	0					
MCA22	8500	-1850	1200	7000	-1400	760	5600	-1030	390	4350	-930	290	3200	-800	160
MCA26	10500	-2180	1250	8370	-1530	600	6670	-1130	200	5840	-960	30			

Application of force at l

Bearing service life L_{10}														
5000 h			10000 h			20000 h			30000 h			50000 h		
F_{rad}	$F_{ax,-}$	$F_{ax,+}$	F_{rad}	$F_{ax,-}$	$F_{ax,+}$	F_{rad}	$F_{ax,-}$	$F_{ax,+}$	F_{rad}	$F_{ax,-}$	$F_{ax,+}$	F_{rad}	$F_{ax,-}$	$F_{ax,+}$
[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]
MCA20	6350	-720	80	4100	-680	40	2800	-640	0					
MCA22	7000	-1750	1100	5500	-1300	660	4700	-920	280	3900	-820	180	3000	-700	60
MCA26	9600	-2200	1280	7700	-1280	360	6000	-960	30					

► The values for the bearing service life L_{10} refer to an average speed of 3000 r/min. Depending on the ambient temperatures, the service life of the bearings is also reduced by the grease lifetime.

6.6

Rated data, non-ventilated

► The data applies to a mains connection voltage of 3 x 400 V.
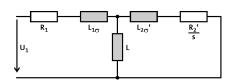
	n_N	M_0	M_N	M_{max}	P_N	I_0	I_N	$U_{N, AC}$	f_N	J [1]	$\eta_{100\%}$
	[r/min]	[Nm]	[Nm]	[Nm]	[kW]	[A]	[A]	[V]	[Hz]	[kgcm²]	[%]
MCA10I40	3950	2.30	2.00	10.0	0.80	2.60	2.40	390	140	2.40	0.70
MCA13I41	4050	4.60	4.00	32.0	1.70	4.60	4.40	390	140	8.30	75.0
MCA14L20	2000	8.00	6.70	60.0	1.40	3.90	3.30	390	70	19.2	84.0
MCA14L41	4100	8.00	5.40	60.0	2.30	7.70	5.80	390	140	19.2	78.0
MCA17N23	2300	12.8	10.8	100	2.60	6.00	5.50	390	80	36.0	86.0
MCA17N41	4110	12.8	9.50	100	4.10	12.0	10.2	350	140	36.0	83.0
MCA19S23	2340	22.5	16.3	180	4.00	9.90	8.20	390	80	72.0	90.0
MCA19S42	4150	22.5	12.0	180	5.20	19.7	14.0	330	140	72.0	83.0
MCA21X25	2490	39.0	24.6	300	6.40	15.9	13.5	390	85	180	85.0
MCA21X42	4160	39.0	17.0	300	7.40	31.8	19.8	320	140	180	84.0

	R_1	$R_{UV\ 20\,°C}$	$R_{UV\ 150\,°C}$	R_2	$L_{1\sigma}$	L	$L_{2\sigma}$	n_{max} [2]	m [1]
	[Ω]	[Ω]	[Ω]	[Ω]	[mH]	[mH]	[mH]	[r/min]	[kg]
MCA10I40	4.70	9.40	12.7	5.20	9.80	169	10.0		6.40
MCA13I41	1.70	3.40	4.60	1.41	5.40	92.6	4.90		10.4
MCA14L20	3.00	6.00	8.10	3.13	10.0	269	10.0		15.1
MCA14L41	0.75	1.50	2.00	0.78	2.50	65.8	2.50		15.1
MCA17N23	1.52	3.04	4.10	1.37	6.20	176	6.80	8000	22.9
MCA17N41	0.38	0.76	1.00	0.34	1.50	43.4	1.70		22.9
MCA19S23	0.69	1.38	1.90	0.62	3.20	111	3.90		44.7
MCA19S42	0.18	0.35	0.50	0.15	0.80	28.0	1.00		44.7
MCA21X25	0.36	0.72	1.00	0.36	2.30	78.1	2.80		60.0
MCA21X42	0.090	0.18	0.20	0.090	0.60	19.5	0.70		60.0

[1] Without brake.
[2] Mechanically permissible maximum speed.
The data in the R_1, $L_{1\sigma}$, L, R_2' and $L_{2\sigma}'$ columns is based on a single-phase equivalent circuit diagram at 20°C.

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Rated data, IP54 forced ventilated
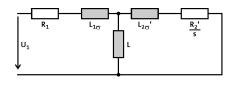
► The data applies to a mains connection voltage of 3 x 400 V.

	n_N [r/min]	M_0 [Nm]	M_N [Nm]	M_{max} [Nm]	P_N [kW]	I_0 [A]	I_N [A]	$U_{N, AC}$ [V]	f_N [Hz]	J [1)] [kgcm²]	$\eta_{100\%}$ [%]
MCA13I34	3410	7.00	6.30	32.0	2.20	6.30	6.00	390	120	8.30	72.0
MCA14L16	1635	13.5	12.0	60.0	2.10	5.30	4.80	390	60	19.2	80.0
MCA14L35	3455	13.5	10.8	60.0	3.90	10.5	9.10	390	120	19.2	79.0
MCA17N17	1680	23.9	21.5	100	3.80	9.10	8.50	390	60	36.0	83.0
MCA17N35	3480	23.9	19.0	100	6.90	18.1	15.8	390	120	36.0	81.0
MCA19S17	1700	40.0	36.3	180	6.40	15.4	13.9	390	60	72.0	82.0
MCA19S35	3510	40.0	36.0	180	13.2	30.8	28.7	390	120	72.0	85.0
MCA21X17	1710	75.0	61.4	300	11.0	25.8	22.5	390	60	180	85.0
MCA21X35	3520	75.0	55.0	300	20.3	49.5	42.5	390	120	180	88.0
MCA22P08...5F□□	760	120	110	500	8.75	23.4	22.1	345	28	487	80.0
MCA22P14...5F□□	1425	120	107	500	16.0	40.5	37.7	350	50	487	87.0
MCA22P17...5F□□	1670	120	106	500	18.5	46.7	42.7	360	58	487	88.0
MCA22P29...5F□□	2935	120	100	500	30.7	80.9	72.1	360	100	487	87.0
MCA26T05...5F□□	550	220	216	1100	12.4	35.4	34.9	350	19	1335	83.0
MCA26T10...5F□□	1030	220	210	1100	22.7	62.9	61.5	350	36	1335	88.0
MCA26T12...5F□□	1200	220	207	1100	26.0	78.4	75.1	350	41	1335	87.0
MCA26T22...5F□□	2235	220	195	1100	45.6	125	113	340	76	1335	92.0

	R_1 [Ω]	$R_{UV\ 20\,°C}$ [Ω]	$R_{UV\ 150\,°C}$ [Ω]	R_2 [Ω]	$L_{1\sigma}$ [mH]	L [mH]	$L_{2\sigma}$ [mH]	n_{max} [2)] [r/min]	m [1)] [kg]
MCA13I34	1.70	3.40	4.60	1.41	4.90	76.7	4.40		12.0
MCA14L16	3.00	6.00	8.10	3.13	9.50	224	9.30		16.9
MCA14L35	0.75	1.50	2.00	0.78	2.40	56.7	2.30		
MCA17N17	1.52	3.04	4.10	1.37	5.60	144	6.00		25.5
MCA17N35	0.38	0.76	1.00	0.34	1.40	36.9	1.50	8000	
MCA19S17	0.69	1.38	1.90	0.62	2.60	80.9	3.10		48.2
MCA19S35	0.18	0.35	0.50	0.15	0.70	20.3	0.80		
MCA21X17	0.36	0.72	1.00	0.36	2.10	68.9	2.60		63.5
MCA21X35	0.090	0.18	0.20	0.090	0.50	16.8	0.60		
MCA22P08...5F□□	0.54	1.07	1.62	0.48	3.56	94.9	4.80		105
MCA22P14...5F□□		0.36	0.54		3.60	94.2	4.85	6500	
MCA22P17...5F□□	0.13	0.27	0.40	0.12	0.90	23.4	1.21		
MCA22P29...5F□□		0.080	0.12			22.9			
MCA26T05...5F□□	0.29	0.59	0.89	0.25	2.86	66.8	5.04		194
MCA26T10...5F□□		0.20	0.30		2.93	69.2	5.12	5500	
MCA26T12...5F□□	0.080	0.15	0.23	0.062	0.74	18.1	1.29		
MCA26T22...5F□□		0.050	0.075		0.78	19.8			

1) Without brake.
2) Mechanically permissible maximum speed.
   The permanent speed in case of MCA20, 22 and 26 is limited to 70% of the value.

The data in the R_1, $L_{1\sigma}$, L, R_2' and $L_{2\sigma}'$ columns is based on a single-phase equivalent circuit diagram at 20°C.

6.6

Rated data, IP23s forced ventilated
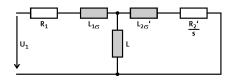
► The data applies to a mains connection voltage of 3 x 400 V.

	n_N	M_0	M_N	M_{max}	P_N	I_0	I_N	$U_{N, AC}$	f_N	J [1]	$\eta_{100\%}$
	[r/min]	[Nm]	[Nm]	[Nm]	[kW]	[A]	[A]	[V]	[Hz]	[kgcm²]	[%]
MCA20X14...2F□□	1420	68.0	61.0	250	9.07	26.0	23.0	350	50	171	82.0
MCA20X29...2F□□	2930	68.0	53.5	250	16.4	52.0	42.4	350	100	171	87.0
MCA22P08...2F□□	760	135	120	500	9.55	26.0	23.5	355	28	487	80.0
MCA22P14...2F□□	1425	135	115	500	17.2	45.1	40.0	360	50	487	86.0
MCA22P17...2F□□	1670	135	112	500	19.6	52.1	44.5	360	58	487	88.0
MCA22P29...2F□□	2935	135	110	500	33.8	90.2	77.8	360	100	487	89.0
MCA26T05...2F□□	550	290	280	1100	16.1	44.0	42.4	350	20	1335	81.0
MCA26T10...2F□□	1030	290	260	1100	28.0	78.0	69.6	350	36	1335	87.0
MCA26T12...2F□□	1200	290	255	1100	32.0	101	83.3	350	41	1335	87.0
MCA26T22...2F□□	2235	290	230	1100	53.8	160	127	340	76	1335	92.0

	R_1	$R_{UV\,20\,°C}$	$R_{UV\,150\,°C}$	R_2	$L_{1\sigma}$	L	$L_{2\sigma}$	n_{max} [2]	m [1]
	[Ω]	[Ω]	[Ω]	[Ω]	[mH]	[mH]	[mH]	[r/min]	[kg]
MCA20X14...2F□□	0.37	0.73	1.10	0.36	2.01	60.2	2.14	6500	64.0
MCA20X29...2F□□	0.090	0.18	0.28	0.090	0.50	14.3	0.54		
MCA22P08...2F□□	0.54	1.07	1.62	0.48	3.50	91.9	4.74	6500	105
MCA22P14...2F□□		0.36	0.54		3.55	90.9	4.79		
MCA22P17...2F□□	0.13	0.27	0.40	0.12	0.90	23.5	1.22		
MCA22P29...2F□□		0.080	0.12			22.9	1.21		
MCA26T05...2F□□	0.29	0.59	0.89	0.25	3.11	72.1	5.08	5500	194
MCA26T10...2F□□		0.20	0.30		3.17	71.4	5.14		
MCA26T12...2F□□	0.080	0.15	0.23	0.062	0.78	18.6	1.30		
MCA26T22...2F□□		0.050	0.077			20.2			

[1] Without brake.
[2] Mechanically permissible maximum speed.
   The permanent speed in case of MCA20, 22 and 26 is limited to 70% of the value.
The data in the R_1, $L_{1\sigma}$, L, R_2' and $L_{2\sigma}$' columns is based on a single-phase equivalent circuit diagram at 20°C.

MCA asynchronous servo motors

Technical data

Selection tables, Servo Drives 9400 HighLine

Non-ventilated motors

► The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 4 kHz.

				E94A□□	E0024	E0034	E0044	E0074	E0094	E0134	E0174	E0244	E0324
				I_N	1.9	3.1	5.0	8.8	11.7	16.3	20.6	29.4	38.4
				$I_{0,max}$	6.0	10.0	16.0	21.0	28.0	39.0	49.5	58.8	76.8
MCA	M_N	n_N	I_N	P_N / I_{max}	6.0	10.0	16.0	21.0	28.0	39.0	49.5	58.8	76.8
10I40	2.0	3950	2.4	0.80 — M_0	1.1	2.3							
				M_N	1.0	2.0							
				$M_{0,max}$	6.9	10.0							
				M_{max}	6.9	10.0							
				n_{eto}	-	-							
13I41	4.0	4050	4.4	1.70 — M_0			4.6	4.6					
				M_N			4.0	4.0					
				$M_{0,max}$			18.9	20.8					
				M_{max}			18.9	20.8					
				n_{eto}			-	-					
14L20	6.7	2000	3.3	1.40 — M_0		5.1	8.0						
				M_N		4.4	6.7						
				$M_{0,max}$		25.0	42.8						
				M_{max}		25.0	42.8						
				n_{eto}		-	-						
14L41	5.4	4100	5.8	2.30 — M_0			3.5	8.0	8.0				
				M_N			3.5	5.4	5.4				
				$M_{0,max}$			21.5	27.0	31.3				
				M_{max}			21.5	27.0	31.3				
				n_{eto}			-	-	-				
17N23	10.8	2300	5.5	2.60 — M_0			9.5	12.8					
				M_N			9.0	10.8					
				$M_{0,max}$			38.0	50.0					
				M_{max}			38.0	50.0					
				n_{eto}			-	-					
17N41	9.5	4110	10.2	4.10 — M_0				7.1	11.5	12.8	12.8		
				M_N				6.7	9.5	9.5	9.5		
				$M_{0,max}$				24.0	33.3	45.8	49.9		
				M_{max}				24.0	33.3	45.8	49.9		
				n_{eto}				-	-	-	-		
19S23	16.3	2340	8.2	4.00 — M_0				18.4	22.5	22.5			
				M_N				15.6	16.3	16.3			
				$M_{0,max}$				55.0	73.7	86.0			
				M_{max}				55.0	73.7	86.0			
				n_{eto}				-	-	-			
19S42	12.0	4150	14.0	5.20 — M_0						15.0	22.5	22.5	
				M_N						12.0	12.0	12.0	
				$M_{0,max}$						48.8	62.0	70.0	
				M_{max}						48.8	62.0	70.0	
				n_{eto}						-	-	-	
21X25	24.6	2490	13.5	6.40 — M_0					21.4	39.0	39.0	39.0	
				M_N					19.6	24.6	24.6	24.6	
				$M_{0,max}$					71.7	96.0	126.0	136.0	
				M_{max}					71.7	96.0	126.0	136.0	
				n_{eto}					-	-	-	-	

► I... [A], M... [Nm], n... [r/min], P... [kW]

6.6

Selection tables, Servo Drives 9400 HighLine

Non-ventilated motors

► The data applies to a mains connection voltage of 3 x 400 V and
an inverter switching frequency of 4 kHz.

					E94A□□	E0024	E0034	E0044	E0074	E0094	E0134	E0174	E0244	E0324
					I_N	1.9	3.1	5.0	8.8	11.7	16.3	20.6	29.4	38.4
					$I_{0,max}$	6.0	10.0	16.0	21.0	28.0	39.0	49.5	58.8	76.8
MCA	M_N	n_N	I_N	P_N	I_{max}	6.0	10.0	16.0	21.0	28.0	39.0	49.5	58.8	76.8
					M_0								31.3	39.0
					M_N								17.0	17.0
21X42	17.0	4160	19.8	7.40	$M_{0,max}$								71.7	91.0
					M_{max}								71.7	91.0
					n_{eto}								-	-

► I... [A], M... [Nm], n... [r/min], P... [kW]

6.6

MCA asynchronous servo motors

Technical data

Selection tables, Servo Drives 9400 HighLine

Forced ventilated IP54 motors

► The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 4 kHz.

				E94A□□	E0044	E0074	E0094	E0134	E0174	E0244	E0324	E0474	E0594	E0864
				I_N	5.0	8.8	11.7	16.3	20.6	29.4	38.4	47.0	59.0	86.0
				$I_{0,max}$	16.0	21.0	28.0	39.0	49.5	58.8	76.8	94.0	118.0	172.0
MCA	M_N	n_N	I_N	P_N	I_{max}	16.0	21.0	28.0	39.0	49.5	58.8	76.8	94.0	118.0	172.0
13I34	6.3	3410	6.0	2.20	M_0	4.6	7.0	7.0							
					M_N	4.4	6.3	6.3							
					$M_{0,max}$	20.8	26.0	29.2							
					M_{max}	20.8	26.0	29.2							
					n_{eto}	-	-	-							
14L16	12.0	1635	4.8	2.10	M_0	12.0	13.5								
					M_N	12.0	12.0								
					$M_{0,max}$	45.4	52.6								
					M_{max}	45.4	52.6								
					n_{eto}	-	-								
14L35	10.8	3455	9.1	3.90	M_0		10.1	13.5	13.5						
					M_N		9.7	10.8	10.8						
					$M_{0,max}$		32.4	46.0	60.0						
					M_{max}		32.4	46.0	60.0						
					n_{eto}		-	-	-						
17N17	21.5	1680	8.5	3.80	M_0		21.6	23.9	23.9						
					M_N		21.5	21.5	21.5						
					$M_{0,max}$		59.4	81.4	84.5						
					M_{max}		59.4	81.4	84.5						
					n_{eto}		-	-	-						
17N35	19.0	3480	15.8	6.90	M_0				19.4	23.9	23.9				
					M_N				19.0	19.0	19.0				
					$M_{0,max}$				59.2	75.0	90.0				
					M_{max}				59.2	75.0	90.0				
					n_{eto}				-	-	-				
19S17	36.3	1700	13.9	6.40	M_0				40.0	40.0	40.0				
					M_N				36.3	36.3	36.3				
					$M_{0,max}$				105.0	133.0	148.0				
					M_{max}				105.0	133.0	148.0				
					n_{eto}				-	-	-				
19S35	36.0	3510	28.7	13.20	M_0						36.9	40.0	40.0	40.0	
					M_N						36.0	36.0	36.0	36.0	
					$M_{0,max}$						82.0	112.0	132.0	160.0	
					M_{max}						82.0	112.0	132.0	160.0	
					n_{eto}						-	-	-	-	
21X17	61.4	1710	22.5	11.00	M_0					54.4	75.0	75.0	75.0		
					M_N					50.4	61.4	61.4	61.4		
					$M_{0,max}$					134.0	158.0	215.0	246.0		
					M_{max}					134.0	158.0	215.0	246.0		
					n_{eto}					-	-	-	-		
21X35	55.0	3520	42.5	20.30	M_0								63.9	75.0	75.0
					M_N								55.0	55.0	55.0
					$M_{0,max}$								134.0	167.0	232.0
					M_{max}								134.0	167.0	232.0
					n_{eto}								-	-	-

► I... [A], M... [Nm], n... [r/min], P... [kW]

6.6

Selection tables, Servo Drives 9400 HighLine

Forced ventilated IP54 motors

► The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 8 kHz.

				E94A□□	E0174	E0244	E0324	E0474	E0594	E0864	E1044	E1454	E1724	E2024	E2454
				I_N	16.5	23.5	32.0	41.0	41.0	73.0	78.0	102.0	120.0	131.0	160.0
				$I_{0,max}$	49.5	58.8	76.8	94.0	118.0	172.0	208.0	261.0	310.0	364.0	441.0
MCA	M_N	n_N	I_N	I_{max}	49.5	58.8	76.8	94.0	118.0	172.0	208.0	261.0	310.0	364.0	441.0
22P08-...5F□□	110.0	760	22.1	8.80	M_0	64.0	110.0	120.0								
					M_N	64.0	110.0	110.0								
					$M_{0,max}$	261.0	313.0	402.0								
					M_{max}	261.0	313.0	402.0								
					n_{eto}	-	-	-								
22P14-...5F□□	107.0	1425	37.7	16.00	M_0			82.0	120.0	120.0						
					M_N			82.0	107.0	107.0						
					$M_{0,max}$			242.0	300.0	372.0						
					M_{max}			242.0	300.0	372.0						
					n_{eto}			-	-	-						
22P17-...5F□□	105.0	1670	42.7	18.50	M_0					99.0	120.0					
					M_N					99.0	106.0					
					$M_{0,max}$					325.0	463.0					
					M_{max}					325.0	463.0					
					n_{eto}					-	-					
22P29-...5F□□	100.0	2935	72.1	30.70	M_0							110.0	120.0	120.0		
					M_N							100.0	100.0	100.0		
					$M_{0,max}$							335.0	416.0	465.0		
					M_{max}							335.0	416.0	465.0		
					n_{eto}							-	-	-		
26T05-...5F□□	216.0	550	34.9	12.40	M_0			191.0	220.0	220.0	220.0					
					M_N			191.0	216.0	216.0	216.0					
					$M_{0,max}$			531.0	665.0	826.0	1010.0					
					M_{max}			531.0	665.0	826.0	1010.0					
					n_{eto}			-	-	-	-					
26T10-...5F□□	210.0	1030	61.5	22.70	M_0					77.0	220.0	220.0	220.0			
					M_N					77.0	210.0	210.0	210.0			
					$M_{0,max}$					472.0	713.0	855.0	1044.0			
					M_{max}					472.0	713.0	855.0	1044.0			
					n_{eto}					-	-	-	-			
26T12-...5F□□	207.0	1200	75.1	26.00	M_0						204.0	219.0	220.0	220.0		
					M_N						204.0	207.0	207.0	207.0		
					$M_{0,max}$						502.0	609.0	739.0	819.0		
					M_{max}						502.0	609.0	739.0	819.0		
					n_{eto}						-	-	-	-		
26T22-...5F□□	195.0	2235	112.9	45.60	M_0								154.0	211.0	220.0	220.0
					M_N								154.0	195.0	195.0	195.0
					$M_{0,max}$								523.0	611.0	711.0	843.0
					M_{max}								523.0	611.0	711.0	843.0
					n_{eto}								-	-	-	-

► I... [A], M... [Nm], n... [r/min], P... [kW]
► If the motors are operated at a lower switching frequency, please contact your Lenze sales office!
► When operating at 4 kHz, the motor generates just 95 % of its rated torque with increased noise emissions.

Selection tables, Servo Drives 9400 HighLine

Forced ventilated IP23s motors

► The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 8 kHz.

					E94A□□	E0174	E0244	E0324	E0474	E0594	E0864	E1044	E1454	E1724	E2024	E2454	E2924
					I_N	16.5	23.5	32.0	41.0	41.0	73.0	78.0	102.0	120.0	131.0	160.0	191.0
					$I_{0,max}$	49.5	58.8	76.8	94.0	118.0	172.0	208.0	261.0	310.0	364.0	441.0	526.0
MCA	M_N	n_N	I_N	P_N	I_{max}	49.5	58.8	76.8	94.0	118.0	172.0	208.0	261.0	310.0	364.0	441.0	526.0
20X14-...2F□□	61.0	1420	23.0	9.10	M_0	32.5	66.0										
					M_N	32.5	61.0										
					$M_{0,max}$	154.2	190.0										
					M_{max}	154.2	190.0										
					n_{eto}	-	-										
20X29-...2F□□	53.5	2930	42.4	16.40	M_0			28.0	51.6	51.6							
					M_N			28.0	51.6	51.6							
					$M_{0,max}$			116.0	148.2	192.8							
					M_{max}			116.0	148.2	192.8							
					n_{eto}			-	-	-							
22P08-...2F□□	120.0	760	23.5	9.60	M_0		120.0	135.0									
					M_N		120.0	120.0									
					$M_{0,max}$		313.0	402.0									
					M_{max}		313.0	402.0									
					n_{eto}		-	-									
22P14-...2F□□	115.0	1425	40.0	17.20	M_0				118.0	118.0							
					M_N				115.0	115.0							
					$M_{0,max}$				300.0	372.0							
					M_{max}				300.0	372.0							
					n_{eto}				-	-							
22P17-...2F□□	112.0	1670	44.5	19.60	M_0					99.0	135.0						
					M_N					99.0	112.0						
					$M_{0,max}$					325.0	463.0						
					M_{max}					325.0	463.0						
					n_{eto}					-	-						
22P29-...2F□□	110.0	2935	77.8	33.80	M_0							110.0	135.0	135.0			
					M_N							110.0	110.0	110.0			
					$M_{0,max}$							335.0	416.0	486.0			
					M_{max}							335.0	416.0	486.0			
					n_{eto}							-	-	-			
26T05-...2F□□	280.0	550	42.4	16.10	M_0				268.0	268.0	290.0						
					M_N				268.0	268.0	280.0						
					$M_{0,max}$				665.0	826.0	1100.0						
					M_{max}				665.0	826.0	1100.0						
					n_{eto}				-	-	-						
26T10-...2F□□	260.0	1030	69.6	28.00	M_0						270.0	290.0	290.0				
					M_N						260.0	260.0	260.0				
					$M_{0,max}$						713.0	855.0	1044.0				
					M_{max}						713.0	855.0	1044.0				
					n_{eto}						-	-	-				

► I... [A], M... [Nm], n... [r/min], P... [kW]
► If the motors are operated at a lower switching frequency, please contact your Lenze sales office!
► When operating at 4 kHz, the motor generates just 95 % of its rated torque with increased noise emissions.

6.6

Selection tables, Servo Drives 9400 HighLine

Forced ventilated IP23s motors

► The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 8 kHz.

MCA	M_N	n_N	I_N	P_N	E94A□□	E0174	E0244	E0324	E0474	E0594	E0864	E1044	E1454	E1724	E2024	E2454	E2924
					I_N	16.5	23.5	32.0	41.0	41.0	73.0	78.0	102.0	120.0	131.0	160.0	191.0
					$I_{0,max}$	49.5	58.8	76.8	94.0	118.0	172.0	208.0	261.0	310.0	364.0	441.0	526.0
					I_{max}	49.5	58.8	76.8	94.0	118.0	172.0	208.0	261.0	310.0	364.0	441.0	526.0
26T12-...2F□□	255.0	1200	83.3	32.00	M_0						204.0	219.0	290.0	290.0	290.0		
					M_N						204.0	219.0	255.0	255.0	255.0		
					$M_{0,max}$						502.0	609.0	739.0	840.0	896.0		
					M_{max}						502.0	609.0	739.0	840.0	896.0		
					n_{eto}						-	-	-	-	-		
26T22-...2F□□	230.0	2235	126.7	53.80	M_0									211.0	242.0	290.0	290.0
					M_N									211.0	230.0	230.0	230.0
					$M_{0,max}$									611.0	711.0	843.0	1001.0
					M_{max}									611.0	711.0	843.0	1001.0
					n_{eto}									-	-	-	-

► I... [A], M... [Nm], n... [r/min], P... [kW]
► If the motors are operated at a lower switching frequency, please contact your Lenze sales office!
► When operating at 4 kHz, the motor generates just 95 % of its rated torque with increased noise emissions.

6.6

MCA asynchronous servo motors

Technical data

Selection tables, Inverter Drives 8400 TopLine

Non-ventilated motors

► The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 8 kHz.

MCA	M_N	n_N	I_N	P_N	E84AVTC	□5514	□7514	□1124	□1524	□2224	□3024	□4024	□5524	□7524	□1134	□1534	□1834
					I_N	1.8	2.4	3.2	3.9	5.9	7.3	9.5	13.0	16.5	23.5	32.0	39.0
					$I_{0,max}$	2.7	3.6	4.8	5.9	8.4	11.0	14.3	19.5	26.4	32.9	43.2	60.0
		I_N			I_{max}	3.6	4.8	6.4	7.8	11.2	14.6	19.0	26.0	33.0	47.0	64.0	78.0
10I40	2.0	3950	2.4	0.80	M_0	-	2.3	2.3	2.3	2.3							
					M_N	-	1.9	1.9	1.9	1.9							
					$M_{0,max}$	4.2	5.8	8.0	9.8	10.0							
					M_{max}	4.2	5.8	8.0	9.8	10.0							
					n_{eto}	-	-	-	-	-							
13I41	4.0	4050	4.4	1.70	M_0			-	-	4.6	4.6	4.6					
					M_N			-	-	4.0	4.0	4.0					
					$M_{0,max}$			7.6	9.6	14.3	18.9	22.9					
					M_{max}			7.6	9.6	14.3	18.9	22.9					
					n_{eto}			-	-	-	-	-					
14L20	6.7	2000	3.3	1.40	M_0		-	-	8.0	8.0	8.0						
					M_N		-	-	6.7	6.7	6.7						
					$M_{0,max}$		11.6	16.2	20.1	29.4	34.7						
					M_{max}		11.6	16.2	20.1	29.4	34.7						
					n_{eto}		-	-	-	-	-						
14L41	5.4	4100	5.8	2.30	M_0					-	8.0	8.0	8.0				
					M_N					-	5.4	5.4	5.4				
					$M_{0,max}$					14.1	19.0	25.1	31.0				
					M_{max}					14.1	19.0	25.1	31.0				
					n_{eto}					-	-	-	-				
17N23	10.8	2300	5.5	2.60	M_0				-	12.8	12.8	12.8	12.8				
					M_N				-	10.8	10.8	10.8	10.8				
					$M_{0,max}$				17.1	25.3	33.3	43.8	51.1				
					M_{max}				17.1	25.3	33.3	43.8	51.1				
					n_{eto}				-	-	-	-	-				
17N41	9.5	4110	10.2	4.10	M_0						-	-	12.8	12.8	12.8		
					M_N						-	-	9.5	9.5	9.5		
					$M_{0,max}$						16.5	22.3	31.1	39.9	49.5		
					M_{max}						16.5	22.3	31.1	39.9	49.5		
					n_{eto}						-	-	-	-	-		
19S23	16.3	2340	8.2	4.00	M_0							-	22.5	22.5	22.5		
					M_N							-	16.3	16.3	16.3		
					$M_{0,max}$							32.8	43.6	60.9	77.5		
					M_{max}							32.8	43.7	61.0	77.5		
					n_{eto}							-	-	-	-		
19S42	12.0	4150	14.0	5.20	M_0								-	22.5	22.5	22.5	
					M_N								-	12.0	12.0	12.0	
					$M_{0,max}$								28.5	37.0	53.7	64.7	
					M_{max}								28.5	37.0	53.8	64.7	
					n_{eto}								-	-	-	-	
21X25	24.6	2490	13.5	6.40	M_0								-	-	39.0	39.0	39.0
					M_N								-	-	24.5	24.5	24.5
					$M_{0,max}$								33.6	46.7	59.3	85.9	97.3
					M_{max}								33.6	46.7	59.3	85.9	97.6
					n_{eto}								-	-	-	-	-

► I... [A], M... [Nm], n... [r/min], P... [kW]

6.6

Selection tables, Inverter Drives 8400 TopLine

Non-ventilated motors

► The data applies to a mains connection voltage of 3 x 400 V and
  an inverter switching frequency of 8 kHz.

MCA	M_N	n_N	I_N	P_N	E84AVTC	□5514	□7514	□1124	□1524	□2224	□3024	□4024	□5524	□7524	□1134	□1534	□1834
					I_N	1.8	2.4	3.2	3.9	5.9	7.3	9.5	13.0	16.5	23.5	32.0	39.0
					$I_{0,max}$	2.7	3.6	4.8	5.9	8.4	11.0	14.3	19.5	26.4	32.9	43.2	60.0
					I_{max}	3.6	4.8	6.4	7.8	11.2	14.6	19.0	26.0	33.0	47.0	64.0	78.0
21X42	17.0	4160	19.8	7.40	M_0									-	39.0	39.0	39.0
					M_N									-	17.0	17.0	17.0
					$M_{0,max}$									35.3	52.2	72.1	88.5
					M_{max}									35.3	52.2	72.1	88.5
					n_{eto}									-	-	-	-

► I... [A], M... [Nm], n... [r/min], P... [kW]

Selection tables, Inverter Drives 8400 TopLine

Forced ventilated IP54 motors

► The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 8 kHz.

MCA	M_N	n_N	I_N	P_N	E84AVTC	□1524	□2224	□3024	□4024	□5524	□7524
					I_N	3.9	5.9	7.3	9.5	13.0	16.5
					$I_{0,max}$	5.9	8.4	11.0	14.3	19.5	26.4
					I_{max}	7.8	11.2	14.6	19.0	26.0	33.0
13I34	6.3	3410	6.0	2.20	M_0		-	7.0	7.0	7.0	
					M_N		-	6.2	6.2	6.2	
					$M_{0,max}$		16.0	21.4	28.2	32.0	
					M_{max}		16.0	21.4	28.2	32.0	
					n_{eto}		-	-	-	-	
14L16	12.0	1635	4.8	2.10	M_0	-	13.5	13.5	13.5		
					M_N	-	12.3	12.3	12.3		
					$M_{0,max}$	23.4	34.7	45.5	50.8		
					M_{max}	23.4	34.7	45.5	50.8		
					n_{eto}	-	-	-	-		
14L35	10.8	3455	9.1	3.90	M_0			-	13.5	13.5	13.5
					M_N			-	10.8	10.8	10.8
					$M_{0,max}$			21.1	28.4	39.8	51.1
					M_{max}			21.1	28.4	39.8	51.1
					n_{eto}			-	-	-	-
17N17	21.5	1680	8.5	3.80	M_0			-	23.9	23.9	23.9
					M_N			-	21.6	21.6	21.6
					$M_{0,max}$			42.1	55.9	77.5	93.3
					M_{max}			42.2	56.0	77.5	93.3
					n_{eto}			-	-	-	-
17N35	19.0	3480	15.8	6.90	M_0					-	23.9
					M_N					-	18.9
					$M_{0,max}$					38.0	49.5
					M_{max}					38.0	49.5
					n_{eto}					-	-
19S17	36.3	1700	13.9	6.40	M_0					-	40.0
					M_N					-	36.0
					$M_{0,max}$					71.6	94.7
					M_{max}					71.6	94.7
					n_{eto}					-	-
19S35	36.0	3510	28.7	13.20	M_0						
					M_N						
					$M_{0,max}$						
					M_{max}						
					n_{eto}						
21X17	61.4	1710	22.5	11.00	M_0						-
					M_N						-
					$M_{0,max}$						99.0
					M_{max}						99.0
					n_{eto}						-
21X35	55.0	3520	42.5	20.30	M_0						
					M_N						
					$M_{0,max}$						
					M_{max}						
					n_{eto}						

► I... [A], M... [Nm], n... [r/min], P... [kW]

6.6

Selection tables, Inverter Drives 8400 TopLine

Forced ventilated IP54 motors

► The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 8 kHz.

□1134	□1534	□1834	□2234	□3034	□3734	□4534	E84AVTC	P_N	I_N	n_N	M_N	MCA
23.5	32.0	39.0	47.0	61.0	76.0	89.0	I_N					
32.9	43.2	60.0	70.5	91.5	114.0	133.5	$I_{0,max}$					
47.0	64.0	78.0	94.0	122.0	152.0	178.0	I_{max}					
							M_0					
							M_N					
							$M_{0,max}$	2.20	6.0	3410	6.3	13I34
							M_{max}					
							n_{eto}					
							M_0					
							M_N					
							$M_{0,max}$	2.10	4.8	1635	12.0	14L16
							M_{max}					
							n_{eto}					
13.5							M_0					
10.8							M_N					
56.5							$M_{0,max}$	3.90	9.1	3455	10.8	14L35
56.6							M_{max}					
-							n_{eto}					
							M_0					
							M_N					
							$M_{0,max}$	3.80	8.5	1680	21.5	17N17
							M_{max}					
							n_{eto}					
23.9	23.9						M_0					
18.9	18.9						M_N					
72.5	97.8						$M_{0,max}$	6.90	15.8	3480	19.0	17N35
72.5	97.8						M_{max}					
-	-						n_{eto}					
40.0	40.0						M_0					
36.0	36.0						M_N					
138.9	165.2						$M_{0,max}$	6.40	13.9	1700	36.3	19S17
139.0	165.3						M_{max}					
-	-						n_{eto}					
-	40.0	40.0	40.0	40.0			M_0					
-	35.9	35.9	35.9	35.9			M_N					
55.1	78.8	97.8	112.8	146.2			$M_{0,max}$	13.20	28.7	3510	36.0	19S35
55.1	78.8	97.8	112.9	146.2			M_{max}					
-	-	-	-	-			n_{eto}					
75.0	75.0	75.0	75.0				M_0					
61.4	61.4	61.4	61.4				M_N					
143.7	198.5	242.2	277.2				$M_{0,max}$	11.00	22.5	1710	61.4	21X17
144.0	198.7	242.3	277.2				M_{max}					
-	-	-	-				n_{eto}					
	-	-	75.0	75.0	75.0	75.0	M_0					
	-	-	55.1	55.1	55.1	55.1	M_N					
	97.5	120.6	138.5	177.5	216.7	267.8	$M_{0,max}$	20.30	42.5	3520	55.0	21X35
	97.5	120.6	138.6	178.0	217.5	269.8	M_{max}					
	-	-	-	-	-	-	n_{eto}					

► I... [A], M... [Nm], n... [r/min], P... [kW]

6.6

Selection tables, Inverter Drives 8400 TopLine

Forced ventilated IP54 motors

► The data applies to a mains connection voltage of 3 x 400 V and
an inverter switching frequency of 8 kHz.

					E84AVTC	□7524	□1134	□1534	□1834	□2234	□3034	□3734	□4534
					I_N	16.5	23.5	32.0	39.0	47.0	61.0	76.0	89.0
					$I_{0,max}$	26.4	32.9	43.2	60.0	70.5	91.5	114.0	133.5
MCA	M_N	n_N	I_N	P_N	I_{max}	33.0	47.0	64.0	78.0	94.0	122.0	152.0	178.0
22P08- ...5F□□	110.0	760	22.1	8.80	M_0	-	120.0	120.0	120.0	120.0			
					M_N	-	110.6	110.6	110.6	110.6			
					$M_{0,max}$	157.8	233.4	323.3	396.6	394.3			
					M_{max}	157.8	233.5	323.3	396.6	394.3			
					n_{eto}	-	-	-	-	-			
22P14- ...5F□□	107.0	1425	37.7	16.00	M_0			-	120.0	120.0	120.0	120.0	120.0
					M_N			-	107.2	107.2	107.2	107.2	107.2
					$M_{0,max}$			186.5	232.5	268.8	345.7	422.7	458.8
					M_{max}			186.7	232.7	269.0	346.3	423.7	460.9
					n_{eto}			-	-	-	-	-	-
22P17- ...5F□□	105.0	1670	42.7	18.50	M_0			-	-	120.0	120.0	120.0	120.0
					M_N			-	-	105.8	105.8	105.8	105.8
					$M_{0,max}$			162.7	204.2	236.9	307.8	374.9	461.2
					M_{max}			162.7	204.2	237.1	308.3	377.0	462.4
					n_{eto}			-	-	-	-	-	-
22P29- ...5F□□	100.0	2935	72.1	30.70	M_0						-	120.0	120.0
					M_N						-	99.9	99.9
					$M_{0,max}$						180.5	224.5	270.5
					M_{max}						180.8	226.0	271.4
					n_{eto}						-	-	-

► I... [A], M... [Nm], n... [r/min], P... [kW]
► If the motors are operated at a lower switching frequency, please
contact your Lenze sales office!

6.6

Selection tables, Inverter Drives 8400 TopLine

Forced ventilated IP23s motors

► The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 8 kHz.

					E84AVTC	□7524	□1134	□1534	□1834	□2234	□3034	□3734	□4534
					I_N	16.5	23.5	32.0	39.0	47.0	61.0	76.0	89.0
					$I_{0,max}$	26.4	32.9	43.2	60.0	70.5	91.5	114.0	133.5
MCA	M_N	n_N	I_N	P_N	I_{max}	33.0	47.0	64.0	78.0	94.0	122.0	152.0	178.0
20X14-...2F□□	61.0	1420	23.0	9.10	M_0	-	67.0	68.0	68.0	68.0			
					M_N	-	61.2	61.2	61.2	61.2			
					$M_{0,max}$	94.8	139.9	192.6	235.5	250.0			
					M_{max}	94.9	139.9	192.8	235.7	250.0			
					n_{eto}	-	-	-	-	-			
20X29-...2F□□	53.5	2930	42.4	16.40	M_0			-	-	57.0	68.0	68.0	68.0
					M_N			-	-	53.4	53.4	53.4	53.4
					$M_{0,max}$			96.8	121.2	140.3	182.5	222.1	250.0
					M_{max}			96.8	121.2	140.4	182.6	223.0	250.0
					n_{eto}			-	-	-	-	-	-
22P08-...2F□□	120.0	760	23.5	9.60	M_0	-	135.0	135.0	135.0	135.0			
					M_N	-	120.6	120.6	120.6	120.6			
					$M_{0,max}$	157.8	234.2	325.4	401.4	400.9			
					M_{max}	157.8	234.8	325.8	401.4	400.9			
					n_{eto}	-	-	-	-	-			
22P14-...2F□□	115.0	1425	40.0	17.20	M_0			-	-	135.0	135.0	135.0	135.0
					M_N			-	-	115.3	115.3	115.3	115.3
					$M_{0,max}$			188.4	235.1	270.8	350.2	425.8	493.6
					M_{max}			188.7	235.1	271.0	350.3	428.1	496.1
					n_{eto}			-	-	-	-	-	-
22P17-...2F□□	112.0	1670	44.5	19.60	M_0			-	-	135.0	135.0	135.0	135.0
					M_N			-	-	112.1	112.1	112.1	112.1
					$M_{0,max}$			163.1	204.6	237.9	309.7	376.9	463.1
					M_{max}			163.1	204.6	238.2	310.6	379.0	465.2
					n_{eto}			-	-	-	-	-	-
22P29-...2F□□	110.0	2935	77.8	33.80	M_0						-	-	135.0
					M_N						-	-	110.0
					$M_{0,max}$						180.0	224.4	268.2
					M_{max}						180.7	225.0	269.4
					n_{eto}						-	-	-

► I... [A], M... [Nm], n... [r/min], P... [kW]
► If the motors are operated at a lower switching frequency, please contact your Lenze sales office!

6.6

Selection tables, Servo Drives ECS

Non-ventilated motors

► The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 4 kHz.

					ECS□□	008C□B	016C□B	032C□B	048C□B	064C□B
					I_N	4.0	8.0	12.7	17.0	20.0
					$I_{0,max}$	4.6	9.1	18.1	27.2	36.3
MCA	M_N	n_N	I_N	P_N	I_{max}	8.0	16.0	32.0	48.0	64.0
10I40	2.0	3950	2.4	0.80	M_0	2.3				
					M_N	2.0				
					$M_{0,max}$	5.6				
					M_{max}	8.1				
					n_{eto}	-				
13I41	4.0	4050	4.4	1.70	M_0	3.0	4.6			
					M_N	3.0	4.0			
					$M_{0,max}$	4.3	11.0			
					M_{max}	9.4	18.2			
					n_{eto}	-	-			
14L20	6.7	2000	3.3	1.40	M_0	8.0	8.0			
					M_N	6.7	6.7			
					$M_{0,max}$	10.7	25.3			
					M_{max}	21.6	42.8			
					n_{eto}	-	-			
14L41	5.4	4100	5.8	2.30	M_0		8.0	8.0		
					M_N		5.4	5.4		
					$M_{0,max}$		11.0	24.0		
					M_{max}		20.7	29.1		
					n_{eto}		-	-		
17N23	10.8	2300	5.5	2.60	M_0		12.8	12.8		
					M_N		10.8	10.8		
					$M_{0,max}$		20.5	43.5		
					M_{max}		40.2	63.7		
					n_{eto}		-	-		
17N41	9.5	4110	10.2	4.10	M_0		6.1	12.8	12.8	
					M_N		6.1	9.5	9.5	
					$M_{0,max}$		7.8	21.5	33.5	
					M_{max}		17.4	29.6	57.7	
					n_{eto}		-	-	-	
19S23	16.3	2340	8.2	4.00	M_0		15.1	22.5		
					M_N		15.1	16.3		
					$M_{0,max}$		18.7	43.5		
					M_{max}		38.5	67.9		
					n_{eto}		-	-		
19S42	12.0	4150	14.0	5.20	M_0			9.8	16.7	
					M_N			9.8	12.0	
					$M_{0,max}$			18.4	31.9	
					M_{max}			29.9	58.2	
					n_{eto}			-	-	
21X25	24.6	2490	13.5	6.40	M_0			21.0	39.0	
					M_N			21.0	24.6	
					$M_{0,max}$			41.0	64.5	
					M_{max}			64.4	120.5	
					n_{eto}			-	-	

► I... [A], M... [Nm], n... [r/min], P... [kW]

6.6

Selection tables, Servo Drives ECS

Non-ventilated motors

► The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 4 kHz.

					ECS☐☐	008C☐B	016C☐B	032C☐B	048C☐B	064C☐B
					I_N	4.0	8.0	12.7	17.0	20.0
					$I_{0,max}$	4.6	9.1	18.1	27.2	36.3
MCA	M_N	n_N	I_N	P_N	I_{max}	8.0	16.0	32.0	48.0	64.0
					M_0				13.0	17.0
					M_N				13.0	17.0
21X42	17.0	4160	19.8	7.40	$M_{0,max}$				30.0	45.0
					M_{max}				59.4	83.0
					n_{eto}				-	-

► I... [A], M... [Nm], n... [r/min], P... [kW]

Selection tables, Servo Drives ECS

Forced ventilated IP54 motors

► The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 4 kHz.

MCA	M_N	n_N	I_N	P_N	ECS□□	008C□B	016C□B	032C□B	048C□B	064C□B
					I_N	4.0	8.0	12.7	17.0	20.0
					$I_{0,max}$	4.6	9.1	18.1	27.2	36.3
					I_{max}	8.0	16.0	32.0	48.0	64.0
13I34	6.3	3410	6.0	2.20	M_0		7.0			
					M_N		6.3			
					$M_{0,max}$		10.7			
					M_{max}		20.8			
					n_{eto}		-			
14L16	12.0	1635	4.8	2.10	M_0	8.9	13.5			
					M_N	8.9	12.0			
					$M_{0,max}$	11.5	25.4			
					M_{max}	21.6	46.7			
					n_{eto}	-	-			
14L35	10.8	3455	9.1	3.90	M_0		8.3	13.5	13.5	
					M_N		8.3	10.8	10.8	
					$M_{0,max}$		11.0	27.0	41.0	
					M_{max}		22.2	42.0	60.0	
					n_{eto}		-	-	-	
17N17	21.5	1680	8.5	3.80	M_0		19.5	23.9		
					M_N		19.5	21.5		
					$M_{0,max}$		23.0	53.0		
					M_{max}		44.8	80.0		
					n_{eto}		-	-		
17N35	19.0	3480	15.8	6.90	M_0			12.7	23.0	
					M_N			12.7	19.0	
					$M_{0,max}$			23.0	37.5	
					M_{max}			37.7	64.4	
					n_{eto}			-	-	
19S17	36.3	1700	13.9	6.40	M_0			28.3	40.0	40.0
					M_N			28.3	36.3	36.3
					$M_{0,max}$			46.5	72.0	98.0
					M_{max}			75.4	130.8	158.9
					n_{eto}			-	-	-
21X17	61.4	1710	22.5	11.00	M_0					52.5
					M_N					52.5
					$M_{0,max}$					107.0
					M_{max}					190.0
					n_{eto}					-

► I... [A], M... [Nm], n... [r/min], P... [kW]

6.6

MCA asynchronous servo motors

Technical data

Selection tables, Servo Inverter 9300

Non-ventilated motors

► The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 8 kHz.

				EVS	9322-E□	9323-E□	9324-E□	9325-E□	9326-E□	9327-E□	9328-E□	9329-E□
				I_N	2.5	3.9	7.0	13.0	23.5	32.0	47.0	59.0
				$I_{0,max}$	3.8	5.9	10.5	19.5	23.5	32.0	47.0	52.0
MCA	M_N	n_N	I_N	P_N	I_{max}	3.8	5.9	10.5	19.5	35.3	48.0	70.5	88.5
10I40	2.0	3950	2.4	0.80	M_0	2.2	2.3						
					M_N	2.0	2.0						
					$M_{0,max}$	4.4	7.3						
					M_{max}	4.4	7.3						
					n_{eto}	-	-						
13I41	4.0	4050	4.4	1.70	M_0			4.6	4.6				
					M_N			4.0	4.0				
					$M_{0,max}$			12.6	19.5				
					M_{max}			12.6	19.5				
					n_{eto}			-	-				
14L20	6.7	2000	3.3	1.40	M_0		8.0	8.0					
					M_N		6.7	6.7					
					$M_{0,max}$		15.1	29.3					
					M_{max}		15.1	29.3					
					n_{eto}		-	-					
14L41	5.4	4100	5.8	2.30	M_0			7.0	8.0				
					M_N			5.4	5.4				
					$M_{0,max}$			13.2	26.0				
					M_{max}			13.2	26.0				
					n_{eto}			-	-				
17N23	10.8	2300	5.5	2.60	M_0			12.8	12.8				
					M_N			10.8	10.8				
					$M_{0,max}$			24.4	46.2				
					M_{max}			24.4	46.2				
					n_{eto}			-	-				
17N41	9.5	4110	10.2	4.10	M_0				12.8	12.8	12.8		
					M_N				9.5	9.5	9.5		
					$M_{0,max}$				23.4	37.0	54.0		
					M_{max}				23.4	43.7	59.4		
					n_{eto}				-	-	-		
19S23	16.3	2340	8.2	4.00	M_0				22.5	22.5			
					M_N				16.3	16.3			
					$M_{0,max}$				47.2	78.0			
					M_{max}				47.2	88.2			
					n_{eto}				-	-			
19S42	12.0	4150	14.0	5.20	M_0				10.0	22.5	22.5		
					M_N				10.0	12.0	12.0		
					$M_{0,max}$				20.7	33.5	51.0		
					M_{max}				20.7	43.3	60.7		
					n_{eto}				-	-	-		
21X25	24.6	2490	13.5	6.40	M_0				23.7	39.0	39.0		
					M_N				23.7	24.6	24.6		
					$M_{0,max}$				46.2	66.0	84.0		
					M_{max}				46.2	78.0	92.4		
					n_{eto}				-	-	-		

► I... [A], M... [Nm], n... [r/min], P... [kW]

Selection tables, Servo Inverter 9300

Non-ventilated motors

► The data applies to a mains connection voltage of 3 x 400 V and
an inverter switching frequency of 8 kHz.

MCA	M_N	n_N	I_N	P_N	EVS	9322-E☐	9323-E☐	9324-E☐	9325-E☐	9326-E☐	9327-E☐	9328-E☐	9329-E☐
					I_N	2.5	3.9	7.0	13.0	23.5	32.0	47.0	59.0
					$I_{0,max}$	3.8	5.9	10.5	19.5	23.5	32.0	47.0	52.0
					I_{max}	3.8	5.9	10.5	19.5	35.3	48.0	70.5	88.5
					M_0					24.0	39.0	39.0	39.0
					M_N					17.0	17.0	17.0	17.0
21X42	17.0	4160	19.8	7.40	$M_{0,max}$					24.0	47.0	84.0	94.0
					M_{max}					43.9	63.3	96.8	123.0
					n_{eto}					-	-	-	-

► I... [A], M... [Nm], n... [r/min], P... [kW]

Selection tables, Servo Inverter 9300

Forced ventilated IP54 motors

► The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 8 kHz.

				EVS	9324-E□	9325-E□	9326-E□	9327-E□	9328-E□	9329-E□	9330-E□	9331-E□
				I_N	7.0	13.0	23.5	32.0	47.0	59.0	89.0	110.0
				$I_{0,max}$	10.5	19.5	23.5	32.0	47.0	52.0	80.0	110.0
MCA	M_N	n_N	I_N	P_N	I_{max}	10.5	19.5	35.3	48.0	70.5	88.5	133.5	165.0
13I34	6.3	3410	6.0	2.20	M_0	7.0	7.0						
					M_N	6.3	6.3						
					$M_{0,max}$	13.0	25.0						
					M_{max}	13.0	25.0						
					n_{eto}	-	-						
14L16	12.0	1635	4.8	2.10	M_0	13.5							
					M_N	12.0							
					$M_{0,max}$	29.6							
					M_{max}	29.6							
					n_{eto}	-							
14L35	10.8	3455	9.1	3.90	M_0		13.5	13.5					
					M_N		10.8	10.8					
					$M_{0,max}$		29.3	47.0					
					M_{max}		29.3	53.8					
					n_{eto}		-	-					
17N17	21.5	1680	8.5	3.80	M_0		23.9						
					M_N		21.5						
					$M_{0,max}$		57.2						
					M_{max}		57.2						
					n_{eto}		-						
17N35	19.0	3480	15.8	6.90	M_0			23.9	23.9	23.9			
					M_N			19.0	19.0	19.0			
					$M_{0,max}$			27.5	57.0	89.0			
					M_{max}			50.7	69.2	100.2			
					n_{eto}			-	-	-			
19S17	36.3	1700	13.9	6.40	M_0		34.0	40.0	40.0				
					M_N		34.0	36.3	36.3				
					$M_{0,max}$		50.1	76.0	112.0				
					M_{max}		50.1	95.9	130.8				
					n_{eto}		-	-	-				
19S35	36.0	3510	28.7	13.20	M_0			21.0	39.0	40.0	40.0	40.0	
					M_N			21.0	36.0	36.0	36.0	36.0	
					$M_{0,max}$			21.0	39.0	73.0	80.0	161.5	
					M_{max}			45.7	67.6	104.3	132.9	180.0	
					n_{eto}			-	-	-	-	-	
21X17	61.4	1710	22.5	11.00	M_0			65.5	75.0	75.0	75.0		
					M_N			61.4	61.4	61.4	61.4		
					$M_{0,max}$			65.5	102.0	178.0	200.0		
					M_{max}			104.1	143.3	210.7	257.3		
					n_{eto}			-	-	-	-		
21X35	55.0	3520	42.5	20.30	M_0					68.0	75.0	75.0	75.0
					M_N					55.0	55.0	55.0	55.0
					$M_{0,max}$					68.0	88.0	156.0	219.0
					M_{max}					107.7	135.9	205.0	250.1
					n_{eto}					-	-	-	-

► I... [A], M... [Nm], n... [r/min], P... [kW]

6.6

Selection tables, Servo Inverter 9300

Forced ventilated IP54 motors

► The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 8 kHz.

					EVS	9326-E□	9327-E□	9328-E□	9329-E□	9330-E□	9331-E□	9332-E□
					I_N	23.5	32.0	47.0	59.0	89.0	110.0	145.0
					$I_{0,max}$	23.5	32.0	47.0	52.0	80.0	110.0	126.0
MCA	M_N	n_N	I_N	P_N	I_{max}	35.3	48.0	70.5	88.5	133.5	165.0	217.5
22P08-...5F□□	110.0	760	22.1	8.80	M_0	115.0	120.0	120.0	120.0			
					M_N	108.0	110.0	110.0	110.0			
					$M_{0,max}$	115.0	166.0	242.0	267.0			
					M_{max}	185.0	247.0	338.8	345.8			
					n_{eto}	-	-	-	-			
22P14-...5F□□	107.0	1425	37.7	16.00	M_0			120.0	120.0	120.0		
					M_N			107.0	107.0	107.0		
					$M_{0,max}$			146.0	160.0	264.0		
					M_{max}			230.1	292.9	341.8		
					n_{eto}			-	-	-		
22P17-...5F□□	105.0	1670	42.7	18.50	M_0			120.0	120.0	120.0	120.0	
					M_N			106.0	106.0	106.0	106.0	
					$M_{0,max}$			124.0	140.0	240.0	335.0	
					M_{max}			180.5	227.7	342.1	378.3	
					n_{eto}			-	-	-	-	
22P29-...5F□□	100.0	2935	72.1	30.70	M_0					118.0	120.0	120.0
					M_N					100.0	100.0	100.0
					$M_{0,max}$					122.0	171.0	200.0
					M_{max}					215.6	273.1	355.1
					n_{eto}					-	-	-
26T05-...5F□□	216.0	550	34.9	12.40	M_0		191.0	220.0	220.0	220.0		
					M_N		191.0	216.0	216.0	216.0		
					$M_{0,max}$		191.0	303.0	333.0	615.0		
					M_{max}		313.0	482.0	612.0	751.0		
					n_{eto}		-	-	-	-		
26T10-...5F□□	210.0	1030	61.5	22.70	M_0				159.0	220.0	220.0	
					M_N				197.0	210.0	210.0	
					$M_{0,max}$				159.0	300.0	440.0	
					M_{max}				343.0	552.0	671.0	
					n_{eto}				-	-	-	
26T12-...5F□□	207.0	1200	75.1	26.00	M_0					207.0	220.0	220.0
					M_N					255.0	207.0	207.0
					$M_{0,max}$					258.0	327.0	397.0
					M_{max}					424.0	512.0	663.0
					n_{eto}					-	-	-
26T22-...5F□□	195.0	2235	112.9	45.60	M_0						177.0	220.0
					M_N						177.0	195.0
					$M_{0,max}$						203.0	220.0
					M_{max}						315.0	432.0
					n_{eto}						-	-

► I... [A], M... [Nm], n... [r/min], P... [kW]
► If the motors are operated at a lower switching frequency, please contact your Lenze sales office!

6.6

Selection tables, Servo Inverter 9300

Forced ventilated IP23s motors

► The data applies to a mains connection voltage of 3 x 400 V and an inverter switching frequency of 8 kHz.

MCA	M_N	n_N	I_N	P_N	EVS	9326-E□	9327-E□	9328-E□	9329-E□	9330-E□	9331-E□	9332-E□
					I_N	23.5	32.0	47.0	59.0	89.0	110.0	145.0
					$I_{0,max}$	23.5	32.0	47.0	52.0	80.0	110.0	126.0
					I_{max}	35.3	48.0	70.5	88.5	133.5	165.0	217.5
20X14-...2F□□	61.0	1420	23.0	9.10	M_0	61.0	68.0	68.0				
					M_N	61.0	61.0	61.0				
					$M_{0,max}$	61.0	93.0	153.0				
					M_{max}	109.3	156.7	232.1				
					n_{eto}	-	-	-				
20X29-...2F□□	53.5	2930	42.4	16.40	M_0		28.0	66.3	68.0	68.0		
					M_N		28.0	53.5	53.5	53.5		
					$M_{0,max}$		28.0	66.3	72.0	129.0		
					M_{max}		68.5	112.5	146.4	226.7		
					n_{eto}		-	-	-	-		
22P08-...2F□□	120.0	760	23.5	9.60	M_0	115.0	135.0	135.0	135.0			
					M_N	115.0	120.0	120.0	120.0			
					$M_{0,max}$	115.0	166.0	242.0	267.0			
					M_{max}	185.0	247.0	338.8	345.8			
					n_{eto}	-	-	-	-			
22P14-...2F□□	115.0	1425	40.0	17.20	M_0			135.0	135.0	135.0		
					M_N			115.0	115.0	115.0		
					$M_{0,max}$			146.0	160.0	264.0		
					M_{max}			230.1	292.9	341.8		
					n_{eto}			-	-	-		
22P17-...2F□□	112.0	1670	44.5	19.60	M_0			124.0	134.0	135.0	135.0	
					M_N			112.0	112.0	112.0	112.0	
					$M_{0,max}$			124.0	140.0	240.0	335.0	
					M_{max}			180.5	227.7	342.1	378.3	
					n_{eto}			-	-	-	-	
22P29-...2F□□	110.0	2935	77.8	33.80	M_0					118.0	135.0	135.0
					M_N					110.0	110.0	110.0
					$M_{0,max}$					122.0	171.0	200.0
					M_{max}					215.6	273.1	355.1
					n_{eto}					-	-	-
26T05-...2F□□	280.0	550	42.4	16.10	M_0		191.0	290.0	290.0	290.0		
					M_N		191.0	280.0	280.0	280.0		
					$M_{0,max}$		191.0	303.0	333.0	615.0		
					M_{max}		313.0	482.0	612.0	751.0		
					n_{eto}		-	-	-	-		
26T10-...2F□□	260.0	1030	69.6	28.00	M_0				159.0	290.0	290.0	
					M_N				197.0	260.0	260.0	
					$M_{0,max}$				159.0	300.0	440.0	
					M_{max}				343.0	552.0	671.0	
					n_{eto}				-	-	-	

► I... [A], M... [Nm], n... [r/min], P... [kW]
► If the motors are operated at a lower switching frequency, please contact your Lenze sales office!

6.6

Selection tables, Servo Inverter 9300

Forced ventilated IP23s motors

► The data applies to a mains connection voltage of 3 x 400 V and
an inverter switching frequency of 8 kHz.

					EVS	9326-E☐	9327-E☐	9328-E☐	9329-E☐	9330-E☐	9331-E☐	9332-E☐
					I_N	23.5	32.0	47.0	59.0	89.0	110.0	145.0
					$I_{0,max}$	23.5	32.0	47.0	52.0	80.0	110.0	126.0
MCA	M_N	n_N	I_N	P_N	I_{max}	35.3	48.0	70.5	88.5	133.5	165.0	217.5
26T12-...2F☐☐	255.0	1200	83.3	32.00	M_0					232.0	290.0	290.0
					M_N					255.0	255.0	255.0
					$M_{0,max}$					258.0	327.0	397.0
					M_{max}					424.0	512.0	663.0
					n_{eto}					-	-	-
26T22-...2F☐☐	230.0	2235	126.7	53.80	M_0						177.0	222.0
					M_N						177.0	230.0
					$M_{0,max}$						203.0	220.0
					M_{max}						315.0	432.0
					n_{eto}						-	-

► I... [A], M... [Nm], n... [r/min], P... [kW]
► If the motors are operated at a lower switching frequency, please
contact your Lenze sales office!

MCA asynchronous servo motors

Technical data

Torque characteristics

► The data applies to a mains connection voltage of 3 x 400 V.

MCA10I40 (non-ventilated)
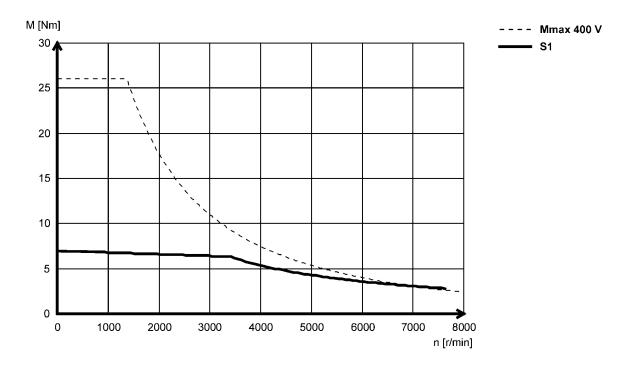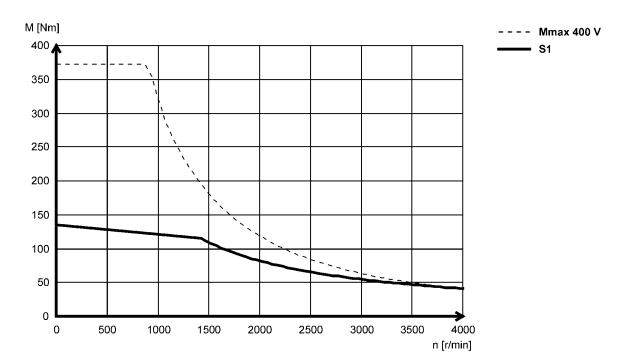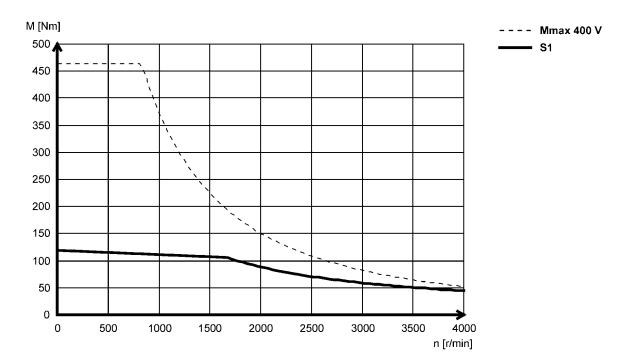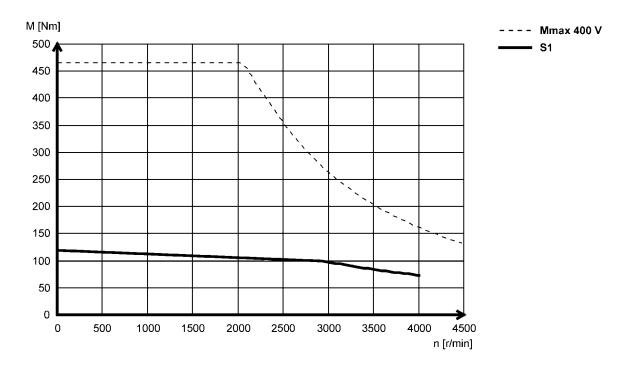
MCA asynchronous servo motors

Technical data

Torque characteristics
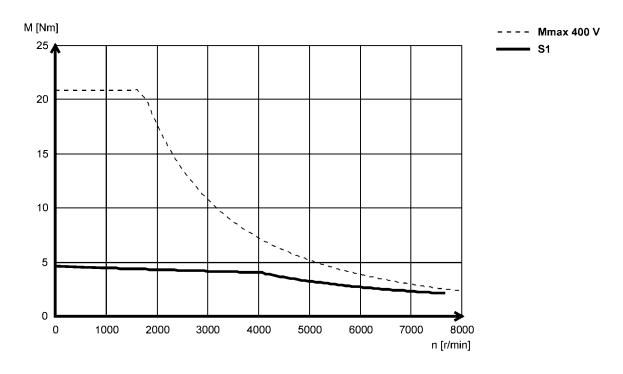
► The data applies to a mains connection voltage of 3 x 400 V.

MCA13I34 (forced ventilated)

MCA13I41 (non-ventilated)
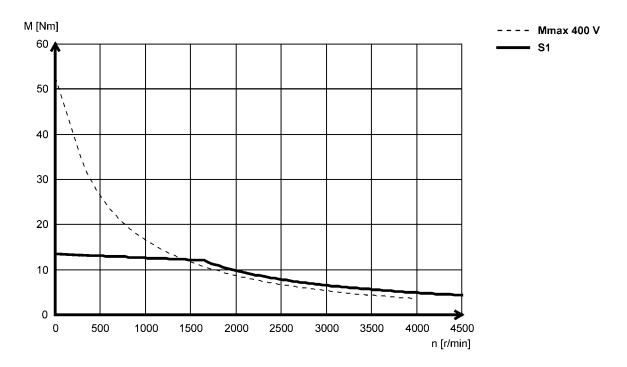
MCA asynchronous servo motors

Technical data

- -

Torque characteristics
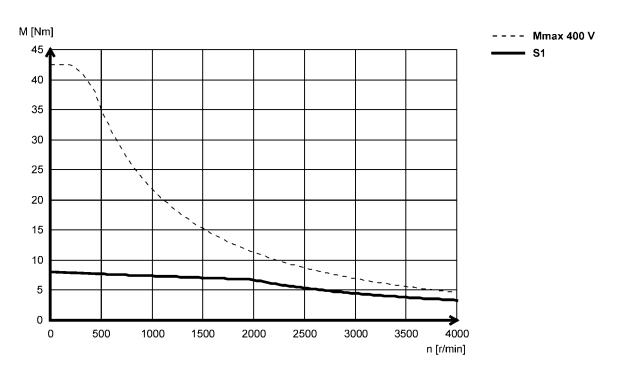
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MCA14L16 (forced ventilated)

MCA14L20 (non-ventilated)
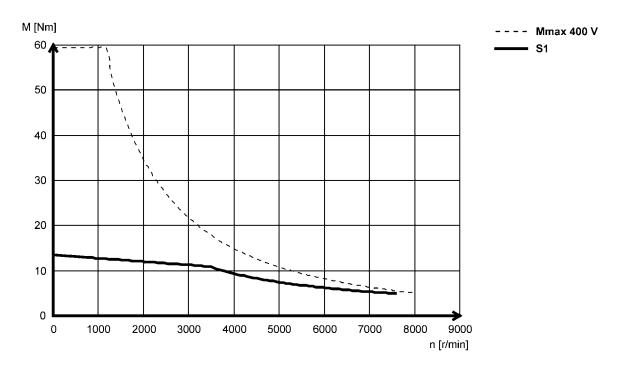
MCA asynchronous servo motors

Technical data

- -

Torque characteristics
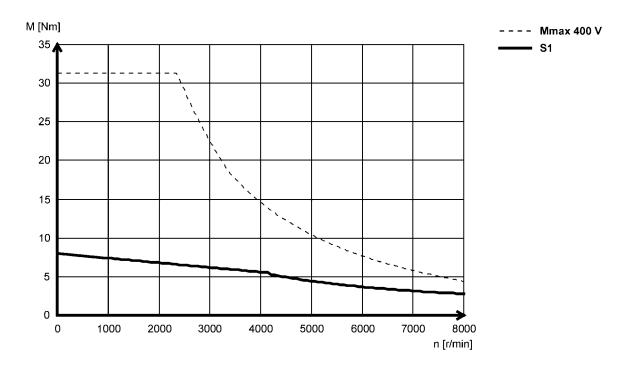
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MCA14L35 (forced ventilated)

MCA14L41 (non-ventilated)
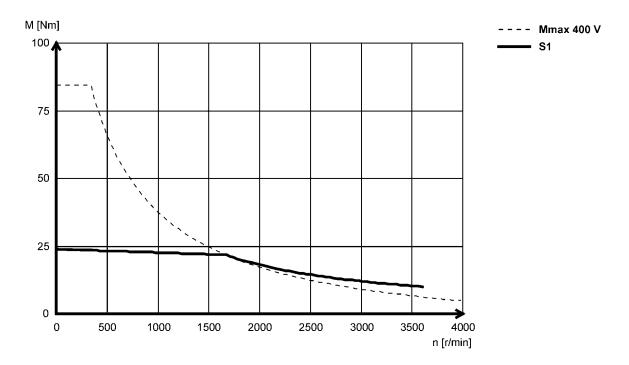
MCA asynchronous servo motors

Technical data

Torque characteristics
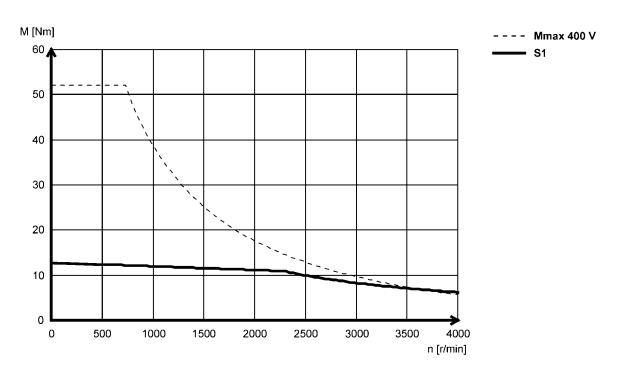
► The data applies to a mains connection voltage of 3 x 400 V.

MCA17N17 (forced ventilated)

MCA17N23 (non-ventilated)
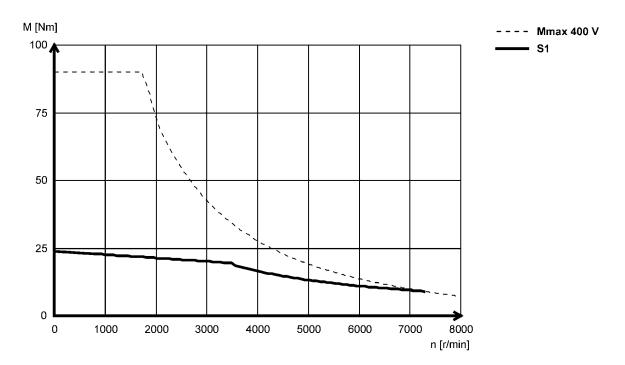
MCA asynchronous servo motors

Technical data

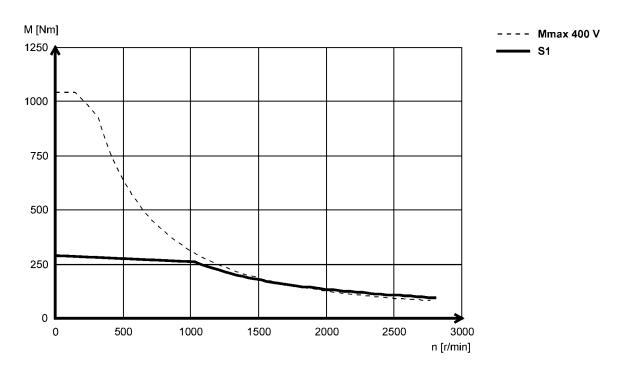--

Torque characteristics
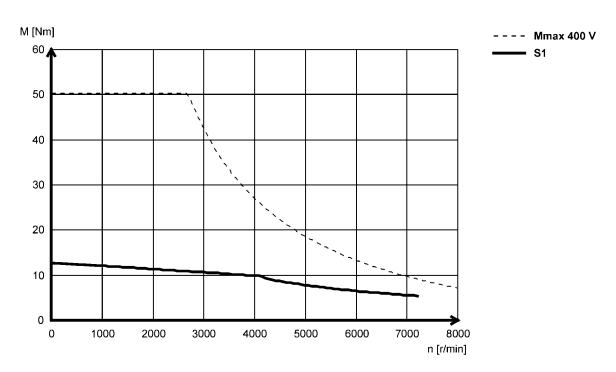
► The data applies to a mains connection voltage of 3 x 400 V.

MCA17N35 (forced ventilated)

MCA17N41 (non-ventilated)
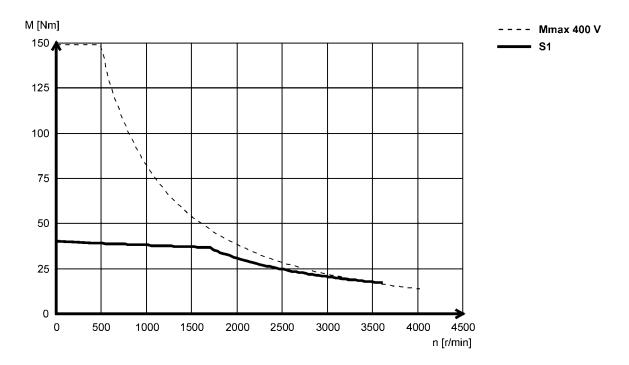
MCA asynchronous servo motors

Technical data

Torque characteristics
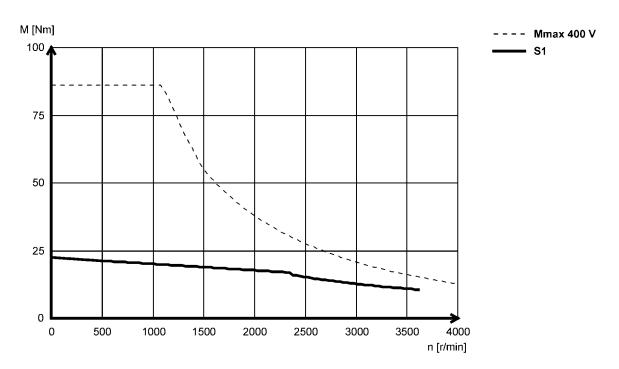
► The data applies to a mains connection voltage of 3 x 400 V.

MCA19S17 (forced ventilated)

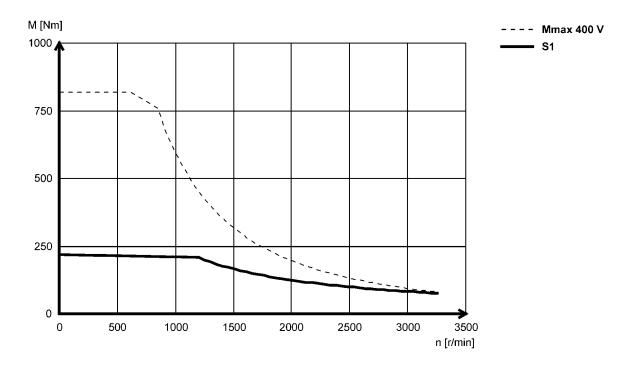**MCA19S23 (non-ventilated)**
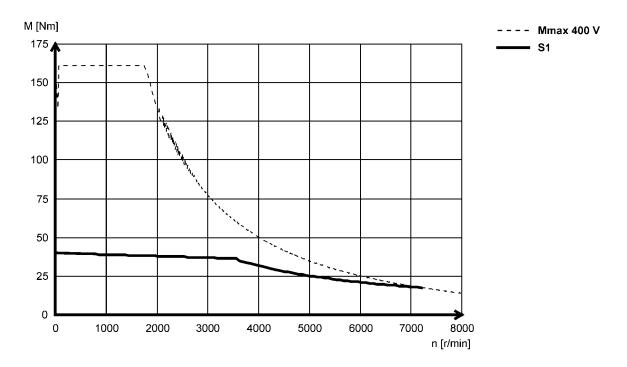
6.6

MCA asynchronous servo motors

Technical data

Torque characteristics
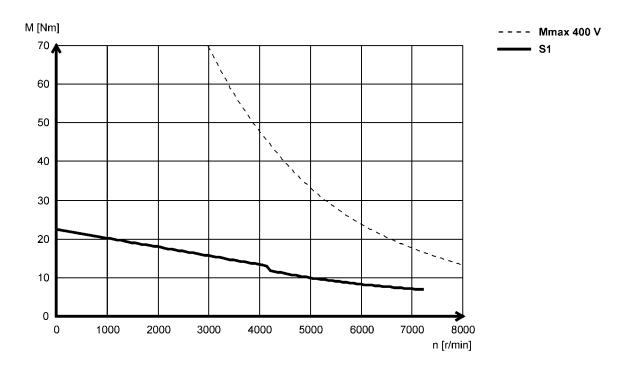
► The data applies to a mains connection voltage of 3 x 400 V.

MCA19S35 (forced ventilated)

MCA19S42 (non-ventilated)
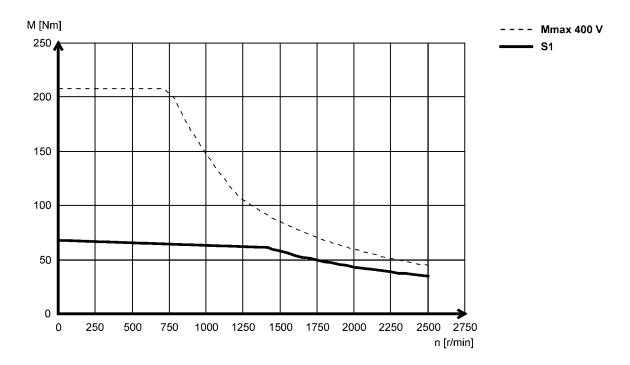
MCA asynchronous servo motors
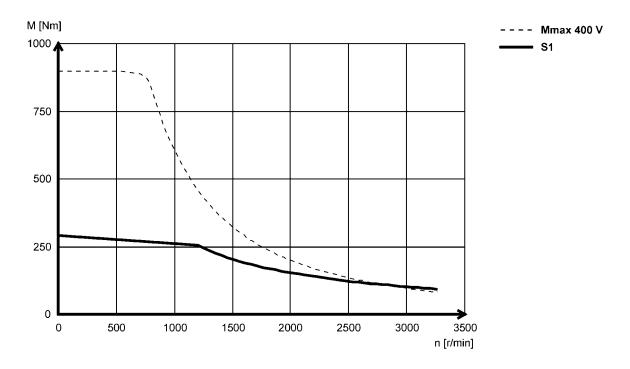
Technical data

_____

Torque characteristics
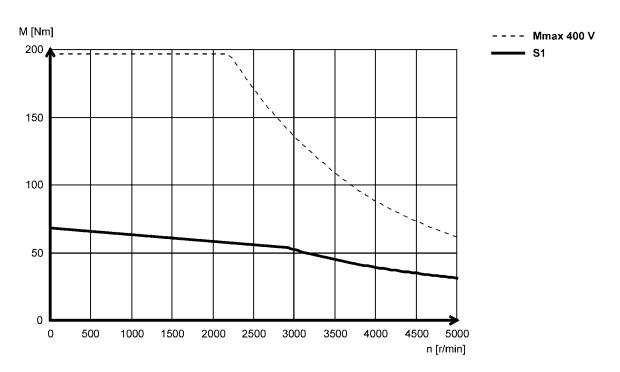
► The data applies to a mains connection voltage of 3 x 400 V.

MCA20X14...2F□□ (forced ventilated)

MCA20X29...2F□□ (forced ventilated)
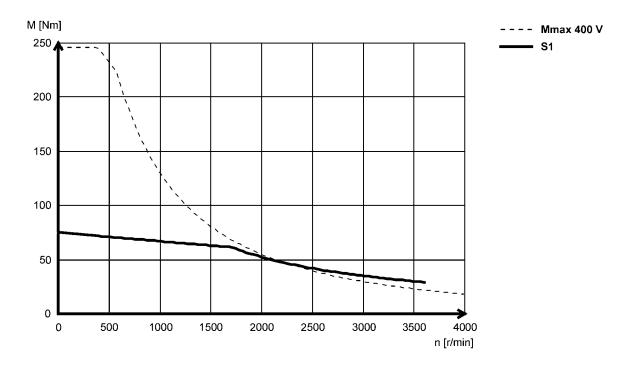
6.6

Torque characteristics
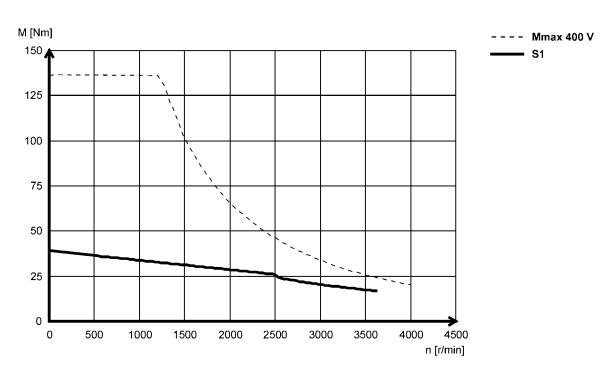
► The data applies to a mains connection voltage of 3 x 400 V.

MCA21X17 (forced ventilated)

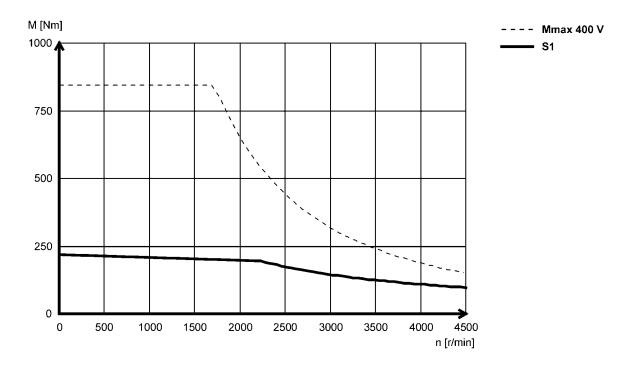**MCA21X25 (non-ventilated)**
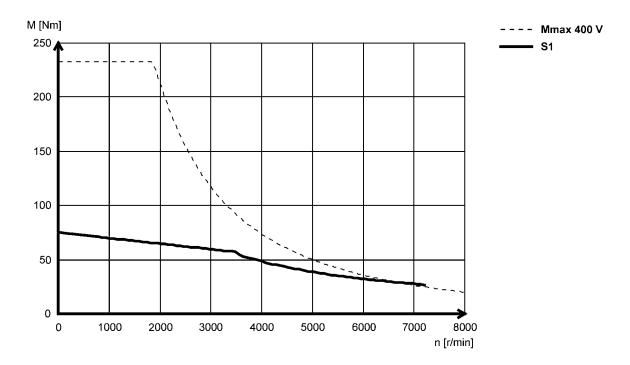
MCA asynchronous servo motors

Technical data

Torque characteristics
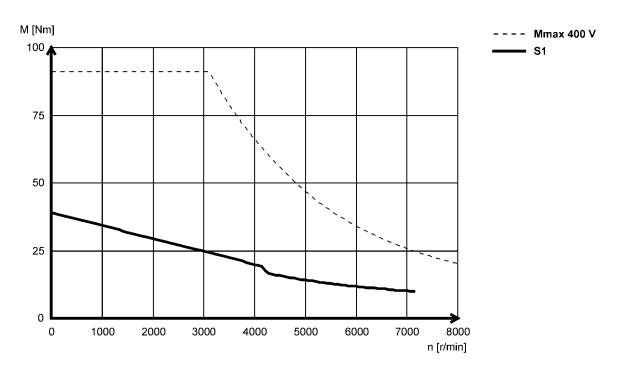
► The data applies to a mains connection voltage of 3 x 400 V.

MCA21X35 (forced ventilated)
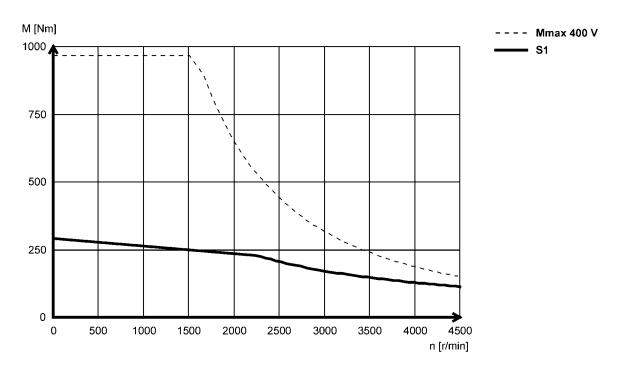

MCA21X42 (non-ventilated)
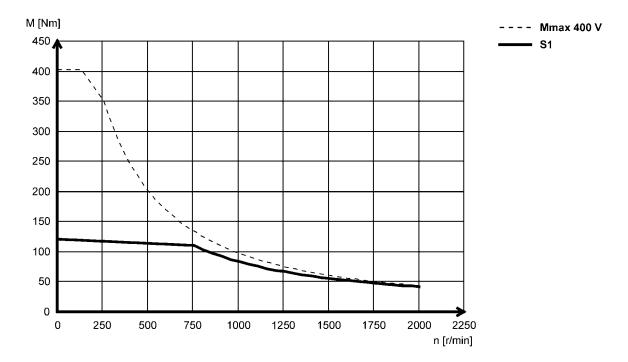
Torque characteristics
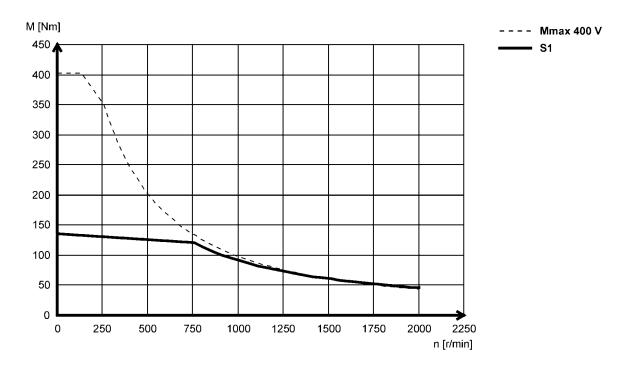
► The data applies to a mains connection voltage of 3 x 400 V.

MCA22P08...5F☐☐ (forced ventilated)

MCA22P08...2F☐☐ (forced ventilated)
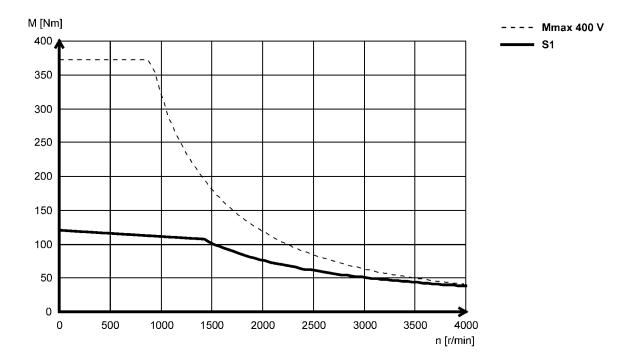
MCA asynchronous servo motors

Technical data

Torque characteristics

► The data applies to a mains connection voltage of 3 x 400 V.

MCA22P14...5F☐☐ (forced ventilated)

MCA22P14...2F☐☐ (forced ventilated)

Torque characteristics
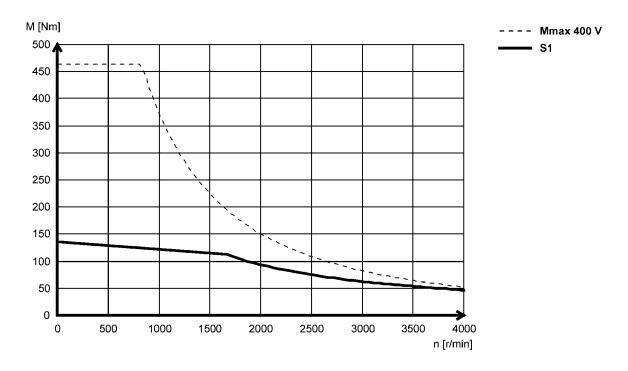
► The data applies to a mains connection voltage of 3 x 400 V.

MCA22P17...5F□□ (forced ventilated)


MCA22P17...2F□□ (forced ventilated)

MCA asynchronous servo motors

Technical data

Torque characteristics
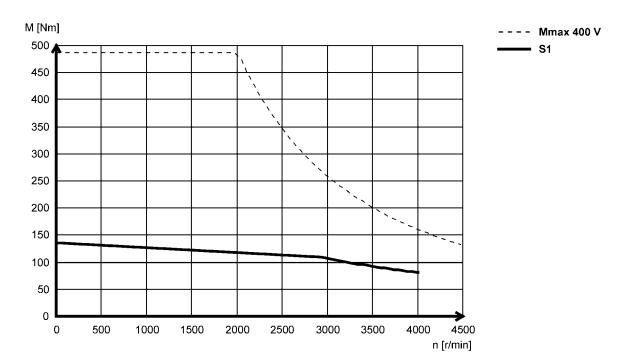
► The data applies to a mains connection voltage of 3 x 400 V.

MCA22P29...5F□□ (forced ventilated)

MCA22P29...2F□□ (forced ventilated)
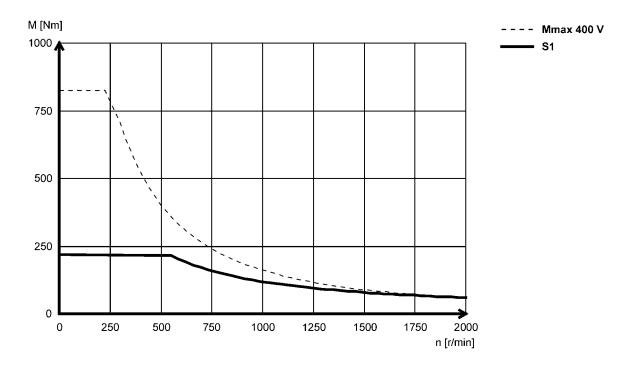
6.6

Torque characteristics
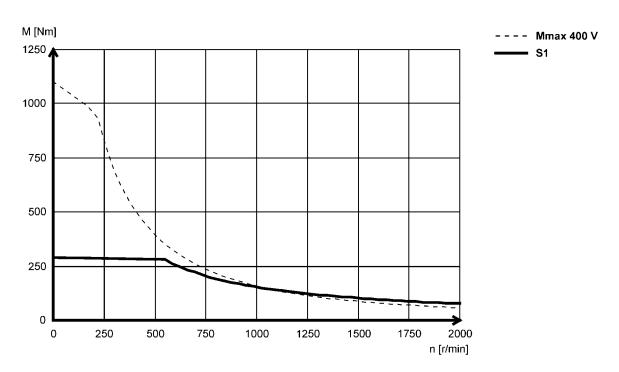
► The data applies to a mains connection voltage of 3 x 400 V.

MCA26T05...5F☐☐ (forced ventilated)

MCA26T05...2F☐☐ (forced ventilated)
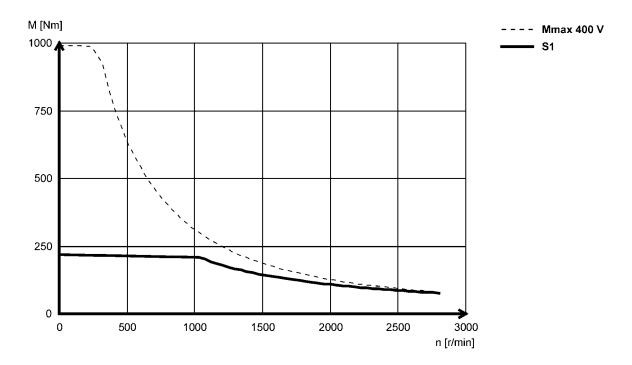
MCA asynchronous servo motors

Technical data

Torque characteristics

► The data applies to a mains connection voltage of 3 x 400 V.

MCA26T10...5F□□ (forced ventilated)

MCA26T10...2F□□ (forced ventilated)

MCA asynchronous servo motors

Technical data

Torque characteristics

► The data applies to a mains connection voltage of 3 x 400 V.

MCA26T12...5F□□ (forced ventilated)

MCA26T12...2F□□ (forced ventilated)

Torque characteristics

► The data applies to a mains connection voltage of 3 x 400 V.

MCA26T22...5F□□ (forced ventilated)

MCA26T22...2F□□ (forced ventilated)
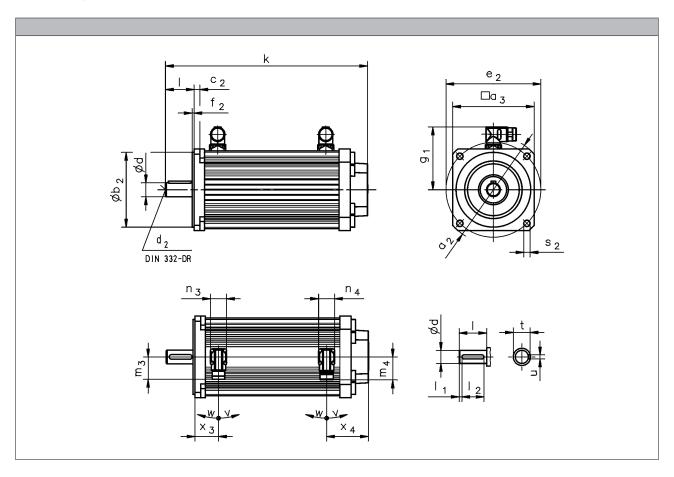
Dimensions, self-ventilated

			MCA10I40	MCA13I41	MCA14L20	MCA17N23	MCA19S23	MCA21X25
					MCA14L41	MCA17N41	MCA19S42	MCA21X42
R□0 B0	k	[mm]	292	311	352	390	461	550
	x_3	[mm]	37	45	41	43	56	62
	x_4	[mm]	61	65		73		78
R□0 P□	k	[mm]	317	346	385	425	499	592
	x_3	[mm]	59	72	68	75	91	102
	x_4	[mm]	61	65		73		78
S□□ / E□□ / T20 / B0	k	[mm]	346	365	407	444	511	599
	x_3	[mm]	37	45	41	43	56	62
	x_4	[mm]	115	119	128	127	123	127
S□□ / E□□ / T20 / P□	k	[mm]	371	400	440	479	549	641
	x_3	[mm]	59	72	68	75	91	102
	x_4	[mm]	115	119	128	127	123	127

► Speed/angle sensor: RS0 / S□□ / E□□ / T20
► Brake: B0 / P□

MCA asynchronous servo motors

Technical data

Dimensions, self-ventilated

	g_1	n_3	n_4	m_3	m_4	v	w
	[mm]	[mm]	[mm]	[mm]	[mm]	[°]	[°]
MCA10I40	90						
MCA13I41	102	28		40			
MCA14L20	109						
MCA14L41	109		28		40	195	80
MCA17N23	118						
MCA17N41	118						
MCA19S23	151						
MCA19S42	151	40		71			
MCA21X25	162						
MCA21X42	162						

	d	d_2	l	l_1	l_2	u	t
	k6						
	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]
MCA10	14	M5	30	2.5	25	5.0	16.0
MCA13	19	M6	40	2.0	36	6.0	21.5
MCA14	24	M8	50		40	8.0	27.0
MCA17	24	M8	50	5.0	40	8.0	27.0
MCA19	28	M10	60		50		31.0
MCA21	38	M12	80		70	10.0	41.0

	a_2	a_3	b_2	c_2	e_2	f_2	s_2
	[mm]	[mm]	j6	[mm]	[mm]	[mm]	[mm]
			[mm]				
MCA10	120	102	80	8	100	3.0	7
			70		85	2.5	M6
MCA13	160	130	110	9	130		9.0
							M8
MCA14	188	142	130	10	165	3.5	11.0
			110		130		M8
MCA17	200	165	130	12	165		11.0
			110		130		M8
MCA19	250	192	180		215	4.0	13.0
			110	11	130	3.5	M8
MCA21		214	180		215	4.0	13.0
	300	250	230	12	265		
	250	214	110	11	130	3.5	M8

MCA asynchronous servo motors

Technical data

Dimensions, forced ventilated
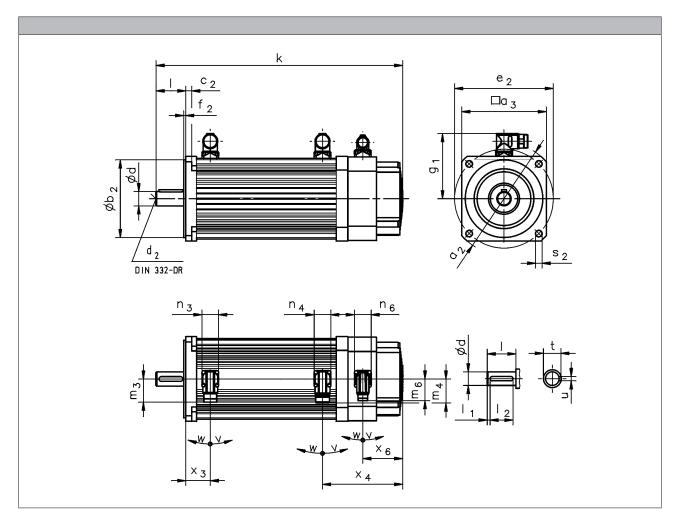
Motors MCA13 to 19/21

			MCA13I34	MCA14L16	MCA17N17	MCA19S17	MCA21X17
			MCA14L35	MCA17N35	MCA19S35	MCA21X35
R□0 B0	k	[mm]	379	414	476	558	646
	x_3	[mm]	45	41	43	56	62
	x_4	[mm]	133	135	159	170	174
R□0 P□	k	[mm]	414	447	511	596	688
	x_3	[mm]	72	68	75	91	102
	x_4	[mm]	133	135	159	170	174
S□□ / E□□ / T20 / B0	k	[mm]	433	469	530	608	695
	x_3	[mm]	45	41	43	56	62
	x_4	[mm]	187	190	213	220	223
S□□ / E□□ / T20 / P□	k	[mm]	468	502	565	646	737
	x_3	[mm]	72	68	75	91	102
	x_4	[mm]	187	190	213	220	223
	x_6	[mm]	73	67	94	103	96

► Speed/angle sensor: RS0 / S□□ / E□□ / T20
► Brake: B0 / P□

Dimensions, forced ventilated

Motors MCA13 to 19/21

	g_1	n_3	n_4	n_6	m_3	m_4	m_6	v	w
	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[°]	[°]
MCA13I34	102								
MCA14L16	109	28			40				
MCA14L35	109								
MCA17N17	118		28	28		40	37	195	80
MCA17N35	118								
MCA19S17	151				71				
MCA19S35	151	40							
MCA21X17	162								
MCA21X35	162								

	d	d_2	l	l_1	l_2	u	t
	k6						
	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]
MCA13	19	M6	40	2.0	36	6.0	21.5
MCA14	24	M8	50	5.0	40	8.0	27.0
MCA17	24	M8	50		40	8.0	27.0
MCA19	28	M10	60		50		31.0
MCA21	38	M12	80		70	10.0	41.0

	a_2	a_3	b_2	c_2	e_2	f_2	s_2
			j6				
	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]
MCA13	160	130	110	9	130	3.5	9.0
							M8
MCA14	188	142	130	10	165	3.5	11.0
			110		130		M8
MCA17	200	165	130	12	165	3.5	11.0
			110		130		M8
MCA19	250	192	180	11	215	4.0	13.0
			110		130	3.5	M8
MCA21	300	214	180	12	215	4.0	13.0
		250	230		265		
	250	214	110	11	130	3.5	M8

6.6

Dimensions, forced ventilated
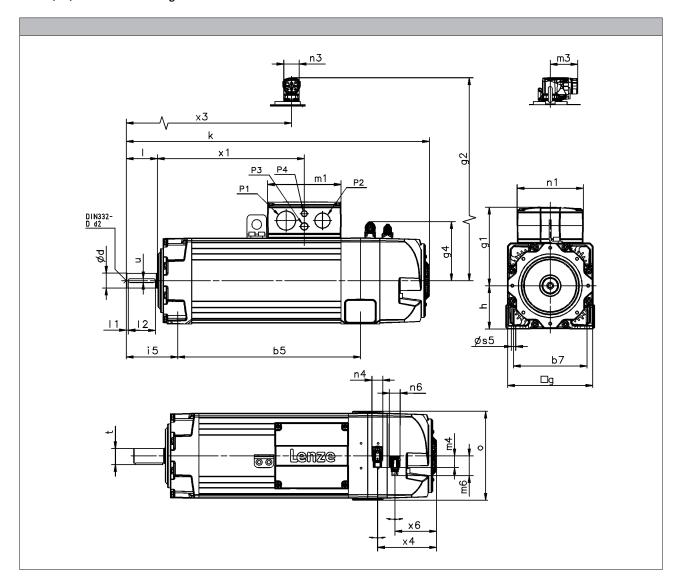
MCA20/22/26 motors in B3 design

			MCA20	MCA22	MCA26
R□0 / E□□ / T□□ / S□□ / B0...F10	k	[mm]	666	783	970
R□0 / E□□ / T□□ / S□□ / B0...F1F	k	[mm]	754	865	1022
R□0 / E□□ / T□□ / S□□ / B0	x₄	[mm]	146	153	194
	m₄	[mm]	25.0	31.0	25.0
R□0 F1...F10	k	[mm]	753	878	1125
R□0 F1...F1F	k	[mm]	842	959	1177
R□0 F1	x₄	[mm]	151	157	201
	m₄	[mm]		31.0	
E□□ / T□□ / S□□ / F1...F10	k	[mm]	797	916	1163
E□□ / T□□ / S□□ / F1...F1F	k	[mm]	885	998	1215
E□□ / T□□ / S□□ / F1	x₄	[mm]	146	162	200
	m₄	[mm]		31.0	
R□0 / E□□ / T□□ / S□□ / F2...F10	k	[mm]	822	948	1163
R□0 / E□□ / T□□ / S□□ / F2...F1F	k	[mm]	910	1030	1215
R□0 / E□□ / T□□ / S□□ / F2	x₄	[mm]	146	162	200
	m₄	[mm]		31.0	

6.6

Technical data

Dimensions, forced ventilated

MCA20/22/26 motors in B3 design

	g	g_1	g_2	g_4	m_1	m_3	m_6	n_1	n_3	n_4	n_6
	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]
MCA20	200	171	168	141	154	72		128	40		
MCA22	220	203		153	190		51	171		28	28
MCA26	260	256		173	234			212			

	o	P_1	P_2	P_3	P_4	x_1	x_3	x_6
	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]
MCA20	206	M32x1.5	M25x1.5			299	422	101
MCA22	230	M50x1.5	M40x1.5	M20x1.5	M16x1.5	380		108
MCA26	269	M63x1.5	M50x1.5			465		152

	d	d	d_2	l	l_1	l_2	u	t
	k6	m6		-0.7 … 0.3				
	[mm]	[mm]	[mm]		[mm]	[mm]	[mm]	[mm]
MCA20	38		M12	80		70	10.0	41.0
MCA22			M12	80	5.0	70	10.0	41.0
MCA26		55	M20	110		100	16.0	59.0

	h	b_5	b_7	s_5	i_5
	[mm]	[mm]	[mm]	[mm]	[mm]
MCA20	100	366	160		134
MCA22	112	472	190	11.5	133
MCA26	132	581	215	14.0	165

► Speed/angle sensor: RS0 / S□□ / E□□ / T□□
► Brake: B0 / F1 / F2
► Blower: F10 / F1F

6.6

MCA asynchronous servo motors

Technical data

- -

Dimensions, forced ventilated

MCA20/22/26 motors in B35 design

2320499-00

			MCA20	MCA22	MCA26
R□0 / E□□ / T□□ / S□□ / B0...F10	k	[mm]	666	783	970
R□0 / E□□ / T□□ / S□□ / B0...F1F	k	[mm]	754	865	1022
R□0 / E□□ / T□□ / S□□ / B0	x_4	[mm]	146	153	194
	m_4	[mm]	25.0	31.0	25.0
R□0 F1...F10	k	[mm]	753	878	1125
R□0 F1...F1F	k	[mm]	842	959	1177
R□0 F1	x_4	[mm]	151	157	201
	m_4	[mm]		31.0	
E□□ / T□□ / S□□ / F1...F10	k	[mm]	797	916	1163
E□□ / T□□ / S□□ / F1...F1F	k	[mm]	885	998	1215
E□□ / T□□ / S□□ / F1	x_4	[mm]	146	162	200
	m_4	[mm]		31.0	
R□0 / E□□ / T□□ / S□□ / F2...F10	k	[mm]	822	948	1163
R□0 / E□□ / T□□ / S□□ / F2...F1F	k	[mm]	910	1030	1215
R□0 / E□□ / T□□ / S□□ / F2	x_4	[mm]	146	162	200
	m_4	[mm]		31.0	

MCA asynchronous servo motors

Technical data

Dimensions, forced ventilated

MCA20/22/26 motors in B35 design

	g	g_1	g_2	g_4	m_1	m_3	m_6	n_1	n_3	n_4	n_6
	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]
MCA20	200	171	168	141	154	72		128	40		
MCA22	220	203		153	190		51	171		28	28
MCA26	260	256		173	234			212			

	o	P_1	P_2	P_3	P_4	x_1	x_3	x_6
	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]
MCA20	206	M32x1.5	M25x1.5			299	422	101
MCA22	230	M50x1.5	M40x1.5	M20x1.5	M16x1.5	380		108
MCA26	269	M63x1.5	M50x1.5			465		152

	d	d	d_2	l	l_1	l_2	u	t
	k6	m6		-0.7 ... 0.3				
	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]
MCA20	38		M12	80	5.0	70	10.0	41.0
MCA22			M12	80		70	10.0	41.0
MCA26		55	M20	110		100	16.0	59.0

	h	b_5	b_7	s_5	i_5
	[mm]	[mm]	[mm]	[mm]	[mm]
MCA20	100	366	160	11.5	134
MCA22	112	472	190		133
MCA26	132	581	215	14.0	165

	a_2	a_3	b_2	b_2	c_2	e_2	f_2	s_2
			j6	h6				
	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]
MCA20	250	196	180			215		
MCA22	300	240	230		15	265	4.0	14
MCA26	400	320		300		350	5.0	18

► Speed/angle sensor: RS0 / S□□ / E□□ / T□□
► Brake: B0 / F1 / F2
► Blower: F10 / F1F

MCA asynchronous servo motors

Accessories

Permanent magnet holding brake

The asynchronous servo motors MCA10 to 19 and 21 can be fitted with integral permanent magnet holding brakes.
In the case of permanent magnet brakes, the rated torque applies solely as holding torque at standstill. This is due to the nature of their design. During braking from full motor speed, e.g. in the event of emergency stops, the braking torque is significantly reduced.
As such, they may not be used as safety elements (particularly with lifting axes) without additional measures being implemented.
The brakes are activated when the supply voltage is disconnected (closed-circuit principle). When using the brakes purely as holding brakes, virtually no wear occurs on the friction surfaces.

For traversing axes, adherence to the permissible load/brake motor (J_L / J_{MB}) moment of inertia ensures that the permissible maximum switching rate of the brake will not be exceeded and at least 2,000 emergency stop functions can be performed from a speed of 3,000 rpm.
For lifting axes, the load torque resulting from the weight acts additionally. In this case the specifications for J_L / J_{MB} do not apply.

Caution:
The brakes used are not safety brakes in the sense that a reduction in torque may arise as a result of disruptive factors that cannot be influenced, e.g. oil ingress.

The ohmic voltage drop along the cable must be taken into consideration in long motor supply cables and must be compensated for by a higher voltage at the line input.

The following applies for Lenze system cables:

$$U[V] = U_B[V] + 0.08 \frac{[V]}{[A] \cdot [m]} \cdot l_{Lg}[m] \cdot l_B[A]$$

If no suitable voltage (incorrect value, incorrect polarity) is applied to the brake, the brake will be applied and can be overheated and destroyed by the motor continuing to rotate.
The shortest switching times of the brakes are achieved by DC switching of the voltage. A spark suppressor is required to suppress interference and to increase the service life of the relay contacts here.

Permanent magnet holding brake

6.6

Permanent magnet holding brake

Rated data with standard braking torque

► The figures stated apply to servo motors. They only apply to geared servo motors when the servo motor is connected via a mounting flange.

	$U_{N, DC}$ [3, 4, 7]	$U_{N, AC}$ [5, 7]	M_N	M_N	M_{av}	I_N [2]	J	t_1 [1]	t_2 [1]	Q_E [6]	m	J_{MB}	J_L/J_{MB}
			20 °C	120 °C	120 °C								
	[V]	[V]	[Nm]	[Nm]	[Nm]	[A]	[kgcm²]	[ms]	[ms]	[J]	[kg]	[kgcm²]	
MCA10	24		3.30	2.50	1.20	0.50	0.38	10.0	20.0	350	0.90	2.78	24.5
	205					0.060							
MCA13	24		12.0	11.0	5.50	0.67	1.06	20.0	29.0	400	0.80	9.36	7.70
	205					0.080							
MCA14	24		15.0	12.0	6.00	0.75	3.60	13.0	30.0	700	1.50	22.8	5.20
	205					0.090							
MCA17	24		24.0	22.0	11.0	0.75		25.0	50.0	1200		39.6	5.10
	205					0.090							
MCA19	24		46.0	40.0	18.0	1.00	9.50		73.0	1900	2.70	81.5	3.70
	205					0.12							
MCA21	24		88.0	80.0	35.0	1.46	31.8	53.0	97.0	2800	5.00	212	1.70
	205					0.18							

[1] Engagement and disengagement times are valid for rated voltage (± 0 %) and protective circuit for brakes with varistor for DC switching. The times may increase without a protective circuit.

[2] The currents are the maximum values when the brake is cold (value used for dimensioning the current supply). The values for a motor at operating temperature are considerably lower.

[3] With 24 V DC brake: smoothed DC voltage, ripple ≤ 1 %.
With 205 V DC brake: connection to 230 V AC through rectifier.

[4] UR not possible in the case of a brake with a 205 V supply voltage.

[5] UR not possible in the case of a brake with 230 V supply voltage.

[6] Maximum switching energy per emergency stop at n = 3000 r/min for at least 2000 emergency stops.

[7] Voltage tolerance: permanent magnet brakes -10% to +5% spring-applied brakes ±10%

6.6

Permanent magnet holding brake

Rated data with increased braking torque

► These ratings apply only for geared servo motors with integrated servo motor (without mounting flange).

	$U_{N, DC}$ [3, 4, 7]	M_N 20 °C	M_N 120 °C	M_{av} 120 °C	I_N [2]	J	t_1 [1]	t_2 [1]	Q_E [6]	m	J_{MB}	J_L/J_{MB}
	[V]	[Nm]	[Nm]	[Nm]	[A]	[kgcm²]	[ms]	[ms]	[J]	[kg]	[kgcm²]	
MCA10	24	6.00	5.00	2.50	0.67	1.06	20.0	29.0	400	0.80	3.46	22.4
	205				0.80							
MCA13	24	15.0	12.0	6.00	0.75	3.60	13.0	30.0	700	1.50	11.9	8.40
	205				0.090							
MCA14	24	23.0	20.0	10.0	0.92	9.50	18.0	55.0	1350	2.40	22.8	6.60
	205				0.12							
MCA17	24				0.92						45.5	5.00
	205				0.12							
MCA19	24	48.0	40.0	20.0	1.46	31.8	30.0	100	2800	4.80	104	4.50
	205				0.18							
MCA21	24	88.0	80.0	35.0	1.46		53.0	97.0		5.00	212	1.70
	205				0.18							

[1] Engagement and disengagement times are valid for rated voltage (± 0 %) and protective circuit for brakes with varistor for DC switching. The times may increase without a protective circuit.

[2] The currents are the maximum values when the brake is cold (value used for dimensioning the current supply). The values for a motor at operating temperature are considerably lower.

[3] With 24 V DC brake: smoothed DC voltage, ripple ≤ 1 %.
With 205 V DC brake: connection to 230 V AC through rectifier.

[4] UR not possible in the case of a brake with a 205 V supply voltage.

[5] UR not possible in the case of a brake with 230 V supply voltage.

[6] Maximum switching energy per emergency stop at n = 3000 r/min for at least 2000 emergency stops.

[7] Voltage tolerance: permanent magnet brakes -10% to +5%
spring-applied brakes ±10%

6.6

Spring-applied holding brake

Spring-operated holding brakes are available for the asynchronous servo motors MCA20, 22 and 26.
The brakes are activated when the supply voltage is disconnected (closed-circuit principle). When using the brakes purely as holding brakes, virtually no wear occurs on the friction surfaces.

Caution:
The brakes used are not safety brakes in the sense that a reduction in torque may arise as a result of disruptive factors that cannot be influenced, e.g. oil ingress.

The ohmic voltage drop along the cable must be taken into consideration in long motor supply cables and must be compensated for by a higher voltage at the line input.

The following applies for Lenze system cables:

$$U[V] = U_B[V] + 0.08 \frac{[V]}{[A] \cdot [m]} \cdot l_{Lg}[m] \cdot l_B[A]$$

If no suitable voltage (incorrect value, incorrect polarity) is applied to the brake, the brake will be applied and can be overheated and destroyed by the motor continuing to rotate.
The shortest switching times of the brakes are achieved by DC switching of the voltage. A spark suppressor is required to suppress interference and to increase the service life of the relay contacts here.

Spring-applied holding brake

- -

Spring-applied holding brake

Rated data with standard braking torque

► The figures stated apply to servo motors. They only apply to geared servo motors when the servo motor is connected via a mounting flange.

	$U_{N, DC}$ [3, 4, 7)	$U_{N, AC}$ [5, 7)	M_N 20 °C	M_N 120 °C	M_{av} 120 °C	I_N [2)	J	t_1 [1)	t_2 [1)	Q_E [6)	m	J_{MB}	J_L/J_{MB}
	[V]	[V]	[Nm]	[Nm]	[Nm]	[A]	[kgcm²]	[ms]	[ms]	[J]	[kg]	[kgcm²]	
MCA20	24		90.0	80.0	50.0	3.13	6.88	70.0	220	18000	13.0	177	19.6
		230				0.37							
MCA22	24		150	130	80.0	3.75	18.1	50.0	260	23000	20.5	505	8.20
		230				0.44		130					
MCA26	24		300	260	160	3.75	36.3	175	320	39000	26.0	1405	12.7
		230			200	0.37	70.4		360	51000	30.7		

Rated data with increased braking torque

► The figures stated apply to servo motors. They only apply to geared servo motors when the servo motor is connected via a mounting flange.

	$U_{N, DC}$ [3, 4, 7)	$U_{N, AC}$ [5, 7)	M_N 20 °C	M_N 120 °C	M_{av} 120 °C	I_N [2)	J	t_1 [1)	t_2 [1)	Q_E [6)	m	J_{MB}	J_L/J_{MB}
	[V]	[V]	[Nm]	[Nm]	[Nm]	[A]	[kgcm²]	[ms]	[ms]	[J]	[kg]	[kgcm²]	
MCA20	24		150	130	100	2.58	14.1	70.0	240	31000	15.4	189	33.0
		230				0.30							
MCA22	24		300	260	160	3.75	36.3	175	320	39000	26.0	523	14.1
		230				0.44		130	310				
MCA26	24		500	430	260	3.75	70.4	175	390	51000	30.8	1405	12.7
		230				0.44							

[1) Engagement and disengagement times are valid for rated voltage (± 0 %) and protective circuit for brakes with varistor for DC switching. The times may increase without a protective circuit.

[2) The currents are the maximum values when the brake is cold (value used for dimensioning the current supply). The values for a motor at operating temperature are considerably lower.

[3) With 24 V DC brake: smoothed DC voltage, ripple ≤ 1 %. With 205 V DC brake: connection to 230 V AC through rectifier.

[4) UR not possible in the case of a brake with a 205 V supply voltage.

[5) UR not possible in the case of a brake with 230 V supply voltage.

[6) Maximum switching energy per emergency stop at n = 3000 rpm for at least 300 emergency stops, maximally 4 emergency stops per hour.

[7) Voltage tolerance: permanent magnet brakes -10% to +5% spring-applied brakes ±10%

6.6

MCA asynchronous servo motors

Accessories

_____

Resolver

Stator-fed resolver with two stator windings offset by 90° and one rotor winding with transformer winding.

Speed/angle sensor					
	1)			RS0	RV0
Product key					
				RS0	RV03
Resolution					
Angle		[']		0.80	
Accuracy					
		[']		-10 … 10	
Absolute positioning					
				1 revolution	
Max. speed					
	n_{max}	[r/min]		8000	
Max. input voltage					
DC	$U_{in,max}$	[V]		10.0	
Max. input frequency					
	$f_{in,max}$	[kHz]		4.00	
Ratio					
Stator / rotor		± 5 %		0.30	
Rotor impedance					
	Z_{ro}	[Ω]		51 + j90	
Stator impedance					
	Z_{so}	[Ω]		102 + j150	
Impedance					
	Z_{rs}	[Ω]		44 + j76	
Min. insulation resistance					
At DC 500 V	R	[MΩ]		10.0	
Number of pole pairs					
				1	
Max. angle error					
		[']		-10 … 10	
Inverter assignment					
				i700 E84AVTC E94A ECS EVS93	E84AVTC E94A ECS EVS93

1) ▶ 🗐   6 - Product key > speed/angle sensor

Speed-dependent safety functions

Suitable for safety function					
				No	Yes
Max. permissible angular acceleration					
MCA10 … MCA19 2)	α	[rad/s²]			22 000
MCA20 … MCA26 2)	α	[rad/s²]			22 000
Functional safety					
IEC 61508					SIL3
EN 13849-1					Up to Performance Level e

2) ▶ 🗐   1 - Single encoder concepts with resolvers

MCA asynchronous servo motors

Accessories

Incremental encoder and SinCos absolute value encoder

Encoder type			TTL incremental		SinCos incremental	
Speed/angle sensor						
	[1]		T20	T40	S20	S1S
Product key						
			IG2048-5V-T	IG4096-5V-T	IG2048-5V-S	IG1024-5V-V3
Encoder type						
					Single-turn	
Pulses						
			2048	4096	2048	1024
Output signals						
			TTL		1 Vss	
Interfaces						
			A, B, N track and inverted			
Absolute revolutions						
			0			
Resolution						
Angle [2]		[']	2.60	1.30	0.40	
Accuracy						
		[']	-2 ... 2		-0.8 ... 0.8	
Min. input voltage						
DC	$U_{in,min}$	[V]	4.75		4.50	4.75
Max. input voltage						
DC	$U_{in,max}$	[V]	5.25		5.50	5.25
Max. speed						
	n_{max}	[r/min]	8789		5273	8000
Max. current consumption						
	I_{max}	[A]	0.15		0.10	0.070
Limit frequency						
	f_{max}	[kHz]	300		180	200
Inverter assignment						
			E84AVTC E94A ECS EVS93			E94A

[1] ▶ 📄 6 - Product key > speed/angle sensor

[2] Inverter-dependent.

Speed-dependent safety functions

Suitable for safety function						
			No	No	No	Yes
Max. permissible angular acceleration						
MQA20 ... MQA26	α	[rad/s²]				73000
Functional safety						
IEC 61508						SIL3
EN 13849-1						Up to Performance Level e

6.6

Incremental encoder and SinCos absolute value encoder

Encoder type							
Speed/angle sensor			SinCos absolute value				
	1)		EQI	SRS	SRM	ECN	EQN
Product key							
			AM32-5V-E	AS1024-8V-H	AM1024-8V-H	AS2048-5V-E	AM2048-5V-E
Encoder type							
			Multi-turn	Single-turn	Multi-turn	Single-turn	Multi-turn
Pulses							
			32	1024		2048	
Output signals							
			1 Vss				
Interfaces							
			EnDat	Hiperface		EnDat	
Absolute revolutions							
			4096	1	4096	1	4096
Resolution							
Angle		[']	0.40				
Accuracy							
		[']	-5 … 5	-0.8 … 0.8		-0.6 … 0.6	
Min. input voltage							
DC	$U_{in,min}$	[V]	4.75	7.00		4.75	
Max. input voltage							
DC	$U_{in,max}$	[V]	5.25	12.0		5.25	
Max. speed							
	n_{max}	[r/min]	12000	6000		12000	
Max. current consumption							
	I_{max}	[A]	0.17	0.080		0.15	0.25
Limit frequency							
	f_{max}	[kHz]	6.00	200			
Inverter assignment							
			E94A	E84AVTC E94A ECS EVS93		E94A	

1) ▶ ▤   6 - Product key > speed/angle sensor

Blower

Rated data for 50 Hz

		Enclosure	Number of phases	U_{min}	U_{max}	$U_{N, AC}$	P_N	I_N
				[V]	[V]	[V]	[kW]	[A]
MCA13	F10	IP54	1	210	240	230	0.019	0.12
MCA14								
MCA17							0.040	0.25
MCA19								
MCA20	F10 F1F	IP23s			250		0.17	0.73
MCA21	F10	IP54			240		0.060	0.26
MCA22	F10 F1F	IP23s IP54			250		0.24	1.05
MCA26							0.40	1.75

Rated data for 60 Hz

		Enclosure	Number of phases	U_{min}	U_{max}	$U_{N, AC}$	P_N	I_N
				[V]	[V]	[V]	[kW]	[A]
MCA13	F10	IP54	1	210	240	230	0.019	0.12
MCA14								
MCA17							0.040	0.25
MCA19								
MCA20	F10 F1F	IP23s			250		0.20	0.90
MCA21	F10	IP54			240		0.060	0.26
MCA22	F10 F1F	IP23s IP54			250		0.28	1.23
MCA26							0.41	1.82
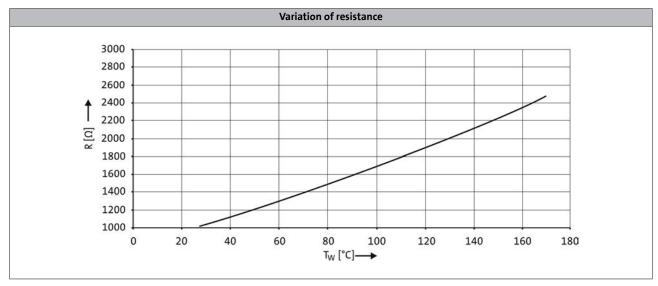
6.6

MCA asynchronous servo motors

Accessories

Temperature monitoring

The thermal sensors (1x KTY 83-110) used continuously monitor the
motor temperature. The temperature signal is transmitted over the
system cable of the feedback system to the servo controller.
This means that the temperature of the motor is determined with
great accuracy in the permitted operating range and at the same time
the overtemperature response configured in the controller is executed
in the event of overtemperature in one of the winding phases.

Variation of resistance

► If the thermal sensor is supplied with a measurement current of
  1 mA, the above relationship between the temperature and the
  resistance applies.

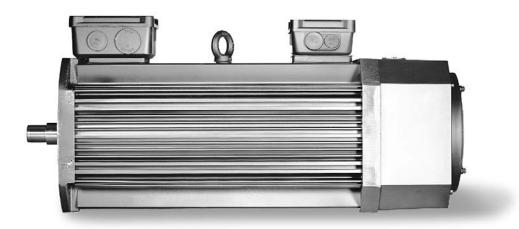--

Terminal box
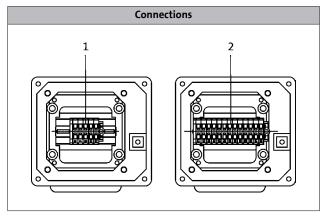
Motors MCA10 to 19/21

If a servo motor is to be connected to an existing cable or plug connectors are not to be used for other reasons, the connection can also be made via a terminal box.

The motor can either be fitted with a terminal box for the power connection and motor holding brake or a second terminal box provided to connect the motor feedback and blower (if applicable).

Connections

1: Power connection + brake connection + PE connection.

2: Angle/speed sensor connection + thermal sensor connection

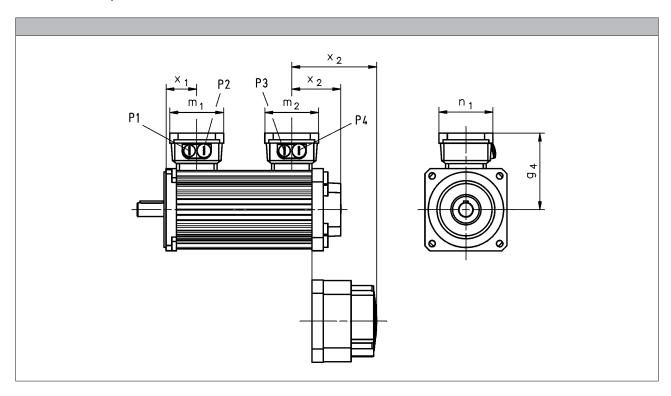**MCA asynchronous servo motors with blower and terminal box**

Terminal box

Motors MCA10 to 19/21

			MCA10I40	MCA13I41	MCA14L20	MCA17N23	MCA19S23	MCA21X25
					MCA14L41	MCA17N41	MCA19S42	MCA21X42
R□0 B0	x_2	[mm]	78	77	85		93	97
R□0 P□	x_2	[mm]	78	77	85		93	97
S□□ / E□□ / T20 / B0	x_2	[mm]	132	131	140	139	143	147
S□□ / E□□ / T20 / P□	x_2	[mm]	132	131	140	139	143	147

			MCA13I34	MCA14L16	MCA17N17	MCA19S17	MCA21X17
				MCA14L35	MCA17N35	MCA19S35	MCA21X35
R□0 B0	x_2	[mm]	145	147	171	190	193
R□0 P□	x_2	[mm]	145	147	171	190	193
S□□ / E□□ / T20 / B0	x_2	[mm]	199	202	225	240	243
S□□ / E□□ / T20 / P□	x_2	[mm]	199	202	225	240	243

► Speed/angle sensor: RS0 / S□□ / E□□ / T20
► Brake: B0 / P□

	g_4	m_1	m_2	n_1	x_1	P_1	P_2	P_3	P_4
	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]
MCA10	113				54				
MCA13	125				57				
MCA14	133	93	93	93	53	M20x1.5	M20x1.5	M20x1.5	M20x1.5
MCA17	141				55				
MCA19	158	115	115	115	64	M25x1.5	M32x1.5		
MCA21	169				70				

ICN connector

Servo motors MCA10 to 21 provide ICN connectors as standard for electrical connection. Servo motors MCA22 and MCA26 provide a terminal box for electrical connection.

A connector is used for the connection of motor and brake. The connections to the feedback system/temperature monitoring and the blower each employ a separate connector.

The connectors can be rotated through 270° and are fitted with a bayonet catch for SpeedTec connectors. As the connector fixing is also compatible with conventional union nuts. Existing mating connectors can therefore still be used without difficulty.

Connection for power and brake

► MCA10 to 17

Pin assignment			
Contact	Designation	Meaning	
1	BD1	Holding brake +	
2	BD2	Holding brake -	
PE	PE	PE conductor	
4	U	Phase U power	
5	V	Phase V power	
6	W	Phase W power	

► MCA19 to 21

Pin assignment			
Contact	Designation	Meaning	
1		Not assigned	
2			
+	BD1	Holding brake +	
-	BD2	Holding brake -	
PE	PE	PE conductor	
U	U	Phase U power	
V	V	Phase V power	
W	W	Phase W power	

- -

ICN connector

Feedback connection

► Resolver

Pin assignment			
Contact	Designation	Meaning	
1	+Ref	Transformer windings	
2	-Ref		
3	+VCC ETS	Supply: Electronic nameplate	
4	+COS	Cosine stator windings	
5	-COS		
6	+SIN	Sine stator windings	
7	-SIN		
8		Not assigned	
9			
10			
11	+KTY	KTY temperature sensor	
12	-KTY		

► Hiperface incremental encoder and SinCos absolute value encoder

Pin assignment			
Contact	Designation	Meaning	
1	B	Track B/+SIN	
2	A$^-$	Track A inverse/-COS	
3	A	Track A/+COS	
4	+U$_B$	Supply +	
5	GND	Mass	
6	Z$^-$	Zero track inverse/-RS485	
7	Z	Zero track/+RS485	
8		Not assigned	
9	B$^-$	Track B inverse/-SIN	
10		Not assigned	
11	+KTY	KTY temperature sensor	
12	-KTY		

MCA asynchronous servo motors

Accessories

ICN connector

Feedback connection

► SinCos absolute value encoder with EnDat interface

Pin assignment			
Contact	Designation	Meaning	
1	U$_P$ sensor	Supply: UP sensor	
2		Not assigned	
3			
4	0 V sensor	Supply: 0 V sensor	
5	+KTY	KTY temperature sensor	
6	-KTY		
7	+U$_B$	Supply +	
8	Cycle	EnDat interface cycle	
9	Cycle$^-$	EnDat interface inverse cycle	
10	GND	Mass	
11	Shield	Encoder housing screen	
12	B	Track B	
13	B$^-$	Track B inverse/-SIN	
14	Data	EnDat interface data	
15	A	Track A	
16	A$^-$	Track A inverse	
17	Data$^-$	EnDat interface inverse data	

Blower connection

Pin assignment			
Contact	Designation	Meaning	
PE	PE	PE conductor	
1	U1	Fan	
2	U2		
3		Not assigned	
4			
5			
6			

6.6

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